

The condition number of a
randomly perturbed matrix

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Terence Tao (UCLA)

Van Vu (Rutgers)

Well-conditioned matrices

Suppose one wants to solve the matrix equation $Mx = b$, where M is an $n \times n$ matrix and the vector b is given.

In theory, this problem is solvable quickly (e.g. by Gaussian elimination) whenever M is non-singular.

In practice, computers can only represent a finite subset of the real numbers, and so one must take into account roundoff error. The effect of this error is controlled by the **condition number**

$$\kappa(M) := \|M\| \|M^{-1}\|$$

where $\|\cdot\|$ is the spectral norm. (We adopt the convention $\kappa(M) := \infty$ when M is singular.)

Let $\varepsilon_{\text{machine}}$ which is half of the distance from 1 to the nearest represented number in one's machine (a typical value is 10^{-30}). Then we have the following fundamental result in numerical linear algebra:

Theorem. If \tilde{x} is the **numerical** solution to $Mx = b$, then

$$\frac{\|\tilde{x} - x\|}{\|x\|} = O(\kappa(M)\varepsilon_{\text{machine}}).$$

Thus upper bounds on the condition number implies numerical stability in linear algebra. (It also affects the running time of numerical linear algebra algorithms.)

Definition. A matrix M is **polynomially well-conditioned** if $\kappa(M) = O(n^{O(1)})$.

Suppose M is **polynomial size** (thus each entry of M is $O(n^{O(1)})$). Then we clearly have $\|M\| = O(n^{O(1)})$. So, being polynomially well-conditioned is usually equivalent to the bound

$$\|M^{-1}\| = O(n^{O(1)}),$$

or equivalently, a lower bound

$$\sigma_n \gg n^{-O(1)}$$

on the least singular value of M .

In **theory**, ill-conditioned matrices exist:

Theorem. (Alon-Vu, 1996) There exists an invertible matrix M with coefficients ± 1 with $\|M^{-1}\| \gg n^{(\frac{1}{2}+o(1))n}$. In particular, $\kappa(M) \gg n^{(\frac{1}{2}+o(1))n}$.

But **in practice**, they only seem to arise very rarely.

In fact, linear algebraic algorithms (e.g. the **simplex method**) frequently run faster (and gives higher accuracy) than the worst case analysis predicts.

Why should this be the case?

The positive effect of noise

[Spielman](#) and [Teng](#) (2002) proposed the following general explanation:

(P) Let M be an arbitrary $n \times n$ matrix of polynomial size and N_n a non-trivial random $n \times n$ matrix. Then with high probability $M + N_n$ is polynomially well conditioned.

Thus, the inherent measurement or roundoff error in the matrix M itself should cause one to avoid the highly ill-conditioned matrices.

The crucial point here is that M itself may have a large condition number, or even be singular (e.g. $M = 0$).

Continuous and discrete noise

[Demmel](#) (1988) established (P) when $M = 0$ and N_n is a Gaussian random matrix. [Spielman](#) and [Terng](#) (2002) established (P) for arbitrary M of polynomial size and Gaussian random M_n .

In applications to numerical linear algebra, it is more realistic to consider **discrete** models for the random matrix N_n . In particular we have the [Bernoulli random matrix model](#) in which each entry of N_n is ± 1 with independent uniform probability.

With [Van Vu](#), we were able to establish (P) for arbitrary M of polynomial size and for Bernoulli random M_n . More precisely:

Theorem. (T.-Vu, 2007) Let M be polynomial size with integer coefficients, let N_n be a random Bernoulli matrix, and let $A > 0$. Then we have

$$\mathbf{P}(\|(M + N_n)^{-1}\| \geq n^B) \ll n^{-A}$$

if B is sufficiently large depending on A (and on the polynomial size of M).

In particular, by making B a bit bigger, we have

$\kappa(M + N_n) = O(n^B)$ with probability $1 - O(n^{-A})$.

For Gaussian noise, the above theorem was proven by [Spielman](#) and [Terng](#) with $B = A - 1/2$.

The theorem generalises to some other discrete models, where each coordinate a_{jk} of N_n is an independent integer-valued random variable of polynomial size. One needs a large fraction of these random variables to be non-degenerate, e.g. the a_{jk} are symmetric and $\mathbb{P}(a_{jk} = +1) \geq \varepsilon$ for all but $n^{0.01}$ of the coordinates a_{jk} (thus N_n is allowed to have some “frozen” entries). There are more general versions of these results but they get a bit technical to state. One can also allow M to have complex entries instead of integer (this is a work in progress; some results in this direction were obtained recently by Pan and Zhou).

Some ingredients of the proof

Let $M_n := M + N_n$ be the noisy matrix. The goal is to show that $\|M_n^{-1}\| \ll n^B$ with probability $1 - O(n^{-A})$, for some sufficiently large B . Thus we would like to upper bound the

$$\mathbf{P}(\|M_n v\| \ll n^{-B} \text{ for some bounded vector } v)$$

by $O(n^{-A})$.

There are infinitely many unit vectors v , but one can use rounding and only have to deal with those v whose coefficients are a multiple of n^{-B-2} (say).

Some vectors v will be **singular** (most of the coordinates are rather small). These can be easily dealt with by standard concentration-of-measure, union bound, and ε -net arguments. (This idea was borrowed from [Litvak-Pajor-Rudelson-Vershynin \(2005\)](#).)

Some vectors v will be **poor**, in the sense that the rows of M_n have only a low probability (e.g. at most n^{-A-4}) of being close to orthogonal to v . These can be dealt with by a conditioning argument of [Komlós](#) (1960s), fixing $n - 1$ of the rows and looking at the remaining row (which is chosen carefully).

The most difficult case to handle is when v is **rich** (so the rows of M_n are often close to orthogonal to v) and **non-singular**.

Inverse Littlewood-Offord theory

To handle this case, we need to understand what vectors v are rich. In the model case when $M = 0$ and N_n is Bernoulli, this question is equivalent to asking for which numbers v_1, \dots, v_n and a is the concentration probability

$$\mathbb{P}(\pm v_1 \pm v_2 \dots \pm v_n = a)$$

large, where the \pm are n iid Bernoulli signs. This is the [inverse Littlewood-Offord problem](#). (The [forward Littlewood-Offord problem](#) specifies v_1, \dots, v_n and a and asks to bound the concentration probability.)

If the numbers v_1, \dots, v_n obey many arithmetic relations (e.g. if they are all equal), then the concentration probability tends to be large. But if the v_1, \dots, v_n are arithmetically “independent” then the concentration probability tends to be low.

There are [inverse Littlewood-Offord theorems](#) which quantify this relationship; roughly speaking, they assert that the concentration probability is large if and only if the v_1, \dots, v_n are mostly concentrated in an [arithmetic progression](#), or a [generalised arithmetic progression](#). These results are inspired by techniques from [additive combinatorics](#), in particular using Fourier analysis and geometry of numbers.

Discretisation of progressions

A key technical lemma is that a generalised arithmetic progression can be “rounded off” to another arithmetic progression, whose elements are well separated from each other. For instance, consider the two-dimensional generalised arithmetic progression

$$P = \{4a + (3 + 10^{-10})b : -10^{-3} \leq a, b \leq 10^3\}.$$

This progression contains some very small spacings - as small as 10^{-10} . But one can round this progression off to a one-dimensional arithmetic progression

$$Q = \{n : -7 \times 10^{-3} \leq n \leq 7 \times 10^{-3}\}$$

in the sense that every element of the former is within $O(10^{-7})$ of an element of the latter.

The significance of this rounding operation is that it can convert **approximate** relations in P to **exact** relations in Q . For instance, if $x, y, z \in P$ are such that $x + y = z + O(10^{-1})$, and $x', y', z' \in Q$ are their rounded counterparts, then $x' + y'$ is **exactly** equal to z' .

In practice, this allows us to round off a statement such as “ Mv is small” to the statement “ Mv' is zero”. Ultimately, this reduces the task of controlling condition numbers to the simpler task of controlling the probability that M is **invertible**. There is some substantial technology (dating back to [Kahn, Komlos, and Szemerédi \(1995\)](#)) to deal with this.