

On defining “algorithm” — why and how?

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Outline

- (I) Features of algorithms:
dependence on primitives, uniformity, effectiveness

- (II) Recursion and computation

- (III) Exploiting uniformity:
The axiomatic derivation of absolute lower bounds

Basic reference *On founding the theory of algorithms*, 1998

Together with other, newer articles and references to others' articles in their bibliographies, on my homepage
[www.math.ucla.edu~ynm](http://www.math.ucla.edu/~ynm)

The Church-Turing Thesis (CT) for $\mathbb{N} = \{0, 1, \dots\}$

- ▶ (CT): If $f : \mathbb{N}^n \rightarrow \mathbb{N}$ is **computable** (by some algorithm), then f is also computed by a Turing machine
- ▶ Does not define (in fact avoids defining) **algorithms**
- ▶ Main application: **undecidability results**
To show that a relation cannot be decided (by any algorithm), we prove that its characteristic function cannot be computed by a Turing machine
- ▶ Key methods of proof: **diagonalization** and **reduction** (of some known undecidable problem to the problem we want to prove undecidable)
- ▶ The precise definition of **algorithms** is almost certainly irrelevant to the development of undecidability theory on \mathbb{N} . (It may be useful for extending the theory to other domains)

The Euclidean algorithm

For $x, y \in \mathbb{N}$, $x \geq y \geq 1$,

$$(\varepsilon) \quad \boxed{\text{gcd}(x, y) = \text{if } (\text{rem}(x, y) = 0) \text{ then } y \text{ else } \text{gcd}(y, \text{rem}(x, y))}$$

where $\text{rem}(x, y)$ is the remainder of the division of x by y ,

$$x = \text{iq}(x, y)y + \text{rem}(x, y) \quad (0 \leq \text{iq}(x, y), 0 \leq \text{rem}(x, y) < y)$$

$\text{calls}_\varepsilon(x, y) =$ the number of divisions (calls to rem)

required to compute $\text{gcd}(x, y)$ by the Euclidean algorithm

$$\leq 2 \log(y) \quad (x \geq y \geq 2)$$

- ▶ Is the Euclidean optimal for **computing** $\text{gcd}(x, y)$ from rem ?
- ▶ Is the Euclidean optimal for **deciding coprimeness** from rem ?

$$x \perp y \iff \text{gcd}(x, y) = 1$$

We need a notion of **algorithm from rem** to answer these questions

Dependence of algorithms on primitives

- ▶ Algorithms are not absolute but **from (relative to)** specified primitives
- ▶ For simplicity, I will consider here only **finitary algorithms**: they compute a partial function $f : A^n \rightarrow A$ on a given set A , **from given partial functions** (of any arity) on A
- ▶ For convenience, we also assume (harmlessly): A contains two distinct elements $0 = \text{falsity}$ and $1 = \text{truth}$; so each relation $R \subseteq A^N$ is identified with its **characteristic function** $\chi_R : A^n \rightarrow \{0, 1\} \subseteq A$
- ▶ Algorithms of a **partial algebra**: $\mathbf{A} = (A, 0, 1, \phi_1^{\mathbf{A}}, \dots, \phi_k^{\mathbf{A}})$

A weak, relative lower bound for coprimeness

Theorem (van den Dries, ynm, 2004, 2009)

If a recursive algorithm α decides the coprimeness relation $x \perp\!\!\!\perp y$ on \mathbb{N} from the primitives $\leq, +, -, \text{iq}, \text{rem}$, then for infinitely many x, y with $x > y$,

$$\text{calls}_\alpha(x, y) \geq \text{depth}_\alpha(x, y) > \frac{1}{10} \log \log x \quad (*)$$

where $\text{depth}_\alpha(x, y)$ is the least number of applications of the primitives which **must be executed in sequence** in the computation

- ▶ $\text{depth}_\alpha(x, y)$ is a natural parallel time complexity measure
- ▶ The result is one log short of establishing the optimality of the Euclidean (and one log = ∞ in this context)
- ▶ (*) holds for all sufficiently large x, y such that
 - $x^2 = 1 + 2y^2$ (solutions of Pell's equation),
 - or $x = F_{n+1}, y = F_n$ (successive Fibonacci numbers)
- ▶ Claim: **This applies to all algorithms from the specified primitives**

Uniformity of algorithms

- ▶ To establish that

$$\text{depth}_\alpha(x, y) > \frac{1}{10} \log \log x$$

for the specified x, y , we appeal to the fact that

the same algorithm α decides whether $\lambda x \perp\!\!\!\perp \lambda y$, where $\lambda = 1 + x!$

- ▶ An $\boxed{\text{algorithm of } \mathbf{A} = (A, 0, 1, \phi_1^{\mathbf{A}}, \dots, \phi_k^{\mathbf{A}})}$ must compute $f(\vec{x})$ for every $\vec{x} \in A^n$ such that $f(\vec{x})$ is defined (converges)

General features of finitary algorithms

Suppose α is a finitary algorithm which computes some $f : A^n \rightarrow A$:

- ▶ **Dependence on primitives:** α computes f from specified (partial) functions ψ_1, \dots, ψ_k on A
- ▶ **Uniformity:** α computes $f(\vec{x})$ for every \vec{x} in the domain of convergence of f
- ▶ **Effectiveness:** α is effective
- ▶ Effectiveness is the most difficult feature of algorithms to make precise in a general (abstract, logical, not ad hoc) way
- ▶ Surprisingly: Sometimes effectiveness does not come into the derivation of interesting lower bounds for algorithms

Iterative algorithms (mechanical procedures)

vs. recursive algorithms

The mergesort (recursive) algorithm

L is a set , $L^* = \{w = (w_0, \dots, w_{n-1}) \mid w_i \in L\}$, $|w| = n \geq 0$

$x * w = (x, w_0, \dots, w_{n-1})$, $\text{head}(w) = w_0$, $\text{tail}(w) = (w_1, \dots, w_{n-1})$,

$\text{half}_1(w) = (w_0, \dots, w_{\lfloor n/2 \rfloor - 1})$, $\text{half}_2(w) = (w_{\lfloor n/2 \rfloor}, \dots, w_{n-1})$

\leq a (total) ordering of L , w is **sorted** $\iff w_0 \leq w_1 \leq \dots \leq w_{n-1}$,

$\text{sort}(w) =$ the unique, sorted w' such that

for some $\pi : \{0, \dots, n-1\} \rightarrow \{0, \dots, n-1\}$, $w'_i = w_{\pi(i)}$

$\text{sort}(w) = \text{merge}(\text{sort}(\text{half}_1(w)), \text{sort}(\text{half}_2(w)))$

$\text{merge}(u, v) =$ if $(|u| = 0)$ then v

else if $(|v| = 0)$ then u

else if $(\boxed{\text{head}(u) \leq \text{head}(v)})$ then $\text{head}(u) * \text{merge}(\text{tail}(u), v)$

else $\text{head}(v) * \text{merge}(u, \text{tail}(v))$

The mergesort computes $\text{sort}(w)$ using $\leq |w|(\log |w|)$ comparisons

The (first order) Formal Language of Recursion FLR(Φ)

$\Phi = \{\phi_1, \dots, \phi_k\}$ (partial function constants)

Variables : $v_0, v_1, \dots, p_0^m, p_1^m, \dots$ (for m -ary partial functions)

Terms (programs) : $t ::= 0 \mid 1 \mid v_i \mid \phi_i(t_1, \dots, t_{k_i}) \mid p_i^m(t_1, \dots, t_m)$
| if $(t_0 = 0)$ then t_1 else t_2
| t_0 where $\{p_1(\vec{u}_1) = t_1, \dots, p_n(\vec{u}_n) = t_n\}$

(In the **recursion construct** $p_1, \vec{u}_1, p_2, \vec{u}_2, \dots, p_n, \vec{u}_n$ are **bound** in t)

- ▶ FLR(Φ) is interpreted on (partial) Φ -**algebras**

$$\mathbf{A} = (A, 0, 1, \Phi^{\mathbf{A}}) = (A, 0, 1, \phi^{\mathbf{A}}, \dots, \phi_k^{\mathbf{A}})$$

- ▶ **Denotational semantics**: the recursion construct is interpreted by the taking of **least fixed points**

REC(\mathbf{A}) = the recursive partial functionals of \mathbf{A}

the partial functionals on A defined by terms of FLR(Φ)

(For $\mathbf{N} = (\mathbb{N}, 0, 1, S, Pd)$, essentially McCarthy 1963)

The intensional semantics of FLR(Φ)

- ▶ A **reduction calculus** $s \Rightarrow t$ is defined on the terms of FLR(Φ). It models **partial program compilation** (not computation)
- ▶ It is shown (easily) that every term t reduces (compiles) to exactly one (up to **congruence**) **irreducible, recursive term**

$$t \Rightarrow \text{cf}(t) \equiv t_0 \text{ where } \{p_1(\vec{u}_1) = t_1, \dots, p_n(\vec{u}_n) = t_n\}$$

$\text{cf}(t)$ is the **canonical form** of t

- ▶ If \vec{x} contains all the free variables of $t(\vec{x})$ and \mathbf{A} is a Φ -algebra, we set

$$f_i^{\mathbf{A}}(\vec{x}, \vec{u}_i, p_1, \dots, p_n) = \text{den}(t_i(\vec{x}))(\mathbf{A}, \vec{u}_i, p_1, \dots, p_n) \quad (i = 0, \dots, n)$$

$\text{int}^{\mathbf{A}}(t(\vec{x})) = (f_0^{\mathbf{A}}, \dots, f_n^{\mathbf{A}})$ = the **referential intension** of $t(\vec{x})$ in \mathbf{A}

- ▶ Claim: $\text{int}^{\mathbf{A}}(t(\vec{x}))$ **models faithfully** the **recursive algorithm** expressed by $t(\vec{x})$ in \mathbf{A}

Key assumption: mutual recursion is a primitive algorithmic construct

Summary

- ▶ Every algorithm α of an algebra $\mathbf{A} = (A, 0, 1, \Phi^{\mathbf{A}})$ which computes $\bar{\alpha} : A^n \rightarrow A$ is **faithfully represented** by the referential intension $\text{int}^{\mathbf{A}}(t(\vec{x}))$ of some FLR(Φ) program $t(\vec{x})$
- ▶ $\text{int}^{\mathbf{A}}(t(\vec{x}))$ is a **recursor**, a tuple of functionals on A satisfying certain conditions. (It is a **semantic** object)
- ▶ Two algorithms are **equal** if their representing recursors are **naturally isomorphic** (the same tuples of functionals except for “rearrangement”)
- ▶ Suppose $\mathbf{A} = (0, 1, \phi^{\mathbf{A}}, \psi^{\mathbf{A}})$ and for all $x \in A$, $\phi^{\mathbf{A}}(x) = \psi^{\mathbf{A}}(x)$; then

$$\text{int}^{\mathbf{A}}(\phi(x)) = \text{int}^{\mathbf{A}}(\psi(x))$$

Recursive vs. iterative algorithms

- ▶ Iterative algorithms can be viewed as special cases of recursive algorithms (tail recursions)
- ▶ Many familiar complexity measures can be defined directly for FLR(Φ) programs so that **implementation independent** upper bounds for them can be easily established (e.g., the mergesort)
- ▶ Sample (classical) lower bound result: *every recursive algorithm which computes $\text{sort}(w)$ for every $w \in L^*$ from the primitives of the mergesort executes at least $\log(|w|!)$ comparisons*
- ★ The theory extends naturally to **infinitary algorithms**:
 - Algorithms which interact with their environment, drop bombs, ...
 - Recursion in higher types (Kleene). Adds algorithmic content:
 - ▶ Gentzen's infinitary cut elimination algorithm for arithmetic
 - ▶ Modeling Frege's **sense of a term** t in Montague semantics by the **referential intension of** t (which computes its denotation)

Model theory of arbitrary structures \Rightarrow finite model theory

vs. direct and independent development of finite model theory

The Recursive Computability Thesis

- RCT: If a partial function $f : A^n \rightarrow A$ is *recursively computable* from ψ_1, \dots, ψ_k , then $f \in \text{REC}(A, 0, 1, \psi_1, \dots, \psi_k)$
 - ▶ RCT basically accepts **calling** (composition) and **branching** as fundamental algorithmic constructs, and claims that the primary (algorithmic) interpretation of self-referential definitions is by the taking of **least fixed points** (grounded recursion)
 - ▶ The definition of $\text{REC}(\mathbf{A})$ does not involve any objects outside \mathbf{A}
 - ▶ \mathbf{A} -recursion is a **logical notion**, preserved by isomorphisms

Theorem (RCT). $f : \mathbb{N} \rightarrow \mathbb{N}$ is recursively computable

if and only if f is Turing computable (**No primitives mentioned**)

Proof. If f is recursive on the natural numbers, then $f \in \text{REC}(\mathbb{N}, 0, 1, S, =)$ because (up to isomorphism)

the natural numbers are the algebra $(\mathbb{N}, 0, 1, S, =)$

and hence f is Turing computable, by classical results ↯

Computability on \mathbb{N} = recursive computability + what the numbers are

Uniform processes (skipping definitions of underlined terms)

An n -ary **uniform process** α of an algebra $\mathbf{A} = (A, 0, 1, \Phi^{\mathbf{A}})$ is a mapping

$$\mathbf{A} \supseteq_p \mathbf{U} \mapsto \bar{\alpha}^{\mathbf{U}} : U^n \rightarrow U$$

on subalgebras of \mathbf{A} to partial functions on their universes such that:

- (1) **Embedding property**: If $\pi : \mathbf{U} \rightarrow \mathbf{V}$ is an embedding of one subalgebra of \mathbf{A} into another, then

$$\bar{\alpha}^{\mathbf{U}}(\vec{x}) = w \implies \bar{\alpha}^{\mathbf{V}}(\pi(\vec{x})) = \pi(w)$$

- (2) **Finiteness property**: If $\bar{\alpha}^{\mathbf{A}}(\vec{x}) = w$, then there exists a finite $\mathbf{U} \subseteq_p \mathbf{A}$, generated by $\{0, 1, \vec{x}\}$ such that $\bar{\alpha}^{\mathbf{U}}(\vec{x}) = w$

A uniform process α of \mathbf{A} **computes** the partial function $\bar{\alpha}^{\mathbf{A}} : A^n \rightarrow A$

- ▶ Every recursive algorithm of \mathbf{A} induces a uniform process which computes the same function and with the same complexity measures. Plausibly: every “algorithm” of \mathbf{A} , too
- ▶ Every $f : \mathbb{N} \rightarrow \mathbb{N}$ is computed by a uniform process of $(\mathbb{N}, 0, 1, S)$

Some lower bounds depend only on uniformity

Theorem (van den Dries, ynm, 2004, 2009)

If a uniform process α of $(\mathbb{N}, 0, 1, \leq, +, -, \text{iq}, \text{rem})$, decides the coprimeness relation $x \perp y$ on \mathbb{N} , then for infinitely many x, y with $x > y$ (e.g., if $x^2 = 1 + 2y^2$ or $x = F_{n+1}, y = F_n, x, y$ large)

$$\text{calls}_\alpha(x, y) \geq \text{depth}_\alpha(x, y) > \frac{1}{10} \log \log x$$

So, in particular, this holds for all recursive programs and all other, familiar models of relative computation (deterministic or non-deterministic) which decide coprimeness from the primitives of $(\mathbb{N}, 0, 1, \leq, +, -, \text{iq}, \text{rem})$

Poly evaluation and 0-testing in $\mathbf{C} = (\mathbb{C}, 0, 1, +, -, \cdot, \div, =)$

For $a_0, \dots, a_n, x \in \mathbb{C}$ and $n \geq 1$:

$$\text{Value}(a_0, a_0, \dots, a_n, x) = V(\vec{a}, x) = a_0 + a_1x + \dots + a_nx^n,$$

$$\text{Nullity}(a_0, a_0, \dots, a_n, x) \iff N(\vec{a}, x) \iff a_0 + a_1x + \dots + a_nx^n = 0$$

- ▶ **Horner's Rule:** $V(\vec{a}, x)$ can be computed by a straight line program using n (\cdot) and n $(+)$
 - ▶ (**Pan 1966, Winograd 1967**): Every straight line program which computes $V(\vec{a}, x)$ for all $\vec{a}, x \in \mathbb{C}$ executes at least n (\cdot/\div) and n $(+/-)$ when \vec{a}, x are algebraically independent
 - ▶ Every uniform process of \mathbf{C} which decides $N(\vec{a}, x)$ for all $\vec{a}, x \in \mathbb{C}$ executes at least n (\cdot/\div) when \vec{a}, x are algebraically independent
- (**Bürgisser, Lickteig 1991** for straight line programs with conds)