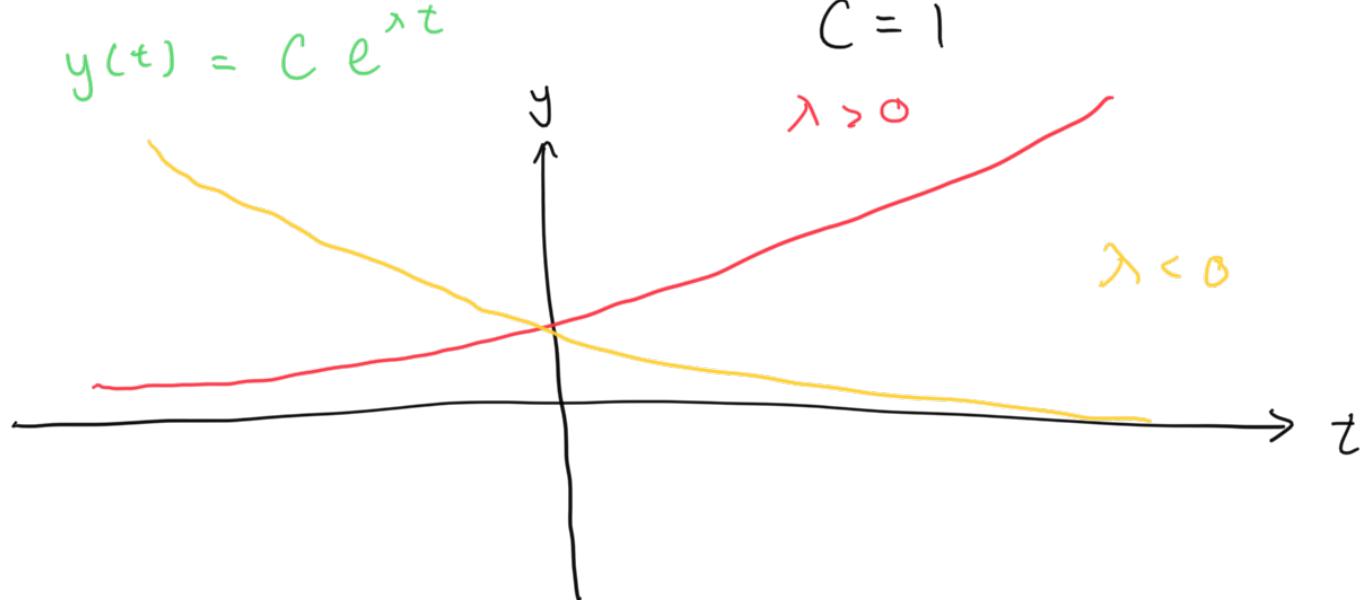


Planar system & the stability of the solutions

$$y' = \lambda y$$

$$y(t) = C e^{\lambda t}$$



$$y' = A y = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} y$$

$$T = a_{11} + a_{22}, \quad D = a_{11}a_{22} - a_{12}a_{21}$$

$$p(\lambda) = \det(A - \lambda I)$$

$$= \det \begin{bmatrix} a_{11} - \lambda & a_{12} \\ a_{21} & a_{22} - \lambda \end{bmatrix}$$

$$= \lambda^2 - (a_{11} + a_{22})\lambda + a_{11}a_{22} - a_{12}a_{21}$$

$$= \lambda^2 - T\lambda + D$$

$$\lambda = \frac{T \pm \sqrt{T^2 - 4D}}{2}$$

$$\begin{array}{cc} \lambda_1 & \lambda_2 \\ v_1 & v_2 \end{array}$$

$$y' = \begin{pmatrix} 1 & 4 \\ 2 & -1 \end{pmatrix} y$$

$$p(\lambda) = \lambda^2 - 9 = (\lambda - 3)(\lambda + 3)$$

$$\begin{pmatrix} 1 & 4 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = -3 \begin{pmatrix} a \\ b \end{pmatrix}$$

$$a + 4b = -3a$$

$$a + b = 0$$

$$v_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 4 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 3 \begin{pmatrix} a \\ b \end{pmatrix}$$

$$a + 4b = 3a$$

$$a = 2b$$

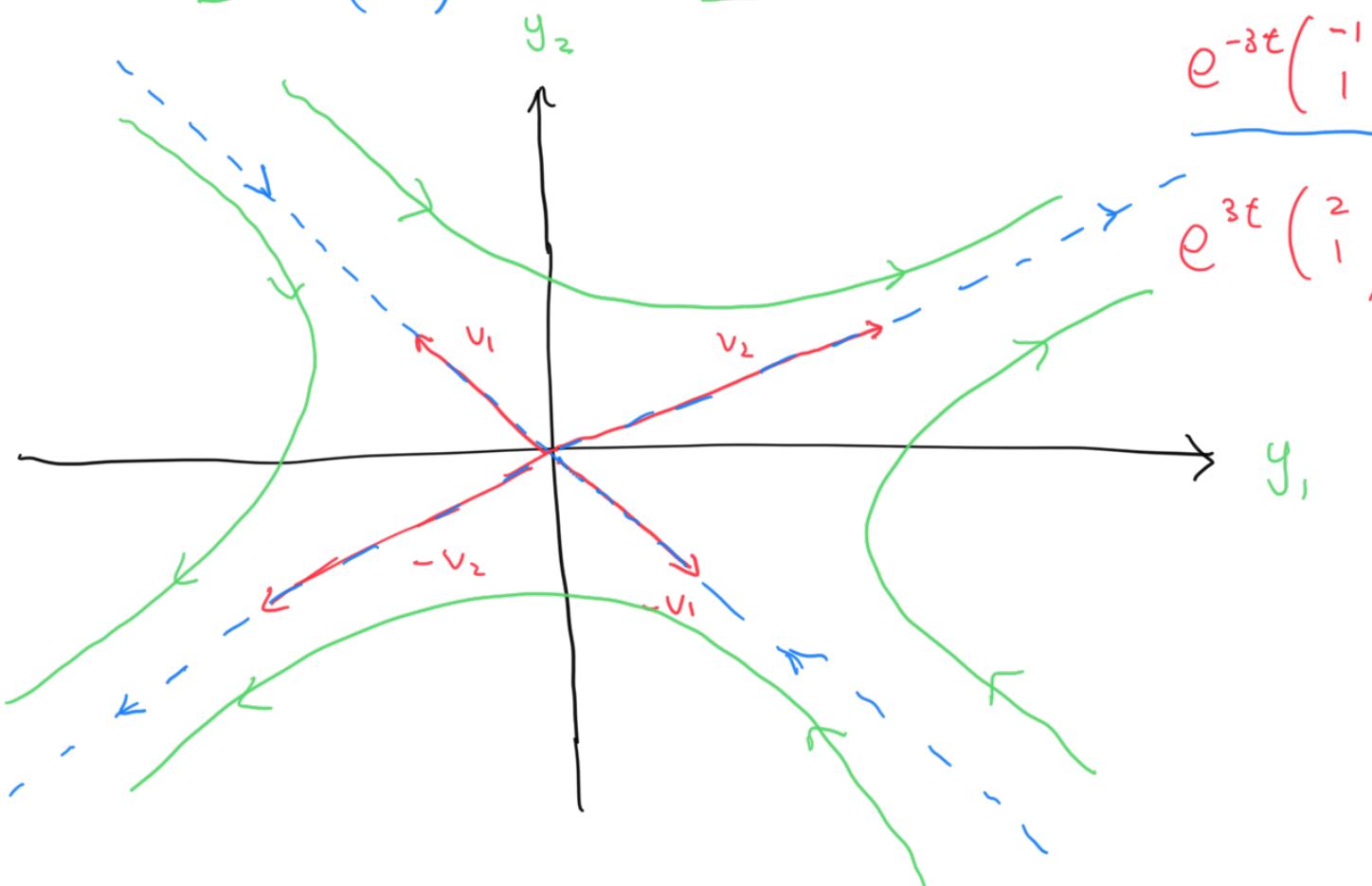
$$v_2 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$y(t) = C_1 \underbrace{e^{-3t} \begin{pmatrix} -1 \\ 1 \end{pmatrix}}_{v_1} + C_2 \underbrace{e^{3t} \begin{pmatrix} 2 \\ 1 \end{pmatrix}}_{v_2}$$

$$y(t) = \begin{pmatrix} y_1(t) \\ y_2(t) \end{pmatrix}$$

$$\underbrace{e^{-3t} \begin{pmatrix} -1 \\ 1 \end{pmatrix}}_{v_1}$$

$$\underbrace{e^{3t} \begin{pmatrix} 2 \\ 1 \end{pmatrix}}_{v_2}$$



$$\lambda_1 < 0 < \lambda_2$$

saddle point

$$y' = \begin{pmatrix} -3 & -1 \\ -1 & -3 \end{pmatrix} y$$

$$p(\lambda) = \lambda^2 + 6\lambda + 8 = (\lambda + 4)(\lambda + 2)$$

$$\left(\begin{array}{cc} -3 & -1 \\ -1 & -3 \end{array} \right) \left(\begin{array}{c} a \\ b \end{array} \right) = -4 \left(\begin{array}{c} a \\ b \end{array} \right) \quad \left| \quad \left(\begin{array}{cc} -3 & -1 \\ -1 & -3 \end{array} \right) \left(\begin{array}{c} a \\ b \end{array} \right) = -2 \left(\begin{array}{c} a \\ b \end{array} \right)$$

$$-3a - b = -4a$$

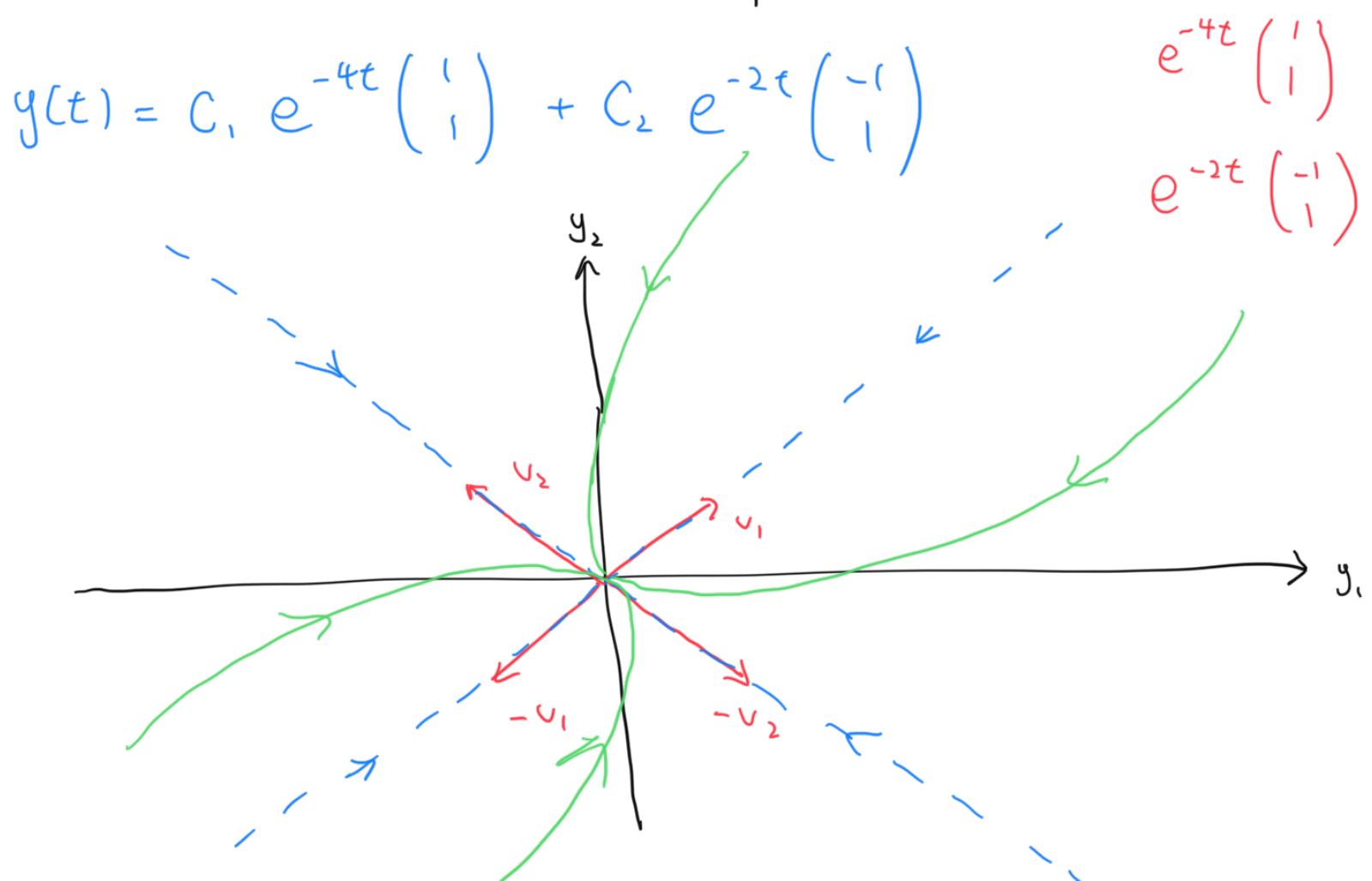
$$a - b = 0$$

$$v_1 = \left(\begin{array}{c} 1 \\ 1 \end{array} \right)$$

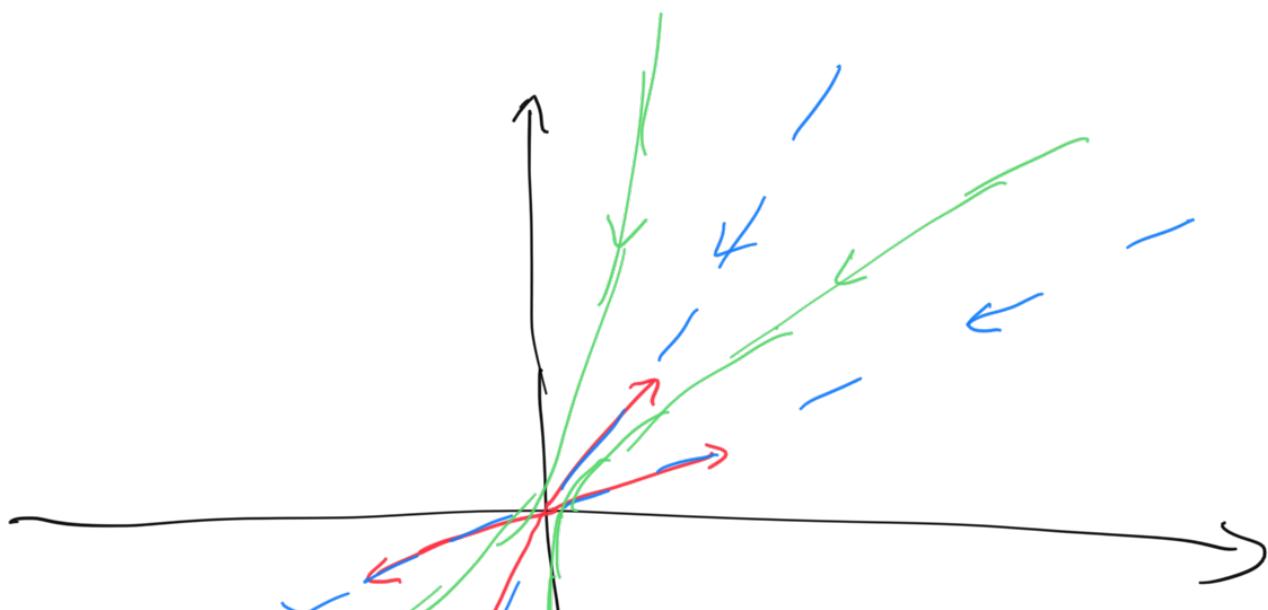
$$-3a - b = -2a$$

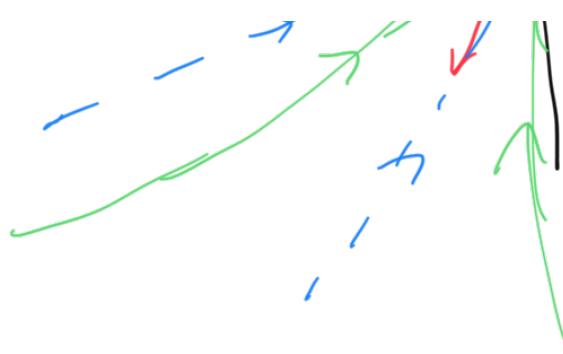
$$a = -b$$

$$v_2 = \left(\begin{array}{c} -1 \\ 1 \end{array} \right)$$



$\lambda_1 < \lambda_2 < 0$ nodal sink





$$y' = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} y$$

$$p(\lambda) = \lambda^2 - 6\lambda + 8 = (\lambda - 2)(\lambda - 4)$$

$$\left(\begin{array}{cc} 3 & 1 \\ 1 & 3 \end{array} \right) \left(\begin{array}{c} a \\ b \end{array} \right) = 2 \left(\begin{array}{c} a \\ b \end{array} \right) \quad \left| \quad \left(\begin{array}{cc} 3 & 1 \\ 1 & 3 \end{array} \right) \left(\begin{array}{c} a \\ b \end{array} \right) = 4 \left(\begin{array}{c} a \\ b \end{array} \right)$$

$$3a + b = 2a$$

$$a + b = 0$$

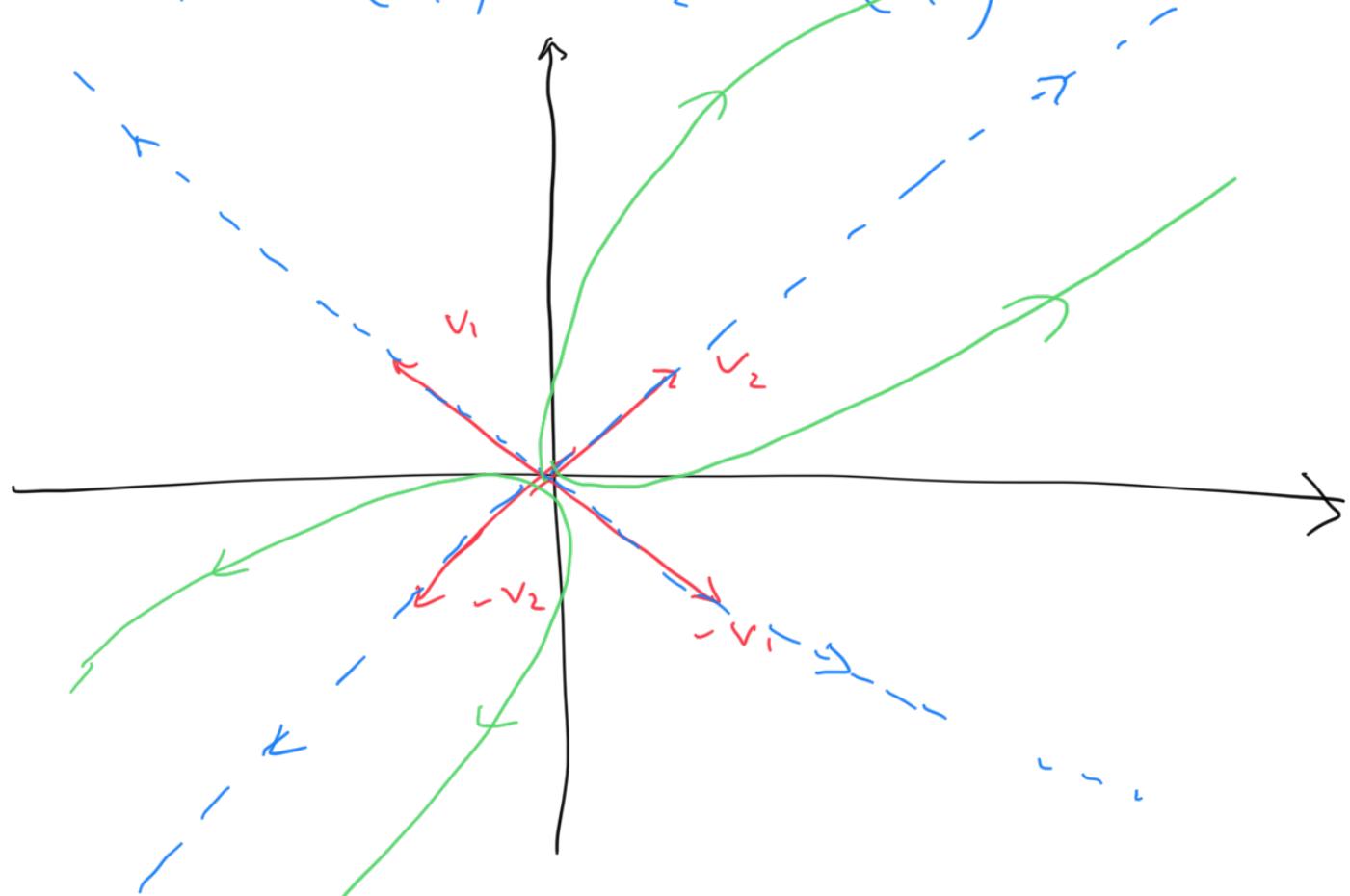
$$v_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$3a + b = 4a$$

$$a = b$$

$$v_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$y(t) = c_1 e^{2t} \begin{pmatrix} -1 \\ 1 \end{pmatrix} + c_2 e^{4t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$



$$0 < \lambda_1 < \lambda_2 \quad \text{nodal} \quad \text{source}$$

$$T^2 - 4D < 0 \quad , \quad T$$

$$\lambda = \alpha + i\beta \quad e^{\alpha t} ((\cos \beta t) v_1 - (\sin \beta t) v_2)$$

$$w = v_1 + i v_2 \quad e^{\alpha t} ((\sin \beta t) v_1 + (\cos \beta t) v_2)$$

$$y' = \begin{pmatrix} 0 & 2 \\ -2 & 0 \end{pmatrix} y$$

$$p(\lambda) = \lambda^2 + 4 = (\lambda - 2i)(\lambda + 2i)$$

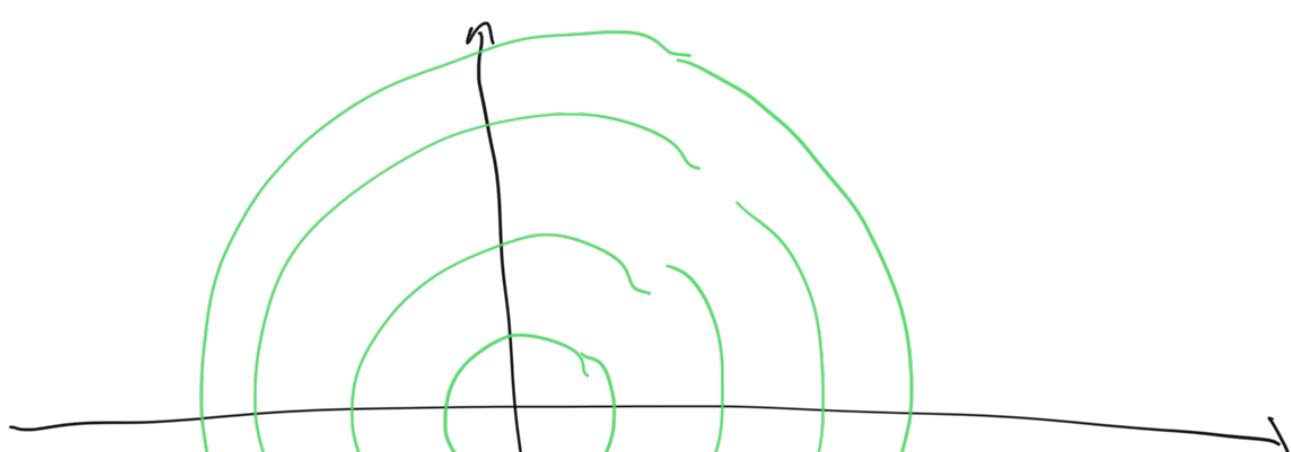
$$\begin{pmatrix} 0 & 2 \\ -2 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 2i \begin{pmatrix} a \\ b \end{pmatrix}$$

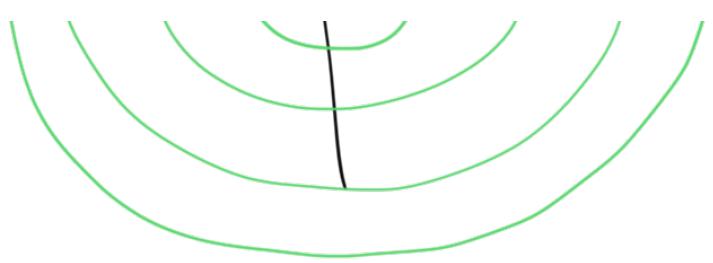
$$2b = 2ia$$

$$w = \begin{pmatrix} 1 \\ i \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + i \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$y(t) = C_1 \left(\cos 2t \begin{pmatrix} 1 \\ 0 \end{pmatrix} - \sin 2t \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right)$$

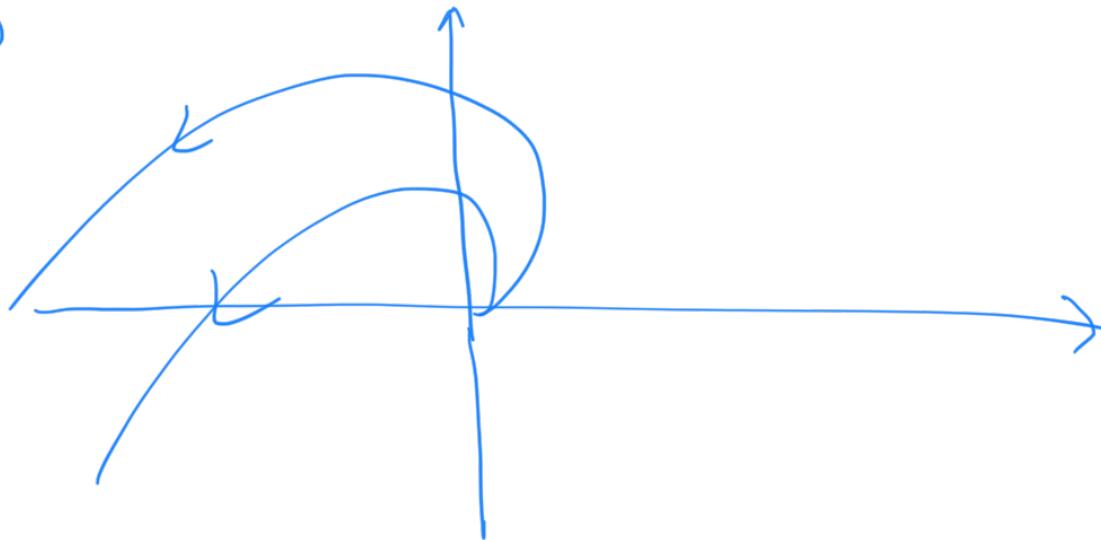
$$+ C_2 \left(\sin 2t \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \cos 2t \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right)$$





center

$T > 0$



$T < 0$

