## Solutions to the Exercises of Section 4.3.

4.3.1. The parameter space is  $\Theta = \{(\theta, j) : 0 \le \theta \le 1, j = 1, ..., n\}$ , the action space is  $\mathcal{A} = [0, 1]$ , and the loss function is  $L((\theta, j), a) = (\theta - a)^2$ . Under  $(\theta, j)$ , the observations,  $X_1, \ldots, X_n$  are independent,  $X_j$  is  $\mathcal{B}(1, \theta)$  and  $X_i$  is  $\mathcal{B}(1, 1/2)$  for  $i \ne j$ .

The problem is invariant under the permutations of the observations,  $g_{\pi}(x_1, \ldots, x_n) = (x_{\pi(1)}, \ldots, x_{\pi(n)})$ for permutations  $\pi$  of  $(1, \ldots, n)$ , with  $\bar{g}_{\pi}(\theta, j) = (\theta, \pi^{-1}(j))$  and  $\tilde{g}_{\pi}(a) = a$ . It is also invariant under the map  $g_2(x_1, \ldots, x_n) = (1 - x_1, \ldots, 1 - x_n)$  with  $\bar{g}_2(\theta, j) = (1 - \theta, j)$  and  $\tilde{g}_2(a) = 1 - a$ . We may restrict attention to nonrandomized invariant rules. A rule *d* is invariant under  $g_{\pi}$  if  $d(g_{\pi}(x_1, \ldots, x_n)) =$  $\tilde{g}_{\pi}d(x_1, \ldots, x_n) = d(x_1, \ldots, x_n)$ . This means that *d* depends on the  $x_i$  only through the sum  $S = X_1 + \cdots + X_n$ . We henceforth write invariant rules as d(s). Such a rule is invariant under  $g_2$  if d(s) = 1 - d(n - s). In particular, if *n* is even then d(n/2) = 1/2.

The distribution of S under  $(\theta, j)$  is independent of j and has mass function,

$$P_{\theta}(S=s) = \begin{cases} \left(\frac{1}{2}\right)^{n-1}(1-\theta) & \text{for } s = 0\\ \binom{n-1}{s-1}\left(\frac{1}{2}\right)^{n-1}\theta + \binom{n-1}{s}\left(\frac{1}{2}\right)^{n-1}(1-\theta) & \text{for } s = 1, \dots, n-1\\ \left(\frac{1}{2}\right)^{n-1}\theta & \text{for } s = n. \end{cases}$$

Note that  $P_{\theta}(S = s)$  is linear in  $\theta$ . The risk function of an invariant rule is  $R((\theta, j), d) = E_{\theta}(\theta - d(S))^2 = \theta^2 - 2\theta E_{\theta} d(S) + E_{\theta} d(S)^2$ . Now note that  $E_{\theta} d(S)$  and  $E_{\theta} d(S)^2$  are linear in  $\theta$ . This implies that  $R((\theta, j), d)$  is quadratic in  $\theta$ . And since d is invariant under  $g_2$ ,  $R((\theta, j), d)$  is symmetric in  $\theta$  about 1/2. Therefore the maximum of  $R((\theta, j), d)$  over  $\theta$  occurs at  $\theta = 1/2$  or at  $\theta = 0$  and  $\theta = 1$ .

Below, we show that  $d_0(s) = s/n$  minimizes R((0, j), d) = R((1, j), d) and then we show that this minimum value is greater than  $R((1/2, j), d_0)$ . First note that R((0, j), d) = (1/2)R((0, j), d) + (1/2)R((1, j), d):

$$R((0,j),d) = \frac{1}{2} \sum_{s=0}^{n-1} \binom{n-1}{s} (\frac{1}{2})^{n-1} d(s)^2 + \frac{1}{2} \sum_{s=1}^n \binom{n-1}{s-1} (\frac{1}{2})^{n-1} (1-d(s))^2$$

We wish to find d to minimize this subject to the restriction that d be invariant, i.e. d(s) = 1 - d(n-s) for s = 0, ..., n. The overall minimum without regard to the restriction is easily found by setting the derivatives of R((0, j), d) with respect to the d(s) separately to zero. We find d(s) = s/n. This satisfies the restriction and so gives the minimum value subject to the restriction.

To show that  $R((0, j), d_0) = E_0(S/n)^2$  is greater than  $R((1/2, j), d_0) = E_{1/2}(S/n - 1/2)^2$ , we evaluate both. When  $\theta = 1/2$ , S has a binomial distribution sample size n and probability of success 1/2, so  $R((1/2, j), d_0) = \operatorname{Var}_{1/2}(S/n) = 1/(4n)$ . When  $\theta = 0$ , S has a binomial distribution sample size n - 1 and success probability 1/2, so

$$R((0,j),d_0) = \operatorname{Var}_0(S/n) + (\operatorname{E}_0(S/n))^2 = \frac{n-1}{4n^2} + \frac{(n-1)^2}{4n^2} = \frac{n-1}{4n}$$

This is greater than 1/4n for all n > 1.

4.3.2. From Lemma 2.11.1, the least favorable distribution must give all its weight to points p for which R(p, 1/4) = v = 1/4. As in Figure 4.1, this occurs only at the three points 0, 1/2 and 1. From Theorem 3(c), we may restrict attention to invariant prior distributions, those that distribute weight symmetrically about 1/2. Thus a least favorable distribution  $\tau$  must be of the form  $\tau(0) = \tau(1) = z$  and  $\tau(1/2) = 1 - 2z$  for some  $0 \le z \le 1/2$ . The Bayes risk of such a prior is

$$r(\tau, x) = z[R(0, x) + R(1, x)] + (1 - 2z)R(1/2, x) = z2x + (1 - 2z)|1 - 2x|.$$

Since this is increasing in x for x > 1/2 we may assume  $x \le 1/2$ , and write  $r(\tau, x) = z2x + (1-2z)(1-2x) = (1/2) - z + x(1-4z)$ . If z = 1/4, this is constant in x with value 1/4. Since 1/4 is the minimax value,  $\tau$  is least favorable.

4.3.3. From Theorem 3, we may search among the invariant priors for a least favorable  $\tau_0$ . If a prior is invariant under  $\bar{g}_1$ , then for all  $\theta$  it must assign equal weight to  $(\theta, 1)$  and  $(\theta, 2)$ . If it is invariant under

 $\bar{g}_2$ , then for i = 1, 2 and all  $\theta$  it must assign equal weight to  $(\theta, i)$  and  $(1 - \theta, i)$ . However, the risk of a nonrandomized invariant rule, z, was found to be  $R((\theta, i), z) = 2z\theta^2 - 2z\theta + z^2/2 + 1/8$  and to be maximized at  $\theta = 0$  and  $\theta = 1$ . Therefore the invariant prior,  $\tau_0$ , that gives mass 1/4 to each of (0, 1), (0, 2), (1, 1), and (1, 2), is least favorable: Its Bayes risk is the average of  $R((\theta, i), z)$  over these four points and so is  $r(\tau_0, z) = z^2/2 + 1/8$ , whose minimum over z is 1/8, the minimax value.

4.3.4. From Exercise 4.2.7(b), we know that a behavioral invariant rule chooses an action at random independent of the observations. For any such distribution,  $\delta$ , we may find, for a given  $\epsilon > 0$ , a number  $\Delta$  such that  $\delta$  assigns  $1 - \epsilon$  of its mass to the interval  $(0, \Delta/2)$ . Then,  $R((\Delta, \Sigma), \delta) \ge 1 - \epsilon$ . This shows that  $\sup_{\theta} R(\theta, \delta) = 1$ . Yet, if  $d(\mathbf{X}, \mathbf{Y}) = (Y_1/X_1)^2$  (note the correction of the text), then

$$R(\theta, d) = 1 - P_{\Delta, \Sigma} \{ |\Delta - (Y_1/X_1)^2| \le \Delta/2 \} = 1 - P_{1, \Sigma} \{ |1 - (Y_1/X_1)^2| \le 1/2 \}.$$

This is independent of  $\Sigma$ , and so is a constant less than one.

4.3.5. (a) If X is  $\mathcal{B}(n,\theta)$  (the binomial distribution), then n-X is  $\mathcal{B}(n,1-\theta)$ , so  $\bar{g}\theta = 1-\theta$ . Moreover, if  $\tilde{g}a = 1-a$ , then  $L(\bar{\theta},\tilde{a}) = (1-(1-\theta))(1-a) + (1-\theta)(1-(1-a)) = L(\theta,a)$ . So the problem is invariant.

(b) A nonrandomized decision rule d is invariant if  $d(g(x)) = \tilde{g}d(x)$ , that is, if d(n-x) = 1-d(x) for all x = 0, 1, ..., n. So if d(x) is specified for x < n/2, then it is determined for  $x \ge n/2$  by d(n-x) = 1-d(x), which implies, if n is even, that d(n/2) = 1/2).

(c) We may compute the risk function for an invariant rule d, using d(n-x) = d(x) to reduce the dependence of the risk to d(x) for x < n/2 as follows.

$$\begin{aligned} R(\theta, d) &= \sum_{x=0}^{n} \binom{n}{x} \theta^{x} (1-\theta)^{n-x} [(1-\theta)d(x) + \theta(1-d(x))] \\ &= \sum_{x < n/2} \left\{ \binom{n}{x} \theta^{x} (1-\theta)^{n-x} [(1-\theta)d(x) + \theta(1-d(x))] \right. \\ &+ \binom{n}{n-x} \theta^{n-x} (1-\theta)^{x} [(1-\theta)(1-d(x)) + \theta d(x)] \right\} + (\text{possible term with } x = n/2) \\ &= \sum_{x < n/2} \binom{n}{x} (1-2\theta)d(x) [\theta^{x} (1-\theta)^{n-x} - \theta^{n-x} (1-\theta)^{x}] + (\text{terms not involving } d(x)). \end{aligned}$$

The coefficients of d(x) are  $(1 - 2\theta)[1 - (\theta/(1 - \theta)^{n-2x}] \ge 0$  for all  $\theta \in [0, 1]$  when x < n/2. Therefore, the risk is minimized by choosing d(x) = 0 for x < n/2, and hence d(x) = 1 for x > n/2 (and, if n is even, d(n/2) = 1/2. This is the best invariant rule.

By Exercise 2.11.15, the rule  $d(x) \equiv 1/2$  is minimax. Since this rule is invariant, the best invariant rule is also minimax. But the best invariant rule has much smaller risk function.

4.3.6. Let  $\tau_0$  be invariant  $(\bar{g}\tau_0 = \tau_0 \text{ for all } g \in \mathcal{G})$  and let  $\delta$  be Bayes with respect to  $\tau_0$   $(r(\tau_0, \delta) \leq r(\tau_0, \delta')$  for all  $\delta'$ ). Define

$$\delta_0 = \frac{1}{N} \sum_{g \in \mathcal{G}} \delta^g$$

where N is the number of elements in  $\mathcal{G}$ . Then  $\delta_0$  is invariant (in fact, it is the same as  $\delta^I$  in the proof of Theorem 1). We will show that  $\delta_0$  is also Bayes with respect to  $\tau_0$ .

$$\begin{aligned} r(\tau_0, \delta_0) &= \frac{1}{N} \sum_{g \in \mathcal{G}} r(\tau_0, \delta^g) \\ &= \frac{1}{N} \sum_{g \in \mathcal{G}} r(\bar{g}\tau_0, \delta) \qquad \text{as in Theorem 3(a)} \\ &= \frac{1}{N} \sum_{g \in \mathcal{G}} r(\tau_0, \delta) \qquad \text{since } \delta_0 \text{ invariant} \\ &= r(\tau_0, \delta). \end{aligned}$$

Thus  $\delta_0$  has the same Bayes risk as  $\delta$  as so is also Bayes with respect to  $\tau_0$ .

4.3.7. Let  $\tau$  be least favorable  $(\inf_{\delta} r(\tau, \delta) \ge \inf_{\delta} r(\tau', \delta)$  for all  $\tau'$ ). Define  $\tau_0 = (1/N) \sum_g \bar{g}\tau$  as in the proof of Theorem 3(a). Then

$$\inf_{\delta} r(\tau_0, \delta) = \inf_{\delta} \frac{1}{N} \sum_{g \in \mathcal{G}} r(\bar{g}\tau, \delta)$$
$$= \inf_{\delta} \frac{1}{N} \sum_{g \in \mathcal{G}} r(\tau, \delta^g)$$
$$\geq \frac{1}{N} \sum_{g \in \mathcal{G}} \inf_{\delta} r(\tau, \delta^g)$$
$$= \frac{1}{N} \sum_{g \in \mathcal{G}} \inf_{\delta} r(\tau, \delta)$$
$$= \inf_{\delta} r(\tau, \delta).$$

Thus,  $\tau_0$  is also least favorable.