Homework 7 Solutions

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Section 7.3, Problem 9(a): Find the first two iterations of the SOR method with $\omega = 1.1$ for the following linear system, using $\mathbf{x}^{(0)} = \mathbf{0}$:

$$3x_1 - x_2 + x_3 = 1,$$

$$3x_1 + 6x_2 + 2x_3 = 0,$$

$$3x_1 + 3x_2 + 7x_3 = 4.$$
(1)

Solution: For general linear system $A\mathbf{x} = \mathbf{b}$ in n equations and n unknowns, we have

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}, \qquad \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}.$$

Successive Over-Relaxation (SOR) method for such system can be written as

$$x_i^{(k)} = (1 - \omega)x_i^{(k-1)} + \frac{\omega}{a_{ii}} \left[b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k)} - \sum_{j=i+1}^n a_{ij} x_j^{(k-1)} \right],$$
 (2)

for some ω and $i = 1, 2, \ldots, n$.

For 3×3 system in (1), we have

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = \begin{bmatrix} 3 & -1 & 1 \\ 3 & 6 & 2 \\ 3 & 3 & 7 \end{bmatrix}, \qquad \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 4 \end{bmatrix}.$$

This linear system has the unique solution $\mathbf{x} = (0.0351, -0.2368, 0.6579)$. For 3×3 system, equations in (2) are written and simplified as

$$\begin{split} x_1^{(k)} &= (1-\omega)x_1^{(k-1)} + \frac{\omega}{a_{11}} \bigg[b_1 - \sum_{j=2}^3 a_{1j} x_j^{(k-1)} \bigg] \\ &= (1-\omega)x_1^{(k-1)} + \frac{\omega}{a_{11}} \bigg[b_1 - a_{12} x_2^{(k-1)} - a_{13} x_3^{(k-1)} \bigg], \\ x_2^{(k)} &= (1-\omega)x_2^{(k-1)} + \frac{\omega}{a_{22}} \bigg[b_2 - \sum_{j=1}^1 a_{2j} x_j^{(k)} - \sum_{j=3}^3 a_{2j} x_j^{(k-1)} \bigg] \\ &= (1-\omega)x_2^{(k-1)} + \frac{\omega}{a_{22}} \bigg[b_2 - a_{21} x_1^{(k)} - a_{23} x_3^{(k-1)} \bigg], \\ x_3^{(k)} &= (1-\omega)x_3^{(k-1)} + \frac{\omega}{a_{33}} \bigg[b_3 - \sum_{j=1}^2 a_{3j} x_j^{(k)} \bigg] \\ &= (1-\omega)x_3^{(k-1)} + \frac{\omega}{a_{33}} \bigg[b_3 - a_{31} x_1^{(k)} - a_{32} x_2^{(k)} \bigg]. \end{split}$$

Plugging in the values into these equations, we obtain

$$x_1^{(k)} = -0.1x_1^{(k-1)} + \frac{1.1}{3} \left[1 + x_2^{(k-1)} - x_3^{(k-1)} \right],$$

$$x_2^{(k)} = -0.1x_2^{(k-1)} + \frac{1.1}{6} \left[-3x_1^{(k)} - 2x_3^{(k-1)} \right],$$

$$x_3^{(k)} = -0.1x_3^{(k-1)} + \frac{1.1}{7} \left[4 - 3x_1^{(k)} - 3x_2^{(k)} \right].$$

Using the initial condition $\mathbf{x}^{(0)} = \mathbf{0}$, the first iteration gives:

$$x_1^{(1)} = -0.1x_1^{(0)} + \frac{1.1}{3} \left[1 + x_2^{(0)} - x_3^{(0)} \right] = 0.36666666666667,$$

$$x_2^{(1)} = -0.1x_2^{(0)} + \frac{1.1}{6} \left[-3x_1^{(1)} - 2x_3^{(0)} \right] = -0.20166666666667,$$

$$x_3^{(1)} = -0.1x_3^{(0)} + \frac{1.1}{7} \left[4 - 3x_1^{(1)} - 3x_2^{(1)} \right] = 0.55078571428571.$$

The second iteration gives:

$$\begin{aligned} x_1^{(2)} &= -0.1x_1^{(1)} + \frac{1.1}{3} \left[1 + x_2^{(1)} - x_3^{(1)} \right] = 0.05410079365079, \\ x_2^{(2)} &= -0.1x_2^{(1)} + \frac{1.1}{6} \left[-3x_1^{(2)} - 2x_3^{(1)} \right] = -0.21154353174603, \\ x_3^{(2)} &= -0.1x_3^{(1)} + \frac{1.1}{7} \left[4 - 3x_1^{(2)} - 3x_2^{(2)} \right] = 0.64771586224490. \end{aligned}$$

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Section 7.3, Problem 17: The linear system

$$2x_1 - x_2 + x_3 = -1,$$

$$2x_1 + 2x_2 + 2x_3 = 4,$$

$$-x_1 - x_2 + 2x_3 = -5$$
(3)

has the solution $(1,2,-1)^T$.

- a) Show that $\rho(T_j) = \frac{\sqrt{5}}{2} > 1$. c) Show that $\rho(T_q) = \frac{1}{2}$.

Solution:

a) A general $n \times n$ linear system can be written as $A\mathbf{x} = \mathbf{b}$, where

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}.$$

Jacobi method is written in the form $\mathbf{x}^{(k)} = T\mathbf{x}^{(k-1)} + \mathbf{c}$ by splitting A. Let D be the diagonal matrix whose diagonal entries are those of A, -L be the strictly lower-triangular part of A, and -U be the strictly upper-triangular part of A. Hence,

$$A = \begin{bmatrix} a_{11} & 0 & \cdots & 0 \\ 0 & a_{22} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & a_{nn} \end{bmatrix} - \begin{bmatrix} 0 & \cdots & \cdots & 0 \\ -a_{21} & \ddots & & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ -a_{n1} & \cdots & -a_{n,n-1} & 0 \end{bmatrix} - \begin{bmatrix} 0 & -a_{12} & \cdots & -a_{1n} \\ \vdots & \ddots & \ddots & \vdots \\ \vdots & & \ddots & -a_{n-1,n} \\ 0 & \cdots & \cdots & 0 \end{bmatrix}$$
$$= D - L - U.$$

The equation $A\mathbf{x} = \mathbf{b}$, or

$$(D - L - U)\mathbf{x} = \mathbf{b},\tag{4}$$

is then transformed into

$$D\mathbf{x} = (L+U)\mathbf{x} + \mathbf{b}.$$

and, if D^{-1} exists,

$$\mathbf{x} = D^{-1}(L+U)\mathbf{x} + D^{-1}\mathbf{b}.$$

This results in the matrix form of the Jacobi iterative technique:

$$\mathbf{x}^{(k)} = D^{-1}(L+U)\mathbf{x}^{(k-1)} + D^{-1}\mathbf{b}.$$

Introducing $T_j = D^{-1}(L+U)$ and $c_j = D^{-1}\mathbf{b}$ (here, "j" stands for "Jacobi"), the Jacobi method has the form

$$\mathbf{x}^{(k)} = T_i \mathbf{x}^{(k-1)} + \mathbf{c}_i.$$

For system in (3), we have

$$A = \left[\begin{array}{ccc} 2 & -1 & 1 \\ 2 & 2 & 2 \\ -1 & -1 & 2 \end{array} \right], \quad D = \left[\begin{array}{ccc} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{array} \right], \quad L = \left[\begin{array}{ccc} 0 & 0 & 0 \\ -2 & 0 & 0 \\ 1 & 1 & 0 \end{array} \right], \quad U = \left[\begin{array}{ccc} 0 & 1 & -1 \\ 0 & 0 & -2 \\ 0 & 0 & 0 \end{array} \right].$$

The inverse of D is

$$D^{-1} = \left[\begin{array}{ccc} 0.5 & 0 & 0 \\ 0 & 0.5 & 0 \\ 0 & 0 & 0.5 \end{array} \right],$$

and

$$T_j = D^{-1}(L+U) = \begin{bmatrix} 0.5 & 0 & 0 \\ 0 & 0.5 & 0 \\ 0 & 0 & 0.5 \end{bmatrix} \begin{bmatrix} 0 & 1 & -1 \\ -2 & 0 & -2 \\ 1 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0.5 & -0.5 \\ -1 & 0 & -1 \\ 0.5 & 0.5 & 0 \end{bmatrix}.$$

The **spectral radius** $\rho(T_i)$ of matrix T_i is defined by

$$\rho(T_i) = \max |\lambda|$$
, where λ is an eigenvalue of T_i .

Eigenvalues of T_i are

$$\lambda_{1,2} = \pm \frac{\sqrt{5}}{2}i, \quad \lambda_3 = 0.$$

Thus,
$$\rho(T_j) = |\pm \frac{\sqrt{5}}{2}i| = \frac{\sqrt{5}}{2} > 1.$$
 \checkmark

c) Equation (4) can be written as

$$(D-L)\mathbf{x} = U\mathbf{x} + \mathbf{b},$$

which gives the Gauss-Seidel method:

$$(D-L)\mathbf{x}^{(k)} = U\mathbf{x}^{(k-1)} + \mathbf{b}$$

or

$$\mathbf{x}^{(k)} = (D-L)^{-1}U\mathbf{x}^{(k-1)} + (D-L)^{-1}\mathbf{b}.$$

Introducing $T_g = (D-L)^{-1}U$ and $c_g = (D-L)^{-1}\mathbf{b}$ (here, "g" stands for "Gauss-Seidel"), the Gauss-Seidel method has the form

$$\mathbf{x}^{(k)} = T_g \mathbf{x}^{(k-1)} + \mathbf{c}_g.$$

For system in (3), we have

$$D - L = \left[\begin{array}{rrr} 2 & 0 & 0 \\ 2 & 2 & 0 \\ -1 & -1 & 2 \end{array} \right].$$

The inverse of D-L is

$$(D-L)^{-1} = \begin{bmatrix} 0.5 & 0 & 0 \\ -0.5 & 0.5 & 0 \\ 0 & 0.25 & 0.5 \end{bmatrix},$$

and

$$T_g = (D-L)^{-1}U = \begin{bmatrix} 0.5 & 0 & 0 \\ -0.5 & 0.5 & 0 \\ 0 & 0.25 & 0.5 \end{bmatrix} \begin{bmatrix} 0 & 1 & -1 \\ 0 & 0 & -2 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0.5 & -0.5 \\ 0 & -0.5 & -0.5 \\ 0 & 0 & -0.5 \end{bmatrix}.$$

Eigenvalues of T_g are

$$\lambda_{1,2} = -\frac{1}{2}, \quad \lambda_3 = 0.$$

Thus,
$$\rho(T_g) = \max(|\lambda_1|, |\lambda_2|, |\lambda_3|) = \frac{1}{2}$$
.

Section 7.3, Problem 21(b): Consider the following bounds:

$$||\mathbf{x}^{(k)} - \mathbf{x}|| \le ||T||^k ||\mathbf{x}^{(0)} - \mathbf{x}||$$
 (5)

and

$$||\mathbf{x}^{(k)} - \mathbf{x}|| \le \frac{||T||^k}{1 - ||T||} ||\mathbf{x}^{(1)} - \mathbf{x}^{(0)}||,$$
 (6)

where T is an $n \times n$ matrix with ||T|| < 1 and

$$\mathbf{x}^{(\mathbf{k})} = T\mathbf{x}^{(\mathbf{k}-1)} + \mathbf{c}, \quad k = 1, 2, \dots,$$

with $\mathbf{x}^{(0)}$ arbitrary, $\mathbf{c} \in \mathbb{R}^n$, and $\mathbf{x} = T\mathbf{x} + \mathbf{c}$.

Apply the bounds to Exercise 2(c), if possible, using the L_{∞} norm.

Solution: In Section 7.3, Exercise 2(c), we had

$$\begin{array}{rcl} \mathbf{x} & = & (-0.75342, 0.041096, -0.28082, 0.69178), \\ \mathbf{x}^{(0)} & = & (0, 0, 0), \\ \mathbf{x}^{(1)} & = & (-0.5, -0.25, 0, 0.33333), \\ \mathbf{x}^{(2)} & = & (-0.52083, -0.041667, -0.21667, 0.41667). \end{array}$$

Thus,

$$\mathbf{x}^{(2)} - \mathbf{x} = (0.2326, -0.0828, 0.0642, -0.2751),$$

 $\Rightarrow ||\mathbf{x}^{(2)} - \mathbf{x}||_{\infty} = 0.2751,$

and

$$||\mathbf{x}^{(0)} - \mathbf{x}||_{\infty} = 0.75342,$$

 $||\mathbf{x}^{(1)} - \mathbf{x}^{(0)}||_{\infty} = 0.5.$

Also,

$$T = \begin{bmatrix} 0 & -\frac{1}{4} & \frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & 0 & \frac{1}{4} & \frac{1}{4} \\ \frac{1}{5} & \frac{1}{5} & 0 & -\frac{1}{5} \\ -\frac{1}{3} & \frac{1}{3} & -\frac{1}{3} & 0 \end{bmatrix} \Rightarrow ||T||_{\infty} = \max_{1 \le i \le n} \sum_{j=1}^{n} |t_{ij}| = 1.0,$$

$$\Rightarrow ||T||_{\infty}^{2} = 1.0.$$

$$||T||_{\infty}^{2}||\mathbf{x}^{(0)} - \mathbf{x}||_{\infty} = 1.0 \cdot 0.75342 = 0.75342,$$
$$\frac{||T||_{\infty}^{2}}{1 - ||T||_{\infty}}||\mathbf{x}^{(1)} - \mathbf{x}^{(0)}|| = \frac{1.0}{1 - 1} \cdot 0.5 = \infty.$$

Thus, both inequalities

$$||\mathbf{x}^{(2)} - \mathbf{x}||_{\infty} \le ||T||_{\infty}^{2} ||\mathbf{x}^{(0)} - \mathbf{x}||_{\infty}$$

and

$$||\mathbf{x}^{(2)} - \mathbf{x}||_{\infty} \le \frac{||T||_{\infty}^{2}}{1 - ||T||_{\infty}} ||\mathbf{x}^{(1)} - \mathbf{x}^{(0)}||_{\infty}$$

hold. \checkmark

Section 7.3, Problem 22: Show that if A is strictly diagonally dominant, then $||T_j||_{\infty} < 1$.

Solution: The $n \times n$ matrix A is said to be strictly diagonally dominant when

$$|a_{ii}| > \sum_{j=1, j \neq i} |a_{ij}|,$$
 (7)

holds for each i = 1, 2, ..., n. Matrix T_i is defined as

$$T_i = D^{-1}(L+U),$$

where D is the diagonal matrix whose diagonal entries are those of A, -L is the strictly lower-triangular part of A, and -U is the strictly upper-triangular part of A:

$$D = \begin{bmatrix} a_{11} & 0 & \cdots & 0 \\ 0 & a_{22} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & a_{nn} \end{bmatrix},$$

$$L = \begin{bmatrix} 0 & \cdots & \cdots & 0 \\ -a_{21} & \ddots & & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ -a_{n1} & \cdots & -a_{n,n-1} & 0 \end{bmatrix},$$

$$U = \begin{bmatrix} 0 & -a_{12} & \cdots & -a_{1n} \\ \vdots & \ddots & \ddots & \vdots \\ \vdots & & \ddots & -a_{n-1,n} \\ 0 & \cdots & \cdots & 0 \end{bmatrix}.$$

Thus,

$$T_{j} = D^{-1}(L+U) = \begin{bmatrix} \frac{1}{a_{11}} & 0 & \cdots & 0 \\ 0 & \frac{1}{a_{22}} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \frac{1}{a_{nn}} \end{bmatrix} \begin{bmatrix} 0 & -a_{12} & \cdots & -a_{1n} \\ -a_{21} & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & -a_{n-1,n} \\ -a_{n1} & \cdots & -a_{n,n-1} & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & -\frac{a_{12}}{a_{11}} & -\frac{a_{13}}{a_{11}} & \cdots & -\frac{a_{1n}}{a_{11}} \\ -\frac{a_{21}}{a_{22}} & 0 & -\frac{a_{23}}{a_{22}} & \cdots & -\frac{a_{2n}}{a_{22}} \\ \vdots & \ddots & \ddots & \vdots \\ \vdots & & \ddots & \ddots & \vdots \\ -\frac{a_{n1}}{a_{n1}} & -\frac{a_{n2}}{a_{n2}} & \cdots & -\frac{a_{n,n-1}}{a_{n-1,n-1}} \\ 0 \end{bmatrix}$$

Thus,

$$||T_j||_{\infty} = \max_{1 \le i \le n} \sum_{j=1, j \ne i}^n \left| -\frac{a_{ij}}{a_{ii}} \right| = \max_{1 \le i \le n} \sum_{j=1, j \ne i}^n \frac{|a_{ij}|}{|a_{ii}|} = \max_{1 \le i \le n} \left\{ \frac{1}{|a_{ii}|} \sum_{j=1, j \ne i}^n |a_{ij}| \right\}.$$

From (7), we have
$$\frac{1}{|a_{ii}|} \sum_{j=1, j \neq i}^{n} |a_{ij}| < 1$$
 for all i , and hence, $||T_j||_{\infty} < 1$. \checkmark

Section 7.4, Problem 2: Compute the condition numbers of the following matrices relative to $||\cdot||_{\infty}$.

a)
$$\begin{bmatrix} 0.03 & 58.9 \\ 5.31 & -6.10 \end{bmatrix}$$
;

$$\mathbf{c}) \qquad \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{bmatrix}.$$

Solution:

The **condition number** of the nonsingular matrix A relative to a norm $||\cdot||$ is

$$K(A) = ||A|| \cdot ||A^{-1}||.$$

In particular, the condition number of A relative to $||\cdot||_{\infty}$ is

$$K(A) = ||A||_{\infty} \cdot ||A^{-1}||_{\infty},$$

where

$$||A||_{\infty} = \max_{1 \le i \le n} \sum_{i=1}^{n} |a_{ij}|.$$

a) We have

$$A = \left[\begin{array}{cc} 0.03 & 58.9 \\ 5.31 & -6.10 \end{array} \right], \quad A^{-1} = \left[\begin{array}{cc} 0.0195 & 0.1882 \\ 0.0170 & -0.0001 \end{array} \right],$$

and

$$||A||_{\infty} = 58.93,$$

 $||A^{-1}||_{\infty} = 0.2077.$

Thus, the condition number of A relative to $||\cdot||_{\infty}$ is

$$K(A) = ||A||_{\infty} \cdot ||A^{-1}||_{\infty} = 58.93 \cdot 0.2077 = 12.24.$$
 \checkmark

c) We have

$$A = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{bmatrix}, \quad A^{-1} = \begin{bmatrix} 1 & 1 & -2 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{bmatrix},$$

and

$$||A||_{\infty} = 3.0,$$

 $||A^{-1}||_{\infty} = 4.0.$

Thus, the condition number of A relative to $||\cdot||_{\infty}$ is

$$K(A) = ||A||_{\infty} \cdot ||A^{-1}||_{\infty} = 3.0 \cdot 4.0 = 12.0.$$

Section 7.4, Problem 4(a): The following linear system Ax = b:

$$0.03x_1 + 58.9x_2 = 59.2,$$

 $5.31x_1 - 6.10x_2 = 47.0.$

has $\mathbf{x} = (10, 1)^T$ as the actual solution and $\tilde{\mathbf{x}} = (30, 0.990)^T$ as an approximate solution. Using the results of Exercise 2(a), compute

$$||\mathbf{x} - \tilde{\mathbf{x}}||_{\infty}$$
 and $K_{\infty}(A) \frac{||\mathbf{b} - A\tilde{\mathbf{x}}||_{\infty}}{||A||_{\infty}}$.

Solution: We have $\mathbf{x} - \tilde{\mathbf{x}} = (-20, 0.010)$, and thus,

$$||\mathbf{x} - \tilde{\mathbf{x}}||_{\infty} = 20.$$
 \checkmark

Also,

$$\mathbf{b} - A\tilde{\mathbf{x}} = \begin{bmatrix} 59.2 \\ 47.0 \end{bmatrix} - \begin{bmatrix} 0.03 & 58.9 \\ 5.31 & -6.10 \end{bmatrix} \begin{bmatrix} 30 \\ 0.990 \end{bmatrix}$$

$$= \begin{bmatrix} 59.2 \\ 47.0 \end{bmatrix} - \begin{bmatrix} 59.211 \\ 153.261 \end{bmatrix}$$

$$= \begin{bmatrix} -0.0110 \\ -106.261 \end{bmatrix},$$

$$||\mathbf{b} - A\tilde{\mathbf{x}}||_{\infty} = 106.261,$$

$$||A||_{\infty} = \max_{1 \le i \le n} \sum_{j=1}^{n} |a_{ij}| = 58.93.$$

Thus,

$$K_{\infty}(A) \frac{||\mathbf{b} - A\tilde{\mathbf{x}}||_{\infty}}{||A||_{\infty}} = 12.24 \cdot \frac{106.261}{58.93} = 22.07.$$