Complexity of computing zeros of structured polynomial systems

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joint work with

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Solving polynomial systems

▸ Given n homogeneous polynomial equations of degree d,

$$f_1(z) = 0, \ldots, f_n(z) = 0,$$

in $n + 1$ variables. Want to compute solutions in $\mathbb{P}^n(\mathbb{C})$.

▸ Intensively studied computational question! Not possible to summarize all the contributions here.

▸ Let's assume the input polynomials f_i are sufficiently generic.

▸ Well known: algebraic algorithms can compute all d^n solutions with $d^{O(n)}$ arithmetic operations: e.g., Renegar ('89), Lakshman ('91), Giusti, Lecerf, Salvy ('01).

▸ Can we do better if we just want one (or a few) solutions?

▸ Numerical homotopy continuation algorithms are capable of this, see impressive software by Breiding and Timme:
`https://www.juliahomotopycontinuation.org`

Homotopy continuation algorithms

▶ Such algorithms have been known for quite some time. Their complexity was investigated in detail by Shub & Smale in the 90ies.

▶ Smale's 17th problem (1998):

> *Can a zero of n complex polynomial equations in n unknowns be found approximately, on the average, in polynomial time with a uniform algorithm?*

▶ Here input polynomials are assumed to be distributed according to a unitary invariant Gaussian distribution (Kostlan, Bombieri, Weyl).

▶ Smale's question was given a positive answer by Lairez (2017), based on work by Shub & Smale, Shub, Beltran & Pardo, and Bürgisser & Cucker.

▶ Essentially optimal result for dense model by Lairez ('20): quasilinear expected cost $\text{poly}(n, d)N$, where N is input size in dense representation (number of coefficients).

How meaningful is the dense model?

▸ Dense representation, polynomials are given by their full list of coefficients: $N := n\binom{d+n}{n}$.

▸ But: Most systems of interest are structured in some sense; they lie in a set of measure zero in the input space of all polynomials.

▸ Thus the above probabilistic analysis doesn't tell us anything about the behaviour of the above algorithms on these structured inputs!

> The dense setting is only the first step towards understanding the problem!

▸ Ask about refinement of Smale's question for structured systems.

Unitary invariance

▸ Unitary invariance is an important feature enabling the probabilistic analysis in the mentioned results.

▸ The unitary group $U(n+1)$ acts on the space H of homogeneous polynomials of degree d in $n+1$ variables by linear transformation: "orthogonal coordinate transformation".

▸ The product $\mathcal{U} := U(n+1)^n$ of unitary groups acts on space $\mathcal{H} := H^n$:

$$(f_1, \ldots, f_n) \cdot (u_1, \ldots, u_n) := (f_1 \circ u_1, \ldots, f_n \circ u_n).$$

▸ Our new result applies to structured settings that respect unitary univariance.

▸ We will bound the expected running time of algorithms (solvers) over $\mathcal{U}$-orbits, that is, we average over $\mathcal{U}$.

Systems given by black-box evaluation. . .

▸ There are many ways to define structured systems.

▸ One may consider sparse systems, i.e., prescribe the support (occurring monomials) of the polynomials. See Malajovich ('19-'20).

▸ However, this model is not unitary invariant.

▸ Here we only assume that the polynomials are given by a black box: i.e., an evaluation routine. (No need to know what the routine actually does.)

▸ This is a common assumption in optimization: a function (and its gradient) are given by a black-box routine.

▸ Note: black box for f_i easily gives black box for composition $f_i \circ u_i$.

...and solving them

- Consider system $F = (f_1, \ldots, f_n) \in H^n$ s.t. zero set of f_i has no singularities.
- We assign to F a quantity reflecting its "numerical conditioning":

$$\Gamma(F) := \left(\Gamma(f_1)^2 + \cdots + \Gamma(f_n)^2\right)^{\frac{1}{2}} < \infty.$$

- $\Gamma(f_i)$ is essentially the average of Smale's γ quantity $\gamma(f_i, z)$, averaged over the compact hypersurface of zeros of f_i.
- $L(F)$: number of arithmetic operations sufficient to evaluate F.

Theorem (I)

We exhibit an algorithm BBS, *which on input* $F \in \mathcal{H}$ *given as black-box, and* $\epsilon > 0$, *computes an approximate zero of* F *with probability at least* $1 - \epsilon$.

On input $u \cdot F$, *where* $u \in \mathcal{U}$ *is uniformly random, this algorithm performs at most*

$$\mathrm{poly}(n, d) \cdot L(F) \cdot \left(\Gamma(F) \log \Gamma(F) + \log \log \epsilon^{-1}\right)$$

operations on average.

Solving random systems with unitary invariant distribution

- ▸ Theorem I applies to any prob. distribution of $F \in \mathcal{H}$ that is unitary invariant.

- ▸ On a random input $F \in \mathcal{H}$, the expected number of operations is bounded by
$$\text{poly}(n, \delta) \cdot L \cdot \left(\Gamma \log \Gamma + \log \log \epsilon^{-1} \right)$$
  where
$$\Gamma = \mathbb{E}[\Gamma(F)^2]^{\frac{1}{2}}$$
  and L denotes an upper bound on $L(F)$.

- ▸ We apply this to the class of polynomial systems computed by small algebraic branching programs.

- ▸ This class is unitary invariant and, by definition, these systems have small L (evaluation complexity).

- ▸ Have a natural invariant Gaussian distribution on this class.

- ▸ We managed to effectively upper bound $\Gamma(F)$ in this case.

Algebraic branching programs

▸ Algebraic branching programs (ABPs), introduced by Nisan ('91), play an important role in algebraic complexity theory: notably in Valiant's VP versus VNP theory.

▸ ABPs provide an elegant graphical way of formalizing computations with polynomials, but the most concise way to express the model is using matrices.

▸ Fix $r_0, \ldots, r_d \in \mathbb{N}_{>0}$ with $r_0 = r_d$ and let

$$A_i(z) = A_{i0}\, z_0 + \cdots + A_{in}\, z_n$$

with complex matrices A_{ij} of format $r_{i-1} \times r_i$, $1 \le i \le d$.

▸ The trace of iterated matrix multiplication

$$f(z) = \mathrm{tr}\left(A_1(z)\cdots A_d(z)\right).$$

is the polynomial defined by the corresponding ABP.

▸ By associativity of matrix multiplication, can evaluate $f(z)$ with a total of $O(ndr^3)$ arithmetic operations, where $r := \max_i r_i$.

Gaussian algebraic branching programs

▸ We assume now that the A_{ij} are independent complex standard Gaussian matrices and focus on the distribution of the (highly structured) random polynomial

$$f(z) = \operatorname{tr}\left(A_1(z)\cdots A_d(z)\right).$$

▸ Important: the distribution of f is unitarily invariant

▸ The support S of this distribution is a low dimensional algebraic subvariety of the space H of d-dimensional forms: $\dim S \leq d(n+1)^2$.

Theorem (II)

We have

$$\mathbb{E}\left[\Gamma(f)^2\right] \leq \tfrac{3}{4}d^3(d+n)\log d,$$

provided $r_1, \ldots, r_{d-1} \geq 2$. Otherwise, $\Gamma(f) = \infty$ almost surely.

The proof is a technical tour de force ...

Solving systems given by Gaussian ABPs

Corollary (II)

If $f_1, \ldots, f_n$ are given by independent Gaussian random ABPs of degree at most d, format $r_1, \ldots, r_{d-1} \geq 2$, and evaluation complexity at most L, then algorithm BBS computes a zero of $f_1 = 0, \ldots, f_n = 0$ with probability at least $1 - \epsilon$ in

$$\mathrm{poly}(n, d) \cdot L \cdot \log \log \epsilon^{-1}$$

operations on average.

Our result may be interpreted as a first step towards providing an affirmative answer to a refined version of Smale's 17th question, concerned with structured systems of polynomial equations.

Rigid Homotopy Continuation

▸ General framework due to Pierre Lairez, J. AMS 2019, substantially improving Shub & Smale and basis of our work.

▸ Fix $F = (f_1, \ldots, f_n) \in \mathcal{H}$ s.t. zero set of f_i has no singularities. Consider the compact "solution variety"

$$\mathcal{V} := \{((u_1, \ldots, u_n), z) \in \mathcal{U} \times \mathbb{P}^n \mid f_1(u_1(z)) = 0, \ldots, f_n(u_n(z)) = 0\}.$$

▸ $\mathcal{V}$ is invariant under action of $\mathcal{U}$, have $\mathcal{U}$-invariant prob. distribution.

▸ It is possible to efficiently compute a sample $(u, z) \in \mathcal{V}$.

▸ Connect u to identity I by a geodesic path $[0, 1] \to \mathcal{U}$, $t \mapsto u_t$, s.t. $u_0 = u$, $u_1 = I$. Continue the zero z by a path $[0, 1] \to \mathbb{P}^n$, $t \mapsto z_t$ s.t. $z_0 = z$ (almost surely possible).

Stepsizes via Monte Carlo sampling

▸ Implement numerical continuation via Newton iteration.
▸ Appropriate step sizes are given by Smale's parameter $\gamma(f, z)$.
▸ Previous algorithm estimated stepsize in terms of condition number, which leads to large step sizes and is much too wasteful!
▸ Definition of $\gamma(f, z)$ involves norm of higher order derivatives

$$\tfrac{1}{k!}\left\|D_z^k f\right\|_F = \|f(z+\bullet)_k\|_W,$$

where $p = f(z + \bullet)_k$ is the homogeneous component of degree k of the shifted polynomial $x \mapsto f(z + x)$.
▸ Trick from algebraic complexity: p is easy to compute in black box model.
▸ Estimate $\gamma(f, z)$ using Monte Carlo random samplling based on

$$\|p\|_W^2 = \binom{n+1+k}{k} \mathbb{E}_w[|p(w)|^2],$$

with w chosen uniformly at random in euclidean unit ball B of $\mathbb{C}^{n+1}$.
▸ The rigid continuation algorithm is Monte-Carlo: it fails with controlled error probability.

Thank you for your attention!