

# Exponential decay of reconstruction error from binary measurements of sparse signals

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Deanna Needell



Joint work with R. Baraniuk, S. Foucart, Y. Plan, and M. Wootters

# Outline

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- ✧ Introduction
  - ✧ Mathematical Formulation & Methods
- ✧ Practical CS
  - ✧ Other notions of sparsity
  - ✧ Heavy quantization
  - ✧ Adaptive sampling

# The mathematical problem

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1. Signal of interest  $f \in \mathbb{C}^d (= \mathbb{C}^{N \times N})$
2. Measurement operator  $\mathcal{A} : \mathbb{C}^d \rightarrow \mathbb{C}^m$  ( $m \ll d$ )
3. Measurements  $y = \mathcal{A} f + \xi$

$$\begin{bmatrix} y \end{bmatrix} = \begin{bmatrix} \mathcal{A} \end{bmatrix} \begin{bmatrix} f \end{bmatrix} + \begin{bmatrix} \xi \end{bmatrix}$$

4. **Problem:** Reconstruct signal  $f$  from measurements  $y$

# Sparsity

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Assume  $f$  is *sparse*:

✧ In the coordinate basis:  $\|f\|_0 \stackrel{\text{def}}{=} |\text{supp}(f)| \leq s \ll d$

✧ In orthonormal basis:  $f = Bx$  where  $\|x\|_0 \leq s \ll d$

In practice, we encounter *compressible* signals.

◆  $f_s$  is the best  $s$ -sparse approximation to  $f$

# Many applications...

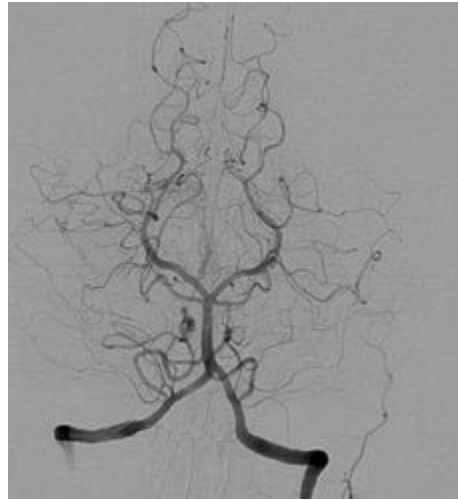
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- ✧ Radar, Error Correction
- ✧ Computational Biology, Geophysical Data Analysis
- ✧ Data Mining, classification
- ✧ Neuroscience
- ✧ Imaging
- ✧ Sparse channel estimation, sparse initial state estimation
- ✧ Topology identification of interconnected systems
- ✧ ...

# Sparsity...

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Sparsity in coordinate basis:  $f=x$



# Reconstructing the signal $f$ from measurements $y$

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◆  $\ell_1$ -minimization [Candès-Romberg-Tao]

Let  $A$  satisfy the *Restricted Isometry Property* and set:

$$\hat{f} = \underset{g}{\operatorname{argmin}} \|g\|_1 \quad \text{such that} \quad \|Af - y\|_2 \leq \varepsilon,$$

where  $\|\xi\|_2 \leq \varepsilon$ . Then we can stably recover the signal  $f$ :

$$\|f - \hat{f}\|_2 \lesssim \varepsilon + \frac{\|x - x_s\|_1}{\sqrt{s}}.$$

This error bound is optimal.

# Restricted Isometry Property

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- ✧  $\mathcal{A}$  satisfies the Restricted Isometry Property (RIP) when there is  $\delta < c$  such that

$$(1 - \delta)\|f\|_2 \leq \|\mathcal{A}f\|_2 \leq (1 + \delta)\|f\|_2 \quad \text{whenever } \|f\|_0 \leq s.$$

- ✧  $m \times d$  Gaussian or Bernoulli measurement matrices satisfy the RIP with high probability when

$$m \gtrsim s \log d.$$

- ✧ Random Fourier and others with fast multiply have similar property:  
 $m \gtrsim s \log^4 d.$



# Other recovery methods

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## Greedy Algorithms

- ✧ If  $A$  satisfies the RIP, then  $A^* A$  is “close” to the identity on sparse vectors
- ✧ Use proxy  $p = A^* y = A^* Ax \approx x$
- ✧ Threshold to maintain sparsity:  $\hat{x} = H_s(p)$
- ✧ Repeat
- ✧ (Iterative Hard Thresholding)

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$$\|\mathbf{x} - \Delta(\mathbf{y})\| \leq \gamma$$

provided the oversampling factor satisfies

$$\lambda := \frac{m}{s \ln(n/s)} \geq f(\gamma)$$

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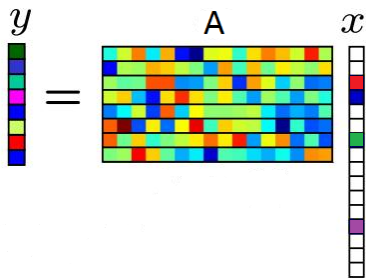
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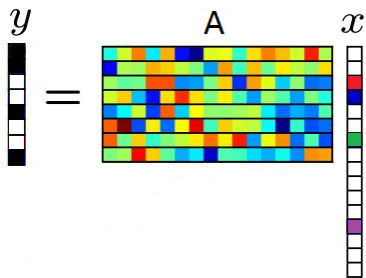
$$\|\mathbf{x} - \Delta(\mathbf{y})\| \leq g(\lambda)$$

for  $g$  rapidly decreasing to zero when  $\lambda$  increases.

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$$\left\| \mathbf{x} - \frac{\Delta_{\text{LP}}(\mathbf{y})}{\|\Delta_{\text{LP}}(\mathbf{y})\|_2} \right\|_2 \lesssim \lambda^{-1/5} \quad \text{whenever } \|\mathbf{x}\|_0 \leq s, \|\mathbf{x}\|_2 = 1.$$

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If  $\mathbf{A} \in \mathbb{R}^{m \times n}$  is a Gaussian matrix, then w/hp

$$\|\mathbf{x} - \Delta_{\text{SOCP}}(\mathbf{y})\|_2 \lesssim \lambda^{-1/12} \quad \text{whenever } \|\mathbf{x}\|_0 \leq s, \|\mathbf{x}\|_2 = 1.$$



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- ▶ Power decay is optimal since

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even if  $\text{supp}(\mathbf{x})$  known in advance [Goyal–Vetterli–Thao 98].

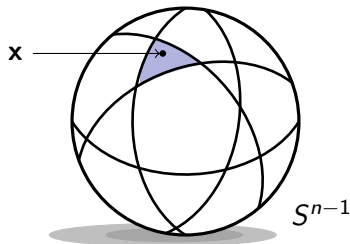
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<http://dsp.rice.edu/1bitCS/choppyanimated.gif>

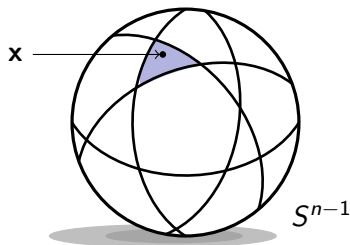
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- ▶ Remedy: adaptive choice of dithers  $\tau_1, \dots, \tau_m$  in

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one-bit measurements and estimate both the direction and the  
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- ▶ Software step needed to compute the thresholds  $\tau_i = \langle \mathbf{a}_i, \mathbf{x}^t \rangle$ .

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- ▶ Pros: dithers are nonadaptive.
- ▶ Cons: slow, post-quantization error not handled.

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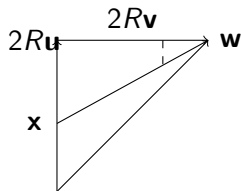
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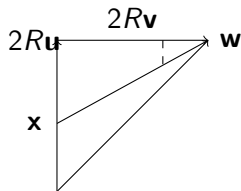


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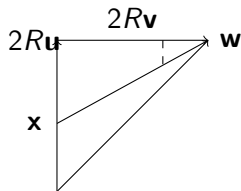
- ▶ Use other half to estimate the direction of  $\mathbf{x} - \mathbf{w}$  applying hard thresholding again.

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- ▶ Measurement vectors  $\mathbf{a}_1, \dots, \mathbf{a}_q$ : independent  $\mathcal{N}(0, \mathbf{I}_q)$ .
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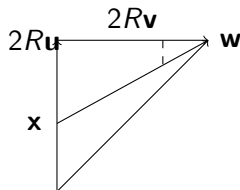


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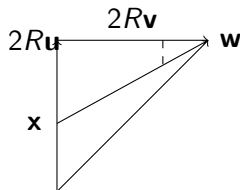
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- ▶ Pros: deterministic, fast, handles pre/post-quantization errors.

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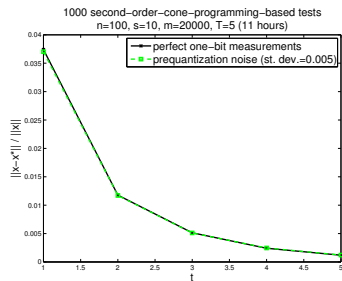
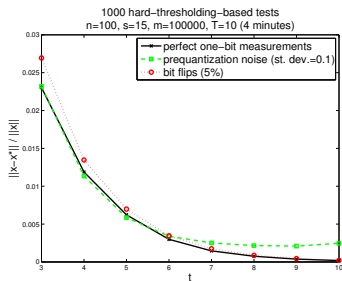
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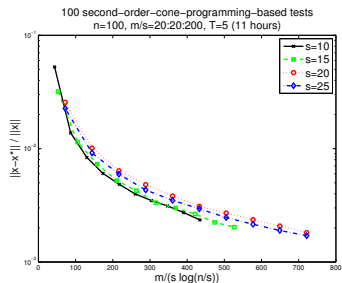
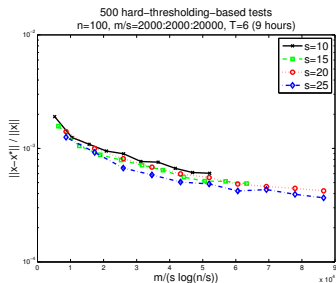
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# Numerical Illustration





# Numerical Illustration, ctd



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# Thank you!

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