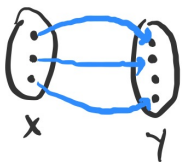
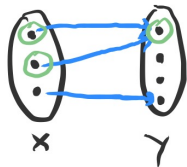


$f: X \rightarrow Y$ is one-to-one if there are no $x_1, x_2 \in X$ such that $x_1 \neq x_2$ and $f(x_1) = f(x_2)$



one-to-one



not 1-to-1

(1) a) $f: \mathbb{N} \rightarrow \mathbb{N}$ $f(n) = 2n$ 1-to-1 $2n = 2m \Rightarrow n = m$
 not onto $\{0, 1, 2, 3, \dots\}$ 1 is not in the range

b) $g: \mathbb{N} \rightarrow \{0, 1\}$ $g(n) = \begin{cases} 0 & n \text{ even} \\ 1 & n \text{ odd} \end{cases}$ $g(0) = 0$
 not 1-to-1 $g(1) = 1$
 onto $g(2) = g(4) = 0$

$$c) h: \{1, 2, 3\} \rightarrow \{4, 5, 6\}$$

$$\begin{array}{l} 1 \mapsto 5 \\ 2 \mapsto 6 \\ 3 \mapsto 5 \end{array} \quad \begin{array}{l} \text{not 1-to-1} \\ h(1) = h(3) = 5 \end{array} \quad \begin{array}{l} \text{not onto} \\ 4 \text{ is not in} \\ \text{the range} \end{array}$$

$$d) k: \mathbb{Z} \rightarrow \mathbb{R}^2 \quad k(n) = \begin{bmatrix} n \\ -n \end{bmatrix}$$

one-to-one
not onto

$$\begin{bmatrix} n & - & m \\ -n & & -m \end{bmatrix} \Rightarrow n = m$$

$$e) j: \{1, 2, 3, \dots\} \rightarrow \mathbb{N} \quad j(n) = n^{\text{th}} \text{ digit of } \pi \quad 3.141\dots$$

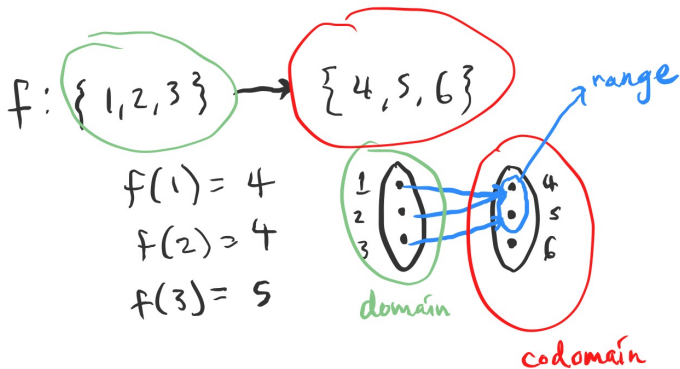
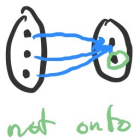
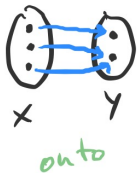
$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ not in the range $\begin{bmatrix} 1.5 \\ 1.5 \end{bmatrix}$ also not in the range

$$\text{not 1-to-1} \quad j(2) = j(4) = 1$$

not onto

10 is not in the range

$f: X \rightarrow Y$ onto if for each $y \in Y$ there is some $x \in X$ such that $f(x) = y$



a) lin. transformation 1-to-1 & onto. $\mathbb{R}^n \rightarrow \mathbb{R}^m$ $n=m$

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$T(\vec{v}) = \vec{v}$$

↑
identity map

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

↑
 I_2

one-to-one:

$$T(\vec{v}) = T(\vec{u}) \Rightarrow \vec{v} = \vec{u}$$

onto: for any \vec{v}

$$T(\vec{v}) = \vec{v} \text{ so } \vec{v} \text{ is} \\ \text{in } \text{range}(T)$$

REF
pivot in every col. \Rightarrow 1-to-1
pivot in every row \Rightarrow onto

$$\begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$$

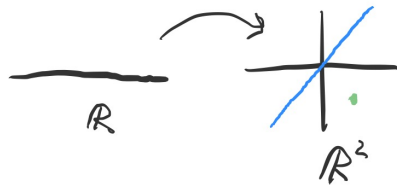
$\mathbb{R}^2 \rightarrow \mathbb{R}^2$
rotation by 90°

etc.

b) 1-to-1, not onto $\mathbb{R}^n \rightarrow \mathbb{R}^m$ $n < m$

$$T: \mathbb{R} \rightarrow \mathbb{R}^2$$

$$T(x) = \begin{bmatrix} x \\ x \end{bmatrix}$$



1-to-1 because

not onto.

$$\begin{bmatrix} x \\ x \end{bmatrix} = \begin{bmatrix} y \\ y \end{bmatrix} \Rightarrow x=y$$

$$\begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

not in the range

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} = [T]_{\text{std}}$$

$$\left. \begin{array}{l} R_2 = R_2 - R_1 \\ \downarrow \end{array} \right\}$$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

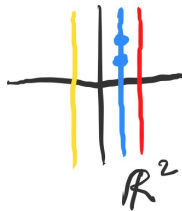
pivot in every col \Rightarrow 1-to-1
no pivot in 2nd row \Rightarrow not onto

c) onto, not 1-to-1

$$\mathbb{R}^n \rightarrow \mathbb{R}^m \quad n > m$$

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = x$$



not one-to-one: $T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = T\left(\begin{bmatrix} 1 \\ 3 \end{bmatrix}\right) = 1$

onto: for each $x \in \mathbb{R}$, $T\left(\begin{bmatrix} x \\ 0 \end{bmatrix}\right) = x$

so $x \in \text{range}(T)$

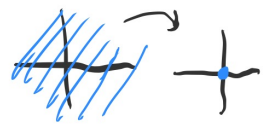
$$[T]_{\text{std}} = \begin{bmatrix} 1 & 0 \end{bmatrix}$$

REF

no pivot in 2nd column \Rightarrow not 1-to-1
pivot in every row \Rightarrow onto

(3d) A linear transformation that is neither one-to-one nor onto

stupid example: $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $T(\vec{x}) = \vec{0}$



not one-to-one $T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
 not onto: $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ not in the range

$[T]_{std} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ REF

no pivot in either col \Rightarrow not 1-to-1
 no pivot in either row \Rightarrow not onto

2nd example: $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $T(\vec{v}) = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \cdot \vec{v}$



everything on this line is mapped to $\vec{0}$

④ $f: \mathbb{R} \rightarrow \mathbb{R}^3$ $f(x) = \begin{bmatrix} x \\ x \\ x \end{bmatrix}$ $g\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = x+y+z$
 $g: \mathbb{R}^3 \rightarrow \mathbb{R}$

a) $g \circ f$ function from $\mathbb{R} \rightarrow \mathbb{R}$

$$g \circ f(x) = g(f(x)) = g\left(\begin{bmatrix} x \\ x \\ x \end{bmatrix}\right) = x+x+x = 3x$$

b) $f \circ g$ function from $\mathbb{R}^3 \rightarrow \mathbb{R}^3$

$$f \circ g\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = f\left(g\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right)\right) = f(x+y+z) = \begin{bmatrix} x+y+z \\ x+y+z \\ x+y+z \end{bmatrix}$$

c) $[g \circ f]_{std} = [g \circ f(\vec{e}_1)] = [g \circ f(1)] = [3]$

$$[f \circ g]_{std} = \begin{bmatrix} f \circ g(\vec{e}_1) & f \circ g(\vec{e}_2) & f \circ g(\vec{e}_3) \end{bmatrix} = \begin{bmatrix} | & | & | \\ | & | & | \\ | & | & | \end{bmatrix}$$