

Lecture 8.

(After the talk of S. Reed on "Knot quandles").

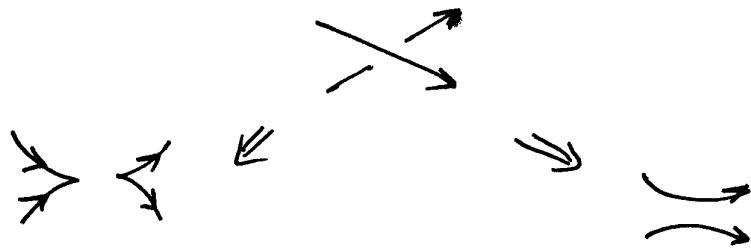
An oriented state model for $V_k(t)$.

Recall: $V_k(t) = (-t^{3/4})^{w(K)} \cdot \langle K \rangle (t^{-y_4})$.

Splicings of unoriented diagrams:



Splicings of oriented diagrams:



{
not in the category
of link diagrams
(because of the kinks)

→ - time.

↗ - represents an interaction (a pass-by)

↗ ↖ - creation and annihilation

In order to get topological invariance, need to have rules on cancellation of creation with annihilation:

[1] ①.

2/ In particular,

$$\begin{array}{c} \uparrow \\ \downarrow \\ \bullet \end{array} = \begin{array}{c} \uparrow \end{array}$$
$$\begin{array}{c} \uparrow \\ \curvearrowleft \\ \curvearrowright \end{array} = \begin{array}{c} \uparrow \end{array}$$

$$\begin{array}{c} \circlearrowleft \\ \circlearrowright \end{array} = \begin{array}{c} \circlearrowright \end{array} = \begin{array}{c} \circlearrowright \end{array}$$

② Channel property:

$$\begin{array}{c} \nearrow \\ \searrow \end{array} = \begin{array}{c} \nearrow \\ \downarrow \end{array} \begin{array}{c} \uparrow \\ \downarrow \end{array}$$

③ Cross-channel property:

$$\begin{array}{c} \nearrow \\ \searrow \\ \nwarrow \end{array} = \begin{array}{c} \nearrow \\ \searrow \end{array} \begin{array}{c} \uparrow \\ \downarrow \end{array}$$

④ Triangle invariance:

$$\begin{array}{c} \nearrow \\ \searrow \\ 1 \quad 2 \quad 3 \end{array} = \begin{array}{c} \nearrow \\ \searrow \\ 1 \quad 2 \quad 3 \end{array}; \quad \begin{array}{c} \nearrow \\ \searrow \\ 1 \quad 2 \quad 3 \end{array} \approx \begin{array}{c} \nearrow \\ \searrow \\ 1 \quad 2 \quad 3 \end{array}$$

Analogously to the bracket, let

$$V_{\nearrow \searrow} = A \cdot V_{\nearrow \downarrow} + B \cdot V_{\searrow \downarrow \nearrow}$$

$$V_{\searrow \nearrow} = A' \cdot V_{\nearrow \downarrow} + B' \cdot V_{\searrow \downarrow \nearrow}$$

A, B, A', B' are weights to be determined from properties ②-④ above.

Assume also that $\bar{V}_{(K \cup \emptyset)} = \delta \cdot \bar{V}_k$, where δ is a parameter.

3/



Using ② - ④ to set conditions on A, A', B, B' :

② Unitarity (channeling)

$$\begin{aligned} V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) &= A \cdot V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) + B \cdot V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) = \\ &= A \cdot \left(A' V_{\text{2G}} + B' V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) \right) + \\ &\quad + B \cdot \left(A' \cdot V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) + B' \cdot V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) \right) \end{aligned}$$

Thus,

$$V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) = AA' \cdot V_{\text{2G}} + (AB' + BB' \delta + BA') \cdot V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right)$$

Unitarity requires:

$$AA' = 1$$

$$\delta = - \left(\frac{A}{B} + \frac{A'}{B'} \right)$$

③ Similarly, cross-unitarity requires

$$BB' = 1$$

$$\delta = - \left(\frac{B'}{A'} + \frac{B}{A} \right)$$

4 Combining the two, we get:

$$A' = \frac{1}{A}, \quad B' = \frac{1}{B}$$

$$\delta = -\left(\frac{A}{B} + \frac{B}{A}\right)$$

④. Annihilation and crossing:

$$V \begin{array}{c} \nearrow \\ \searrow \end{array} = A' \cdot V \begin{array}{c} \nearrow \\ \searrow \end{array} + B' \cdot V \begin{array}{c} \nearrow \\ \searrow \end{array} =$$

$$= A' \cdot \left(A' \cdot V \begin{array}{c} \nearrow \\ \searrow \end{array} + B' \cdot V \begin{array}{c} \nearrow \\ \searrow \end{array} \right) +$$

$$+ B' \cdot \left(A' \cdot V \begin{array}{c} \nearrow \\ \searrow \end{array} + B' \cdot V \begin{array}{c} \nearrow \\ \searrow \end{array} \right) =$$

$$= (A')^2 + (B')^2 + \delta_{A'B'} V \begin{array}{c} \nearrow \\ \searrow \end{array} + A' \cdot B' \cdot V \begin{array}{c} \nearrow \\ \searrow \end{array}$$

$$V \begin{array}{c} \nearrow \\ \searrow \end{array} = A' \cdot B' \cdot V \begin{array}{c} \nearrow \\ \searrow \end{array} = \frac{1}{AB} V \begin{array}{c} \nearrow \\ \searrow \end{array}$$

$$V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) = \frac{1}{AB} V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right)$$

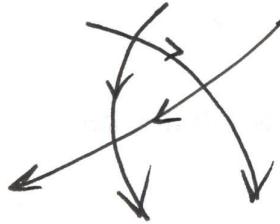
Similarly, can get relations for other triangle moves
(such as $\begin{array}{c} \nearrow \\ \searrow \end{array} \rightarrow \overrightarrow{\nearrow \searrow}$, etc.)

Substituting them, verify

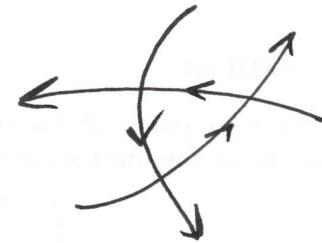
$$V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) = V \left(\begin{array}{c} \nearrow \\ \searrow \end{array} \right) \text{ and similar relations.}$$

5/

Notice that there are two types of triangles:

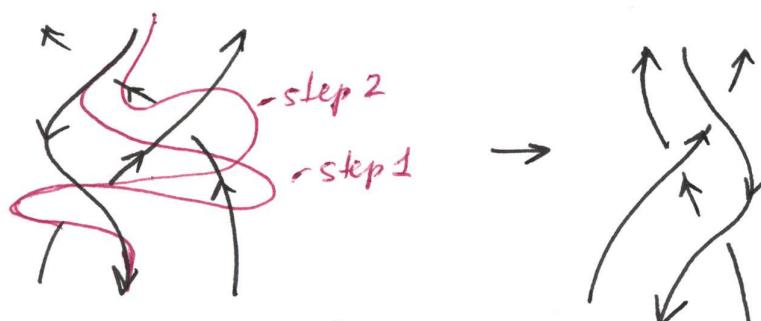


(central triangle
doesn't have
cyclic orientation)



(cyclic orientation
of the central triangle)

These triangles can be reduced to each other using channel & cross-channel unitarity:



cyclic triangle
in the center \Rightarrow non-cyclic triangle.

Thus, the model

$$V_{\swarrow\searrow} = A V_{\swarrow\searrow} + B V_{\nearrow\searrow}$$

$$V_{\swarrow\searrow} = \frac{1}{A} V_{\swarrow\searrow} + \frac{1}{B} V_{\nearrow\searrow}$$

is invariant
under
regular isotopy
for oriented link
diagrams.

What about the
moves of type
similar to R1?