Selected Solutions to Homework 6

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6.6.6. Let T be a normal operator on a finite-dimensional inner product space. Prove that if T is a projection, then T is also an orthogonal projection.

Solution: We know from previous homework that $\operatorname{im}(T)^{\perp} = \operatorname{ker}(T^*)$. Since T is normal, from 3a) here $\operatorname{ker}(T) = \operatorname{ker}(T^*)$. This says $\operatorname{im}(T)^{\perp} = \operatorname{ker}(T)$ and $\operatorname{im}(T) = \operatorname{ker}(T)^{\perp}$ since V is finite dimensional.

7.1.10 Let T be a linear operator on a finite-dimensional vector space whose characteristic polynomial splits, and let λ be an eigenvalue of T.

- (a) Suppose that γ is a basis for K_{λ} consisting of the union of q disjoint cycles of generalized eigenvectors. Prove that $q \leq \dim(E_{\lambda})$.
- (b) Let β be a Jordan canonical basis for T and suppose that $J = [T]_{\beta}$ has q Jordan blocks with λ in the diagonal positions. Prove that $q \leq \dim(E_{\lambda})$.

Solution:

- (a) Each cycle in γ contains precisely one eigenvector. Therefore, γ contains q eigenvectors. Since these eigenvectors are part of a basis, they're linearly independent. Therefore, we can find at least q linearly independent eigenvectors, which tells us that $q \leq \dim(E_{\lambda})$ since the latter is the maximal number of linearly independent eigenvectors we can find.
- (b) By definition of β , we have $\beta = \beta_1 \cup \ldots \cup \beta_k$ where β_i is a basis of K_{λ_i} that is a union of disjoint cycles. Since Jordan blocks correspond to cycles, the assumption of the problem says that the basis β_{λ} of K_{λ} breaks up into q disjoint cycles, so by the previous part we're done.

2. Let $T: V \to V$ be a normal operator on a finite dimensional inner product space. Show that the minimal polynomial of T is a product of distinct, monic, irreducible factors of degree 1 and 2.

Solution: Pick a basis β of V and let $[T]_{\beta} = A$. First, suppose that V is a complex inner product space. Then we know that A is diagonalizable over \mathbb{C} , so the minimal polynomial of A (which is the minimal polynomial of T) has distinct linear factors. Now suppose that V is a real inner product space, so that in particular, A is a real matrix. First, we show that the minimal polynomial of A (viewed over \mathbb{R}) is the same as the minimal polynomial of A (viewed over \mathbb{C}).

Let's denote the potentially different minimal polynomials by $m_{A,\mathbb{R}}$ and $m_{A,\mathbb{C}}$ respectively. Then since $m_{A,\mathbb{R}}$ has real coefficients (which are in particular, complex numbers) we have $m_{A,\mathbb{C}} \mid m_{A,\mathbb{R}}$. Since both polynomials are *monic*, they're equal if they have the same degree. So suppose that $\deg(m_{A,\mathbb{C}}) < \deg(m_{A,\mathbb{R}})$. Then as A is a matrix with real entries, it's quite easy to see that $\overline{m_{A,\mathbb{C}}}(A) = 0$, where $\overline{m_{A,\mathbb{C}}}$ is the polynomial with conjugate coefficients to $m_{A,\mathbb{C}}$. Then $m_{A,\mathbb{C}} + \overline{m_{A,\mathbb{C}}}$ is a polynomial with real coefficients of that kills A, but $\deg(m_{A,\mathbb{C}} + \overline{m_{A,\mathbb{C}}}) < \deg(m_{A,\mathbb{R}})$, which is a contradiction to the definition of $m_{A,\mathbb{R}}$. Therefore, $m_{A,\mathbb{C}} = m_{A,\mathbb{R}}$ so it makes sense to speak of "the" minimal polynomial.

To finish up the problem, we now know that viewing A as a complex matrix, the minimal polynomial of A factors into a product of distinct linear factors in \mathbb{C} . Since the minimal polynomial is real, the complex roots come in conjugate pairs. Pairing them up yields an irreducible real quadratic factor. Doing this for all such factors over \mathbb{C} tells us that m_A factors into a product of distinct linear factors (corresponding to real roots) and irreducible quadratic factors (corresponding to a pair of conjugate conplex roots) as desired.

3. Let $g : \mathbb{R}^n \to \mathbb{R}^n$ be a rigid motion, and let $f : \mathbb{R}^n \to \mathbb{R}^n$ be a translation. Show that $g^{-1} \circ f \circ g$ is also a translation.

Solution: Since g is a rigid motion, we may write $g = h \circ T$ for some orthogonal operator T and translation h. Then $g^{-1} = T^{-1} \circ h^{-1}$, so $g^{-1} \circ f \circ g = T^{-1} \circ h^{-1} \circ f \circ h \circ T$. Note that $h^{-1} \circ f \circ h = f$, so $g^{-1} \circ f \circ g = T^{-1} \circ f \circ T$. For $v \in \mathbb{R}^n$, suppose that f(v) = v + x for fixed x. Then $(T^{-1} \circ f \circ T)(v) = v + T^{-1}(x)$, so that $g^{-1} \circ f \circ g$ is a translation by $T^{-1}(x)$ as desired.

4. Determine the number of all possible Jordan canonical forms (up to ordering) of linear transformations with $c_T = (x+3)^8(x-2)^5(x-4)^2$ and $m_T(x) = (x+3)^5(x-2)^2(x-4)^2$.

Solution: We know that the algebraic multiplicity of an eigenvalue is equal to the sum of the sizes of the Jordan blocks for λ_i , and that the multiplicity of λ_i in the minimal polynomial is the size of the largest Jordan block that appears in the Jordan canonical form of T. Combining these two facts, we see the following:

- $\lambda = -3$: We have a 5 × 5 block and the sum of sizes of blocks must be 8. The possibilities for the sizes of Jordan blocks (listed as tuples) are (5, 1, 1, 1), (5, 2, 1), or (5, 3).
 - $\lambda = 2$: We have a 2 × 2 block and the sum of sizes of blocks must be 5. The possibilities for the sizes of Jordan blocks are (2, 2, 1), (2, 1, 1, 1).
 - $\lambda = 4$: We have a 2 × 2 block and this is the *only* Jordan block.

This gives a total of 6 different Jordan forms (up to permutation of the factors).