What is an algorithm?

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Some publications, all posted in www.math.ucla.edu/ \sim ynm

On the general theory

- The formal language of recursion (1989)
- A mathematical modeling of pure, recursive algorithms (1989)
- On founding the theory of algorithms (1998)
- What is an algorithm? (2001)
- Elementary algorithms and their implementations, with Vasilis Paschalis (2008)

Applications

- Is the Euclidean algorithm optimal among its peers?, with Lou van den Dries (2004)
- Arithmetic complexity with Lou van den Dries (2009)
- A logical calculus of meaning and synonymy (2006)

Outline

- (1) Computation models; the (almost) standard view
- (2) Three classical algorithms
- (3) Least fixed point recursion
- (4) Monotone recursors: the set-theoretic objects which model deterministic algorithms
- (5) Operations on recursors
- (6) Implementations
- (7) Algorithms are recursors from given primitives
- (8) Recursive programs
- (9) Elementary algorithms
- (10) Some applications
- (11) Computation models vs. recursive algorithms

36,500,000 Google hits and no formal definition

- Wikipedia: An algorithm is a step-by-step procedure for calculations
- Common: Algorithms are Turing machines or processes which can be simulated by Turing machines

Turing machines do not express faithfully low complexity algorithms van Emde Boas: simulation ... is very hard to define as a mathematical object

- Knuth: A computational method [computation model] is ... An algorithm is a computational method which terminates in finitely many steps for all [inputs]
- Girard (and others): An algorithm is expressed by a constructive proof of a statement of the form (∀x ∈ A)(∃y ∈ B)P(x, y)

We need to make precise

- The mathematical structure of algorithms
- The way in which algorithms are effective (constructive, definable)

These two aspects of algorithms are related but separate

Structure: computation models (machines, while programs)



A computation model $\mathfrak{m} : X \rightsquigarrow W$ is a tuple (S, in, σ, T, out) such that

- (1) S is a non-empty set (of states)
- (2) X is a set and in : $X \to S$ is the input function
- (3) $\sigma: S \to S$ is the transition function
- (4) T is the set of terminal states, $T \subseteq S$
- (5) W is a set and out : $T \rightarrow W$ is the output function
 - $\overline{\mathfrak{m}}(x) = \operatorname{out}(\sigma^n(\operatorname{in}(x)))$ where $n = \text{least such that } \sigma^n(\operatorname{in}(x)) \in T$

•
$$s := in(x)$$
; while $(s \notin T) \{ s := \sigma(s) \}$; return out (s)

• \mathfrak{m} computes the partial function $\overline{\mathfrak{m}}: X \rightarrow W$

Definability in M = ({ M_i }_{*i* \in *I*}, { $\varphi^{M} \mid \varphi \in \Phi$ })

• Each M_i is a set of sort *i* including $M_{boole} = \{t, ff\}$

Each φ ∈ Φ has a type (((i₁,..., i_{n-1}), j) (with i_k ≠ boole) and φ^M : M_{i1} × ··· × M_{in-1} → M_j is a strict partial function
 M is total if every φ^M is total

• A (usual) first-order structure $\mathbf{M} = (M, f_1, \dots, f_{k-1}, R_1, \dots, R_{l-1})$, with M and $\{\mathfrak{t}, \mathrm{ff}\}$ as the basic universes and the relations represented by their characteristic functions

• Unary arithmetic, $\mathbf{N}_1 = (\mathbb{N}, 0, S, \mathsf{Pd}, =_0)$

• Binary arithmetic, $\mathbf{N}_2 = (\mathbb{N}, 0, 1, iq_2, rem_2, em_2, om_2, =_0)$, with $iq_2(x) = iq(x, 2), rem_2(x) = rem(x, 2), em_2(x) = 2x, om_2(x) = 2x + 1$

• An **M**-machine for a first-order $\mathbf{M} = (M, \{\varphi^{\mathbf{M}} \mid \varphi \in \Phi\})$ is a computation model $(S, in, \sigma, T, out) : M^n \rightsquigarrow M_j$ in which $S = M^k$ for some k and in, σ, T , out are definable by explicit Φ -terms with branching, if A then B else C

Turing machines on k symbols are N_k-machines (k-ary arithmetic)

The (almost) standard view

 \star Algorithms are computation models

* Algorithms from given functions and relations are M-machines, where the primitives of M include the given functions and relations and some additional absolutely computable operations

E.g., a Turing machine from $R \subset \mathbb{N}^2$ has an oracle for R but operates on the set of strings Σ^* from some alphabet, uses the basic operations on them and assumes a specific representation of numbers by strings (typically unary or binary)

• These principles are implicitly assumed in much of complexity theory and defended (with specific extra operations) by Gurevich and others

• There is no general agreement on which primitives of computation are absolute—one of the problems with this view

• I will discuss a broader view, by which algorithms are specified by systems of recursive equations and computation models are implementations of elementary algorithms

The Euclidean algorithm

For $x, y \in \mathbb{N}^+ = \{n \in \mathbb{N} \mid n > 0\}$, with set of states $S = \mathbb{N}^2$

(*)
$$| s := x$$
; $t := y$; while(rem $(s, t) \neq 0$)[$(s, t) := (t, rem(s, t))$]; return t

where rem(s, t) is the remainder of the division of s by t,

• (*) defines an $(\mathbb{N}, \operatorname{rem}, =_0)$ -machine ε which computes $\operatorname{gcd}(x, y)$

 $\begin{aligned} \mathsf{calls}^{\mathsf{rem}}_{\varepsilon}(x,y) &= \mathsf{the number of calls to rem} \\ & \mathsf{required to compute } \gcd(x,y) \mathsf{ by } \varepsilon \\ &\leq 2\log(y) \qquad (x \geq y \geq 2) \end{aligned}$

Conjecture (open): For every algorithm α which computes the gcd function from rem and $=_0$:

for x, y with arbitrarily large min(x, y),

 $\mathsf{calls}^{\mathsf{rem}}_\varepsilon(x,y) \le \mathsf{calls}^{\mathsf{rem}}_\alpha(x,y)$

• It assumes that "algorithm from rem, $=_0$ " and calls^{rem} are defined and is trivial for computation models with more primitives (e.g., TMs)

The extended Euclidean (as a recursive algorithm)

Bezout's Lemma. There are functions $\alpha, \beta : \mathbb{N}^+ \times \mathbb{N}^+ \to \mathbb{Z}$ such that (*) if $x, y \in \mathbb{N}^+$, then $gcd(x, y) = \alpha(x, y)x + \beta(x, y)y$

It is easy to check that (*) holds if $\alpha(x,y), \beta(x,y)$ satisfy the system

$$\begin{aligned} \alpha(x,y) &= \text{ if } (\text{rem}(x,y) = 0) \text{ then } 0 \text{ else } \beta(y,\text{rem}(x,y)), \\ \beta(x,y) &= \text{ if } (\text{rem}(x,y) = 0) \text{ then } 1 \\ &\quad \text{ else } \alpha(y,\text{rem}(x,y)) - \text{iq}(x,y)\beta(y,\text{rem}(x,y)) \end{aligned}$$

where iq(x, y) is the integer quotient of x by y;

and this expresses a recursive algorithm which computes suitable functions $\alpha, \beta : \mathbb{N}^+ \times \mathbb{N}^+ \to \mathbb{Z}$ from the primitives 0, 1, rem, iq, -, =₀

• The corresponding recursive equation expressing the Euclidean is

$$gcd(x, y) = if (rem(x, y) = 0)$$
 then y else $gcd(y, rem(x, y))$

The color of leaves

A (binary, colored) forest is a structure

 $\mathbf{F} = (F, s, d, \text{Leaf}, \text{Red}, =)$ where Leaf, $\text{Red} \subseteq F$ and $s, d : F \to F$

A path from x_0 is any sequence $p = (x_0, \ldots)$ of length $|p| \le \infty$ s.t.

$$i+1 < |p| \implies [\neg \mathsf{Leaf}(x_i) \& x_{i+1} \in \{s(x_i), d(x_i)\}]$$

F is grounded if it has no infinite paths, and on such F we set
 R(x) ⇐⇒ every maximal path from x ends in a red leaf

(*)
$$|R(x) \iff \text{if Leaf}(x) \text{ then } \text{Red}(x) \text{ else } [R(s(x)) \& R(d(x))]|$$

• (*) expresses a recursive algorithm ρ which decides R(x) on **F** and there are many such divide-and-conquer algorithms (e.g., the mergesort)

• (Tiuryn 1989) On some grounded forest, no algorithm expressed by an **F**-machine decides R(x)

★ ρ can be implemented by many machines on $F' \supset F$ with more primitives

The sieve of Eratosthenes

$$\begin{aligned} \mathsf{Primes} &= p(u_0) \text{ where} \\ & \left\{ u_0 = (2, 3, 4, 5, \ldots), \\ p(u) &= \mathsf{Print}(\mathsf{head}(u))^{\widehat{}} p(\mathit{sieve}(\mathsf{head}(u), \mathsf{tail}(u))), \\ & \mathit{sieve}(x, v) &= \mathsf{if} \ (x \mid \mathsf{head}(v)) \text{ then } \mathit{sieve}(x, \mathsf{tail}(v)) \\ & \quad \mathsf{else} \ \mathsf{head}(v)^{\widehat{}} \mathit{sieve}(x, \mathsf{tail}(v)) \right\} \end{aligned}$$

$$(S = (\mathbb{N} \rightarrow \mathbb{N}), u_0, u, v \in S, p : S \rightarrow S, x \in \mathbb{N}, \textit{sieve} : \mathbb{N} \times S \rightarrow S)$$

- A system of recursive equations which expresses an algorithm σ on S from head, tail, $|, \hat{}$ and (the act) Print
- sieve(x, v) removes from v all numbers divisible by x
- p(u) prints head(u) and then calls itself on sieve(head(u), tail(u))
- σ computes successively $u_0 = (2, 3, 4, \ldots), u_1 = (3, 5, 7, \ldots), u_2 = (5, 7, 11, \ldots), \ldots$ and (as a side effect) "prints" the heads of these sequences

• σ operates on completed infinite objects and never terminates

• The basic notion is that of algorithm from primitives with a very broad understanding of "primitives"

• Problem: too many notions are associated with an algorithm: calls to the primitives, recursive definitions, complexity functions, termination, side effects (and interaction, which is more complex), simulation, implementability, ...

For specific algorithms many of these are simple and naturally defined, but a general theory might be excessively complex

• The lesson from probability theory: it is even more complex, but there is a useful and fairly simple basic notion:

A random variable is a measurable function $X : M \to \mathbb{R}$ on a sample space (a measure space of total measure 1)

• We look for a similar solution, which takes the basic notions of the theory of algorithms from an existing mathematical theory

• Claim: For deterministic algorithms, the background theory is least fixed point recursion on complete posets

Yiannis N. Moschovakis: What is an algorithm?

Basic poset theory, I

• A poset is a pair (X, \leq_X) where \leq_X is a partial ordering of X

• A poset *D* is (directed- or chain-) complete if every linearly ordered subset (chain) $C \subseteq D$ has a least upper bound sup(*C*).

Every complete poset has a least element, $\sup(\emptyset) = \bot$

- A poset D is complete if and only if every directed subset $C \subseteq D$ has a least upper bound. (The proof requires the Axiom of Choice)
- A set X can be viewed as a discrete poset or represented by the complete flat poset $X_{\perp} = X \cup \{\perp\}$, where

 $s \leq_{X_{\perp}} t \iff s = \perp \lor s = t$

• The (naturally defined, cartesian) product $D_1 \times \cdots \times D_n$ of complete posets is complete

Basic poset theory, II

• A function $f: X \to W$ is monotone if

$$x \leq_X y \implies f(x) \leq_W f(y),$$

and strict if $f(x) \neq \bot \implies x$ is total (maximal) in X

• A function $f: X \to W$ is (Scott) continuous if

$$\sup_X(C) = \overline{x} \implies \sup_W \{f(x) \mid x \in C\} = f(\overline{x})$$

for every chain $C \subseteq X$ or (equivalently) for every directed subset $C \subseteq X$ • Strict(X, W), Cont(X, W) and Mon(X, W) are complete if W is

complete, and

$$\mathsf{Strict}(X,W)\subseteq\mathsf{Cont}(X,W)\subseteq\mathsf{Mon}(X,W)$$

For sets X, Y, Strict(X_⊥, Y_⊥) ≅ (X → Y)
 = the poset of all partial functions on X to Y ordered under inclusion

Least fixed point recursion

Theorem (Least Fixed Point Theorem, LFP, classical) Every monotone function $f : D \rightarrow D$ on a complete poset has a least fixed point $\overline{d} = \min(d \in D)[f(d) = d]$, characterized by

$$f(\overline{d}) = \overline{d}, \quad (\forall d)[f(d) \le d \implies \overline{d} \le d]$$

Moreover: if $f : X \times D \rightarrow D$ is monotone, then the function

$$g(x) = \min(d \in D)[f(x, d) = d] \quad (x \in X)$$

is also monotone, and if f is continuous, then so is g

• The proof is "constructive", i.e., \overline{d} is built up by iterating f,

$$\overline{d}^0 = f(\perp), \overline{d}^1 = f(\overline{d}^0), \dots, \overline{d} = \sup_{\xi \in \mathsf{Ords}} \overline{d}_{\xi}$$

• In many applications, $D = D_1 \times \cdots \times D_k$ is a product poset

Definition by mutual recursion

The examples we gave were all definitions of the form

(*)
$$f(x) = f_0(x, p)$$
 where
 $\left\{ p_1(u_1) = f_1(u_1, x, p), \dots, p_k(u_k) = f_k(u_k, x, p) \right\}$
 $= f_0(x, p)$ where $\left\{ p_1 = \lambda(u_1)f_1(u_1, x, p), \dots, p_k = \lambda(u_k)f_k(u_k, x, p) \right\}$
with $p = (p_1, \dots, p_k)$;

the value f(x) is determined by computing the least solution tuple $\overline{p}_x = (\overline{p}_{1,x}, \dots, \overline{p}_{k,x})$ of the system within the braces and then setting

$$f(x) = f_0(\overline{p}_x) = f_0(x, \overline{p}_{1,x}, \dots, \overline{p}_{k,x})$$

• We argued in each case that (*) expresses an algorithm for computing f from f_0, f_1, \ldots, f_k

• Key idea: An algorithm is the semantic content of a definition by simultaneous recursion

★ (Monotone) recursors $\alpha = (\alpha_0, \ldots, \alpha_k) : X \rightsquigarrow W$

• A recursor $\alpha : X \rightsquigarrow W$ on a poset X to a complete poset W is a tuple

$$\alpha = (\alpha_0, \alpha_1, \ldots, \alpha_k),$$

such that for suitable, complete posets D_1, \ldots, D_k :

- (1) Each part $\alpha_i: X \times D_1 \times \cdots D_k \to D_i$, $(i = 1, \dots, k)$ is monotone
- (2) The head part $\alpha_0 : X \times D_1 \times \cdots \times D_k \to W$ is also monotone
- $(\alpha_1, \ldots, \alpha_k)$ is the body of α ; $D_{\alpha} = D_1 \times \cdots \times D_k$ is its solution space; and its transition mapping $\tau_{\alpha} : X \times D_{\alpha} \to D_{\alpha}$ is

$$au_{lpha}(x,d) = (lpha_1(x,d),\ldots,lpha_n(x,d)) \quad (x \in X, d \in D_{lpha})$$

• The function $\overline{\alpha}: X \to W$ computed by α is

$$\overline{lpha}(x) = lpha_0(x, \overline{d}_x), \text{ where } \overline{d}_x = \min(d \in D_{lpha})[au_{lpha}(x, d) = d]$$

★ (Monotone) recursors $\alpha = (\alpha_0, \ldots, \alpha_k) : X \rightsquigarrow W$



- (1) X, W are posets and W is complete
- (2) The solution space $D_{\alpha} = D_1 \times \cdots \times D_{\alpha}$ of α is the (complete) product of complete posets D_1, \ldots, D_k
- (3) Each part $\alpha_i : X \times D_{\alpha} \to D_i$ (i = 1, ..., k) is monotone
- (4) The head $\alpha_0 : X \times D_\alpha \to W$ is monotone
- (5) The transition map $\tau_{\alpha} : X \times D_{\alpha} \to D_{\alpha}$ is given by $\tau_{\alpha}(x, d) = (\alpha_1(x, d), \dots, \alpha_k(x, d))$
- We express all this succinctly by writing

$$\begin{aligned} \alpha(x) &= \alpha_0(x, d) \text{ where } \{ d = \tau_\alpha(x, d) \}, \\ (\text{function}) & \overline{\alpha}(x) = \alpha_0(x, d) \, \overline{\text{where}} \, \{ d = \tau_\alpha(x, d) \} \end{aligned}$$

The importance of the solution space

$$\alpha(x) = \alpha_0(x, d)$$
 where $\{d = \tau_\alpha(x, d)\}, (x \in X, d \in D_\alpha = D_1 \times \cdots \times D_k)$

• The Morris example (Manna 1975)

$$p(s,t) = ext{if } (s=0) ext{ then } 0 ext{ else } p(s-1,p(s,t)) \Big| \quad (s,t\in\mathbb{N})$$

- The "official" associated recursor (with a head) is $\alpha(s,t) = p(s,t)$ where $\{p = \lambda(s,t) | \text{if } (s = 0) \text{ then } 0 \text{ else } p(s-1,p(s,t))] \}$
- If p varies over $\text{Strict}(\mathbb{N}^2_{\perp}, \mathbb{N}_{\perp}) \cong (\mathbb{N}^2 \to \mathbb{N})$ (call by value), then $\overline{\alpha}(s, t) = \overline{p}(s, t) = \text{if } (s = 0) \text{ then } 0 \text{ else } \perp (s, t \in \mathbb{N})$
- If p varies over $\operatorname{Cont}(\mathbb{N}_{\perp} \times \mathbb{N}_{\perp}, \mathbb{N}_{\perp})$ (call by name), then $\overline{\alpha}(s, t) = \overline{p}(s, t) = 0 \quad (s, t \in \mathbb{N})$
- A variant of the sieve of Eratosthenes can be expressed by a continuous recursor on the poset Streams(\mathbb{N}, \mathbb{N}) of all streams on \mathbb{N}

Natural recursor isomorphism (identity)

Suppose $\alpha, \beta : X \rightsquigarrow W$ are recursors

$$\begin{aligned} \alpha(x) &= \alpha_0(x, d) \text{ where } \{d = \tau_\alpha(x, d)\}, \quad D = D_1 \times \cdots, D_k \\ \beta(x) &= \beta_0(x, e) \text{ where } \{e = \tau_\beta(x, e)\}, \quad E = E_1 \times \cdots \times E_l \end{aligned}$$

★ A recursor does not change if we replace its posets by isomorphic copies and permute the order of the parts in its body
We say that α is naturally isomorphic (equal) with β, α ≅ β, if
k = l, i.e., α and β have the same number of parts
There is a permutation π : {1,..., k} → {1,..., k} and for each i = 1,..., k, a poset isomorphism ρ_i : D_i → E_{π(i)}, such that the induced isomorphism ρ_π : D → E preserves the parts, i.e.,

$$\begin{aligned} \alpha_0(x,d) &= \beta_0(x,\rho_\pi(d)),\\ \rho_i(\alpha_i(x,d)) &= \beta_{\pi(i)}(x,\rho_\pi(d)) \quad (i=1,\ldots,k) \end{aligned}$$

Natural recursor isomorphism is a very fine notion—perhaps too fine

Operations on recursors, I

• Trivial recursors. Each monotone function $f : X \to W$ can be viewed as a degenerate recursor $\delta_f = (f)$ with empty body,

$$\delta_f(x) = f(x)$$
 where $\{ \}$

• Composition of a recursor with a function. For $\beta: Y \rightsquigarrow W$ and $g: X \rightarrow Y$ a monotone function, define $\alpha: X \rightsquigarrow W$ by

$$\alpha(x) = \beta(g(x)) = \beta_0(g(x), d)$$
 where $\{d = \tau_\beta(g(x), d)\};$

then $\overline{\alpha}(x) = \overline{\beta}(g(x))$

Operations on recursors, II

• Recursor composition. For $\gamma: X \rightsquigarrow V$ and $\beta: V \times Y \rightsquigarrow W$, put

$$\begin{aligned} &\alpha(x,y) = \beta(\gamma(x),y) \\ &= \beta_0(v,y,d) \text{ where } \{v = \gamma_0(x,e), e = \tau_\gamma(x,e), d = \tau_\beta(v,y,d)\}; \end{aligned}$$

then
$$\overline{\alpha}(x,y) = \overline{\beta}(\overline{\gamma}(x),y)$$

• Composition with a function is not the same as composition with the trivial recursor representing it: e.g., if $\beta = \delta_f$ and $\gamma = \delta_g$,

$$\beta(g(x)) = \delta_f(g(x)) = f(g(x)) \text{ where } \{ \}$$

$$\cong \beta(\delta_g(x)) = \delta_f(\delta_g(x)) = f(v) \text{ where } \{v = g(x)\}$$

(Both of these recursors compute the same function $x \mapsto f(g(x))$)

Operations on recursors, III

• Recursor combination. For given recursors β^0, \ldots, β^k , put

$$\begin{aligned} \alpha(x) &= \quad \beta^{0}(x,d) \text{ where } \{d_{1} = \beta^{1}(x,d), \dots, d_{k} = \beta^{k}(x,d)\} \\ &= \quad \beta^{0}_{0}(x,d,e^{0}) \text{ where } \{d_{1} = \beta^{1}_{0}(x,d,e^{1}), \dots, d_{k} = \beta^{k}_{0}(x,d,e^{k}), \\ e^{0} &= \tau_{\beta^{0}}(x,d,e^{0}), \\ e^{1} &= \tau_{\beta^{1}}(x,d,e^{1}), \\ &\vdots \\ e^{k} &= \tau_{\beta^{k}}(x,d,e^{k})\}; \end{aligned}$$

then
$$\overline{\alpha}(x) = \overline{\beta}^0(x, d) \overline{where} \{ d_1 = \overline{\beta}^1(x, d), \dots, d_k = \overline{\beta}^k(x, d) \}$$

- This operation combines in parallel k + 1 recursive definitions
- Application: Proof of Kleene's First Recursion Theorem

Operations on recursors, IV, λ -substitution

Given $\gamma : X \times U \rightsquigarrow V$, $\beta : P \times Y \rightsquigarrow W$ with $P \subseteq Mon(U, V)$ complete, we want to define

(*)
$$\alpha(x, y) = \beta(\lambda u \gamma(x, u), y)$$

so that

(**)
$$\overline{\alpha}(x,y) = \overline{\beta}(\lambda u \overline{\gamma}(x,u),y)$$

The obvious necessary hypothesis is that

for all $x \in X$, $\lambda u \overline{\gamma}(x, u) \in P$

and when this holds, we set (with p ranging over P)

$$\alpha(x,y) = \beta(\lambda u \gamma(x,u), y) = \beta_0(p, y, e)$$

where $\left\{ e = \tau_\beta(p, y, e), p = \lambda u \gamma_0(x, u, d(u)), d = \lambda u \tau_\gamma(x, u, d(u)) \right\}$

which insures (**)

• Typically P = Strict(X, W) in first order or higher type recursion

The recursor representation of computation models If $\mathfrak{m} : X \rightsquigarrow W$ is a computation model expressed by the program

$$s := in(x)$$
; while $(s \notin T) \{ s := \sigma(s) \}$; return out (s) ,

we associate with \mathfrak{m} the tail recursor

 $\alpha_{\mathfrak{m}}(x) = p(\mathfrak{in}(x))$ where $\{p(s) = \mathfrak{if} (s \in T) \text{ then } \mathfrak{out}(s) \text{ else } p(\sigma(s))\}$

where *p* ranges over the poset of strict partial functions $(S \rightarrow W)$

Theorem (ynm, Paschalis)

For any two computation models $\mathfrak{m}, \mathfrak{m}' : X \rightsquigarrow W$ and with the natural notion of machine isomorphism,

$$\mathfrak{m} \cong \mathfrak{m}' \iff \alpha_{\mathfrak{m}} \cong \alpha_{\mathfrak{m}'}$$

• This result (with the specific definition of $\alpha_{\mathfrak{m}}$) insure that the recursor representation $\alpha_{\mathfrak{m}}$ of a computation model codes faithfully all the combinatorial and complexity properties of \mathfrak{m}

Implementations (sketch)

• For $\alpha, \beta: X \rightsquigarrow W$, a reduction (or direct simulation) of α to β is any monotone $\pi: X \times D_{\alpha} \rightarrow D_{\beta}$ such that for all $x, \in X, d \in D_{\alpha}$,

$$\begin{array}{l} (\mathsf{R1}) \ \ \tau_{\beta}(x,\pi(x,d)) \leq_{D_{\beta}} \pi(x,\tau_{\alpha}(x,d)) \\ (\mathsf{R2}) \ \ \beta_{0}(x,\pi(x,d)) \leq_{W} \alpha_{0}(x,d) \\ (\mathsf{R3}) \ \ \overline{\alpha}(x) = \overline{\beta}(x) \end{array}$$

• $\alpha \leq_{\mathsf{r}} \beta \iff$ there is a reduction $\pi : \mathsf{X} \times \mathsf{D}_{\alpha} \to \mathsf{D}_{\beta}$

• An implementation of $\alpha: X \rightsquigarrow W$ is any computation model $\mathfrak{m}: X \rightsquigarrow W$ such that $\alpha \leq_r \alpha_{\mathfrak{m}}$, and α is implementable if it has an implementation

• Most standard "implementations" of recursive algorithms satisfy this definition, but very little beyond this is known about this notion which is central to our

★ Main view: Algorithms are recursors and computation models implement them—when they are implementable

* Algorithms are recursors from given primitives

$$lpha(x) = lpha_0(x, d)$$
 where $\{d_1 = lpha_1(x, d), \dots, d_k = lpha_k(x, d)\}$

is an algorithm from $(\alpha_0, \alpha_1, \ldots, \alpha_k)$; obvious but not very useful

• Example. Duplication on \mathbb{N} from 0, *S*, Pd and $=_0$:

$$\alpha(x) = p(x, x) \text{ where } \left\{ p(x, y) = \boxed{\text{ if } (y = 0) \text{ then } x \text{ else } S(p(x, \text{Pd}(y)))} \right\}$$
$$\overline{p}(x, y) = x + y, \quad \overline{\alpha}(x) = \overline{p}(x, x) = 2x$$

• α is an algorithm from the function defined in the box

$$\beta(x) = p(x, x) \text{ where } \left\{ p(x, y) = \text{ if } q_1(x, y) \text{ then } x \text{ else } q_2(x, y), \\ q_1(x, y) = \chi_{=_0}(y), \quad q_2(x, y) = S(q_3(x, y)), \\ q_3(x, y) = p(x, q_4(x, y)), \quad q_4(x, y) = \mathsf{Pd}(y) \right\}$$

• Again $\overline{\beta}(x) = 2x$, and β is an algorithm from 0, S, Pd, $=_0$, because its parts are direct calls to these primitives and the conditional

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$$\alpha = (\alpha_0, \alpha_1, \dots, \alpha_k) : X \rightsquigarrow W$$

$$\alpha(x) = \alpha_0(x, d) \text{ where } \{d_1 = \alpha_1(x, d), \dots, d_k = \alpha_k(x, d)\}$$

• What does it mean to say that

(*)
$$\alpha$$
 is from $oldsymbol{\Phi}$

- Φ must include the complete posets in the solution space
 D = D₁ × ··· × D_k of α
 (to distinguish e.g., call-by-value from call-by-name)
- Φ may include "given" functions and operations on various sets and posets (like 0, S, Pd, =₀ in the example)
- The conditional and recursive calls should be allowed "for free", together (perhaps) with other logical operations
- A definition of (*) in the most general case is difficult to formulate (and in any case I don't have one I like)
- I will develop here the simplest and most useful case of first-order primitives and then discuss some of its extensions

The term language $L(\Phi)$, $M = (\{M_i\}_{i \in I}, \{\varphi^M \mid \varphi \in \Phi\})$

- Individual variables v_0^i, v_1^i, \ldots for each sort $i \in I$
- Function variables p_0^s, p_1^s, \ldots for each type $s = (\langle i_1, \ldots, i_{n-1} \rangle, j)$
- Constants φ for each function symbol $\varphi \in \Phi$

• Terms and their sorts and free and bound variable occurrences are defined recursively, subject to the natural restrictions:

$$\begin{array}{l} A :\equiv \texttt{t} \mid \texttt{ff} \mid \textit{v} \mid \textit{p}(A_1, \dots, A_n) \mid \varphi(A_1, \dots, A_n) \\ \quad \mid \texttt{if} \; A \; \texttt{then} \; B \; \texttt{else} \; C \\ \quad \mid A_0 \; \texttt{where} \; \{\textit{p}_1(u_1) = A_1, \dots, \textit{p}_k(u_k) = A_k\} \end{array}$$

• In the recursive term $A \equiv A_0$ where $\{p_1(u_1) = A_1, \dots, p_k(u_k) = A_k\}$:

- Each u_i is a list of individual variables which are bound in all their occurrences in the equation $p_i(u_i) = A_i$ (equivalent to $p_i = \lambda u_i A_i$)
- Each function variable p_i is bound in all its occurrences in A

-
$$\operatorname{sort}(A) = \operatorname{sort}(A_0)$$

Denotational semantics of $L(\Phi)$, $M = (\{M_i\}_{i \in I}, \{\varphi^M \mid \varphi \in \Phi\})$

$$A :\equiv \texttt{t} \mid \texttt{ff} \mid v \mid p(A_1, \dots, A_n) \mid \varphi(A_1, \dots, A_n)$$
$$\mid \texttt{if } A \texttt{ then } B \texttt{ else } C$$

$$|A_0 \text{ where } \{p_1(u_1) = A_1, \dots, p_k(u_k) = A_k\}$$

• If type(p) = ($\langle i_1, \dots, i_{n-1} \rangle$, j), then $p : M_{i_1} \times \dots \times M_{i_{n-1}} \rightharpoonup M_j$

• For each term A, each sequence x of distinct individual and function variables which includes all the free variables of A, and each sequence x of objects of **M** with matching sorts and types

$$den(A){x := x} = the denotation of A when x = x$$

- Standard definition, using least-fixed-points for recursion
- A partial function or functional f : X → M_j is recursive in M if
 f(x) = den(A){x := x} for some term A and variables x
- \bullet $\mathsf{rec}(N_1)=\mathsf{rec}(N_2)$ =the classical recursive partial functionals on $\mathbb N$

 \bullet John McCarthy's elegant, deterministic definition of recursion on $\mathbb N$

Elementary algorithms, $\mathbf{M} = (\{M_i\}_{i \in I}, \{\varphi^{\mathbf{M}} \mid \varphi \in \Phi\})$ $A :\equiv tt \mid ff \mid v \mid p(A_1, \dots, A_n) \mid \varphi(A_1, \dots, A_n)$ $\mid if A \text{ then } B \text{ else } C$ $\mid A_0 \text{ where } \{p_1(u_1) = A_1, \dots, p_k(u_k) = A_k\}$

- Immediate: $Z :\equiv u \mid p(u_1, \ldots, u_m)$
- Exp-irreducible: $T := Z \mid \mathfrak{t} \mid \mathsf{ff} \mid \varphi(Z_1, \ldots, Z_n) \mid \mathsf{if} \ Z_1 \ \mathsf{then} \ Z_2 \ \mathsf{else} \ Z_3$
- An M-algorithm or algorithm from $\{\varphi^{M} \mid \varphi \in \Phi\}$ is any recursor

(*)
$$\alpha(x) = \alpha_0(x, \vec{p})$$
 where

$$\left\{ p_1(u_1) = \alpha_1(u_1, x, \vec{p}), \dots, p_k(u_k) = \alpha_k(u_k, x, \vec{p}) \right\}$$

in which every α_i is defined in **M** by an explicit irreducible term

- Key idea: the (absolute) primitives of first-order computation are
 - the constants tt, ff,
 - random access to function variables $p(u_1, \ldots, u_m)$,
 - calls to the given primitives and the conditional,
 - mutual recursion

Referential intensions, $\mathbf{M} = (\{M_i\}_{i \in I}, \{\varphi^{\mathbf{M}} \mid \varphi \in \Phi\})$ $A :\equiv \mathfrak{t} \mid \mathrm{ff} \mid v \mid p(A_1, \dots, A_n) \mid \varphi(A_1, \dots, A_n)$ $\mid \mathrm{if} A \mathrm{then} B \mathrm{else} C$ $\mid A_0 \mathrm{where} \{p_1(u_1) = A_1, \dots, p_k(u_k) = A_k\}$

• With each term A and list x of distinct variables which includes all the free variables of A, we can associate its referential intension int(A)(x) = $\alpha_0(x, \vec{p})$ where $\left\{ p_1(u_1) = \alpha_1(u_1, x, \vec{p}), \dots, p_k(u_k) = \alpha_k(u_k, x, \vec{p}) \right\},$

an algorithm of **M** which computes $den(A)\{x := x\}$

• This is done by a (careful) recursion on *A*, which takes into account which subterms of *A* are immediate

- Immediate terms $Z \equiv u \mid p(u_1, \dots, u_m)$ are assigned functions, not recursors; they denote immediately
- Exp-irreducible terms Z | tt | ff | φ(Z₁,..., Z_n) | if Z₁ then Z₂ else Z₃ are assigned trivial recursors; they denote directly

 $\mathbf{M} = (M, \{ \varphi^{\mathbf{M}} \mid \varphi \in \Phi \}), \quad alg(\mathbf{M}) = the algorithms of \mathbf{M}$

 \bullet The algorithms of ${\bf M}$ compute the ${\bf M}\mbox{-recursive partial functions}$ and relations on M

• They can be easily specified using $\Phi\text{-}\mathsf{recursive}$ programs, i.e., terms of $L(\Phi)$

 \bullet alg(M) is closed under many operations on recursors, including composition and recursion combination

• There is a small, interesting collection of facts about these objects

★ The basic definitions and results can be extended easily to structures whose universes are the sets in the higher types over given basic sets $\{M_i\}_{i \in I}$ and whose primitives are higher type objects of various kinds Basic example: the Gentzen cut elimination algorithm on extensions of arithmetic with the ω -rule (cf. Schwichtenberg's article in the Handbook of Logic)

Yiannis N. Moschovakis: What is an algorithm?

Applications to complexity in arithmetic

• Calls complexity. For each algorithm $\alpha : M^n \rightsquigarrow M_j$ of a structure $\mathbf{M} = (M, \{\varphi^{\mathbf{M}} \mid \varphi \in \Phi\})$ and each $\Phi_0 \subseteq \Phi$, we can define

 $\operatorname{calls}_{\alpha}^{\Phi_0}(x) = \operatorname{the number of calls to primitives } \varphi^{\mathsf{M}} \text{ with } \varphi \in \Phi_0$ made by α in the computation of $\overline{\alpha}(x) \quad (\overline{\alpha}(x)\downarrow)$

This agrees with the usual calls-complexity for "concrete algorithms" defined by computation models

• Many more "natural" complexity functions including time $_{\alpha}(x)$ and

size_{α}(x) = the size of the smallest set $M_x \subseteq M$

that α must see to compute $\overline{\alpha}(x) \leq \text{calls}_{\alpha}(x) = \text{calls}_{\alpha}^{\Phi}(x)$

• Obvious: $(\mathbb{N}, 0, S, \mathsf{Pd}, =_0) = \mathsf{rec}(\mathbb{N}, 0, 1, \mathsf{iq}_2, \mathsf{rem}_2, \mathsf{em}_2, \mathsf{om}_2, =_0)$ but $\mathsf{alg}(\mathbb{N}, 0, S, \mathsf{Pd}, =_0) \neq \mathsf{alg}(\mathbb{N}, 0, 1, \mathsf{iq}_2, \mathsf{rem}_2, \mathsf{em}_2, \mathsf{om}_2, =_0)$

• Complexity theory for elementary algorithms depends heavily and essentially on the primitives included in the structure

The weak optimality of Stein's algorithm for coprimeness

 $x ext{ is coprime with } y \iff \gcd(x,y) = 1 \quad (x,y \in \mathbb{N}^+)$

• The structure of Stein: $N_s = (\mathbb{N}, 0, 1, +, -, iq_2, rem_2, <, =)$

The primitives are **Presburger** (piecewise linear) functions and relations

• Stein's algorithm $\sigma : \mathbb{N}^+ \times \mathbb{N}^+ \rightsquigarrow \mathbb{N}$ computes gcd(x, y) and so decides coprimeness in \mathbf{N}_s with $calls_{\sigma}(x, y) \leq C \log \max(x, y)$

Theorem (van den Dries, ynm, 2004, 2009)

If an algorithm α from finitely many Presburger primitives decides coprimeness on \mathbb{N} , then for some r > 0 and all a > 2,

$$\mathsf{calls}_{\alpha}(a,a^2-1) > r \log_2(a^2-1)$$

It follows that Stein's algorithm is optimal (up to a multiplicative constant) from Presburger primitives on infinitely many inputs

• Similar lower bounds for Presburger algorithms hold for *primality*, *being a perfect square*, *having no square factors* and several more relations in arithmetic and algebra

Yiannis N. Moschovakis: What is an algorithm?

A lower bound for algorithms from division with remainder

Theorem (van den Dries, ynm, 2004, 2009)

Suppose α is an algorithm from finitely many Presburger primitives, iq and rem, and $\xi > 1$ is a quadratic irrational; there is some r > 0 such that for all sufficiently large coprime $a, b \in \mathbb{N}$

$$\left|\xi - \frac{a}{b}\right| < \frac{1}{b^2} \implies \mathsf{calls}_{\alpha}(a, b) > r \log_2 \log_2 a$$

In particular, this holds

- for positive Pell pairs (a, b) satisfying $a^2 = 2b^2 + 1$ $(\xi = \sqrt{2})$
- For Fibonacci pairs (F_{k+1}, F_k) with $k \ge 3$ $(\xi = \frac{1}{2}(1 + \sqrt{5}))$
- This is one log short of the conjecture about the Euclidean and the method of proof cannot prove it (Vaughan Pratt)
- The discovery of the results in this and the preceding slide depend essentially on the notion of elementary recursive algorithm

Frege's sense and denotation as algorithm and value

1+1=2 vs. there are infinitely many primes
 Same denotation (truth value) but different meaning

• Frege: Each closed well-formed "term" (including every sentence) has a sense (meaning) which determines its denotation,

$$A \mapsto \operatorname{sense}(A) \mapsto \operatorname{den}(A)$$

- [The sense of a sign]
- may be the common property of many people,
- is grasped by everyone who is sufficiently familiar with the language,
- [is preserved by faithful translation]
- The sense contains the mode of presentation of the denotation
- Common view: sense(A) is a "process" which computes den(A)
- With a precise notion of (abstract) "algorithm" replacing "process", it is possible to turn this view into an interesting mathematical theory of meaning and synonymy

Adding meaning to Montague semantics

• Language: The typed λ -calculus with acyclic recursion L_{ar}^{λ} , an extension of Richard Montague's language of intensional logic which can "express" substantial fragments of natural language

• Interpretation: In every higher type structure **M** over basic sets of entities, truth values and states, each closed term A of L_{ar}^{λ} is assigned

a value den(A) and a referential intension int(A)

int(A) is an **M**-algorithm, the meaning of A, and it computes den(A)

• int(A) and the synonymy relation $int(A) \cong int(B)$ are definable in L_{ar}^{λ}

• The theory yields defensible accounts of some standard puzzles about global and local synonymy in the philosophy of language, e.g.,

he is the thief $\not\cong_a$ George is the thief in a state *a* where he(*a*) = George

• It can express quantification and anaphora into propositional attitudes

George claims that someone stole his laptop

Machines vs. recursors on total $\mathbf{M} = (\{M_i\}_{i \in I}, \{\varphi^{\mathbf{M}} \mid \varphi \in \Phi\})$

• An M-machine is a computation model $(S, in, \sigma, T, out) : M^n \rightsquigarrow M_j$ in which $S = M^k$ for some k and in, σ, T , out are definable by explicit Φ -terms

• Tiuryn's Theorem: There is a structure ${\bf M}$ and an ${\bf M}$ -recursive relation which cannot be decided by any machine of ${\bf M}$

• Fact: Every algorithm α of a structure **M** can be implemented by a machine of some **M**^{*}, an expansion of an extension of **M**

• Typically M^* is the set of all finite sequences from the M'_is and the additional primitives manipulate these strings—but there are many choices for \mathbf{M}^* and no principled way to choose one among them

• Divide-and-conquer recursive algorithms (such as that of Tiuryn) include the mergesort, the (finitary) Gentzen cut-elimination algorithm, etc. Most (arguably all) their important properties can be derived directly from their recursive specifications

What are the absolute primitives of elementary algorithms?

- In modeling elementary algorithms by recursors, we assumed "for free"
- (1) random access to function variables,
- (2) calls to the primitives,
- (3) branching, and
- (4) mutual recursion

• In defining computation models which do not have function variables, (1) is typically replaced by assignments

x := A (with an explicit term A)

• Random Access Machines (RAMs) over $\mathbf{M} = (M, \{\varphi^{\mathbf{M}} \mid \varphi \in \Phi\})$ allow a partial function $F : M \rightarrow M$ and assignments F(a) := b

• If 0,1 and $=_0$ are among the primitives of **M** for some $0, 1 \in M$, then equality on M is decided by the RAM program

F(x) := 1; F(y) := 0; if (F(x) = 0) return t else return ff

 \bullet This can be managed for N_1 or $N_2,$ but not in the abstract case