

Lecture 11 - Jordan Form

Last time: Given A , we have

$\mathbb{F}^n = E_0 \oplus U$, where both are invariant, A is nilpotent on E_0 , and A is injective (\Rightarrow bijective) on U .

Prop) The only eigenvalue of A on E_0 is 0

z) 0 is not an eigenvalue of A on U .

Pf i) If $A\bar{v} = \lambda\bar{v}$, then $A^m\bar{v} = \lambda^m\bar{v}$. Thus a non-zero eigenvector for $\lambda \neq 0$ is one on which A does not act nilpotently.
 \Rightarrow none in E_0 .

z) 0 is an eigenvalue $\Leftrightarrow \ker(A) \neq \{0\}$. A is injective on U .

Now a small piece of notation. If U is an A -invariant subspace, then multiplication by A is a linear operator on U . We'll denote this operator by $A|_U$.

Cor If $P_A(\lambda) = \lambda^{m_0}(\lambda - \lambda_1)^{m_1} \dots$, then

$$P_{A|_{E_0}}(\lambda) = \lambda^{m_0} \quad \text{and} \quad P_{A|_U}(\lambda) = (\lambda - \lambda_1)^{m_1} \dots$$

Thus $\dim E_0 = m_0$.

Pf By invariance, we have a block decomposition

$$A \sim \begin{bmatrix} A_0 & | & 0 \\ \hline \cdots & & \cdots \\ 0 & : & A_1 \end{bmatrix} \quad A_0 = A|_{E_0}, \quad A_1 = A|_U.$$

$$\text{So } P_A(\lambda) = \begin{vmatrix} A_0 - \lambda I & & & \\ & \ddots & & \\ & & A_1 - \lambda I & \\ & & & \vdots \end{vmatrix} = \det(A_0 - \lambda I) \cdot \det(A_1 - \lambda I)$$

By the previous prop, only roots of $\det(A_0 - \lambda I)$ are zero & zero not a root of $\det(A_1 - \lambda I)$

So, up to a sign, $\det(A_0 - \lambda I) = \lambda^m$

$$\det(A_1 - \lambda I) = P_A(\lambda)/\lambda^m.$$

Since $\dim V = \deg P_A(\lambda)$, $\dim E_0 = m$. \square

Def Let λ_0 be an eigenvalue of A . The generalized eigenspace for λ_0 , E_{λ_0} , is $\bigcup \ker((A - \lambda I)^m)$.

Lemma If $B = A - \lambda_0 I$, then $P_B(\lambda) = P_A(\lambda + \lambda_0)$.

$$\begin{aligned} \text{Pf } P_B(\lambda) &= \det(B - \lambda I) = \det(A - \lambda_0 I - \lambda I) \\ &= \det(A - (\lambda + \lambda_0) I) = P_A(\lambda + \lambda_0) \end{aligned}$$

Prop $\dim E_{\lambda_0} = \text{multiplicity of } \lambda_0 \text{ as a root in } P_A(\lambda)$.

Pf Apply the previous theorem to $A - \lambda_0 I$. Then if $B = A - \lambda_0 I$, then E_0 for B is E_{λ_0} for A . Thus $\dim E_{\lambda_0} = \text{multiplicity of } 0 \text{ as a root of } P_B(\lambda)$. This is the multiplicity of λ_0 as a root of $P_A(\lambda)$. \square

We are now in a position to generalize the splitting into eigenspaces.

Thm If $P_A(\lambda) = (\lambda - \lambda_1)^{m_1} \cdots (\lambda - \lambda_r)^{m_r}$, then

$$V = E_{\lambda_1} \oplus \cdots \oplus E_{\lambda_r} \text{ and } \dim E_{\lambda_k} = m_k.$$

Pf By induction on r . The base case is obvious

By our previous propositions, we know that

$V = U \oplus E_{\lambda_r}$, and U is A -invariant & $(A - \lambda_r I)$ is an isomorphism on U . Then the char poly of A on U is $P_{A|_U}(\lambda) = (\lambda - \lambda_1)^{m_1} \cdots (\lambda - \lambda_{r-1})^{m_{r-1}}$. Now on U , we can apply the inductive hypothesis \Rightarrow

$$U = E_{\lambda_1} \oplus \cdots \oplus E_{\lambda_{r-1}}$$

$$\Rightarrow V = E_{\lambda_1} \oplus \cdots \oplus E_{\lambda_r}. \quad \square$$

Remark In fact, the E_{λ_k} are the ones named above:

$\dim(E_{\lambda_k}) = m_k$: the E_{λ_k} in U is a subspace of \mathbb{F}^n w/ same dimension and contained in E_{λ_k} .

So it must be E_{λ_k} .

This theorem makes Jordan form work. The direct sum decomposition tells us that A is similar to a matrix:

$$\begin{bmatrix} A_{\lambda_1} & 0 & 0 & \dots & 0 \\ 0 & A_{\lambda_2} & 0 & \dots & 0 \\ 0 & 0 & 1 & \ddots & 0 \\ \vdots & & & \ddots & \\ 0 & 0 & 0 & \dots & A_{\lambda_r} \end{bmatrix}_{m_1 \ m_2 \ \dots \ m_r}^{m_1 \ m_2 \ \dots \ m_r}$$

& moreover, the behavior of A_{λ_k} is determined by the nilpotent matrix $(A_{\lambda_k} - \lambda_k \cdot I)$.

So if we can find a nice form for $B = (A_{\lambda_k} - \lambda_k \cdot I)$, say J , then the corresponding one for $A_{\lambda_k} = J + \lambda_k \cdot I$.

We look now at a nilpotent matrix A , acting on \mathbb{F}^n .

So we have a sequence of subspaces

$$\{\bar{0}\} \subseteq \ker(A) \subseteq \ker(A^2) \subseteq \dots \subseteq \ker(A^m) = \mathbb{F}^n$$

and we also know that for $0 < k \leq m$,

$$\ker(A^{k-1}) \subsetneq \ker(A^k)$$

Prop $A \cdot \ker(A^k) \subseteq \ker(A^{k-1})$

Pf If $\bar{v} \in \ker(A^k)$, then $\bar{o} = A^k \bar{v} = A^{k-1} A \bar{v}$
 $\Rightarrow A \bar{v} \in \ker(A^{k-1})$

□

Now we can get a sequence of linearly independent elements, each lying in distinct strata.

Prop If $\bar{v} \in \ker(A^k) - \ker(A^{k-1})$, then

$\{\bar{v}, A\bar{v}, \dots, A^{k-1}\bar{v}\}$ is linearly independent.

Pf By induction on k , and the base case is obvious.

So assume that for all $\bar{w} \in \ker(A^{k-1}) - \ker(A^{k-2})$,
 $\{\bar{w}, \dots, A^{k-2}\bar{w}\}$ is linearly independent, and consider
a linear dependence relation

$$a_0 \bar{v} + \dots + a_{k-1} A^{k-1} \bar{v} = \bar{o}$$

Applying A , and letting $\bar{w} = A\bar{v}$, we get

$$a_0 \bar{w} + \dots + a_{k-2} A^{k-2} \bar{w} = \bar{o}.$$

By the induction hypothesis, $\{\bar{w}, \dots, A^{k-2}\bar{w}\}$ is lin. ind,

so $a_0 = \dots = a_{k-2} = 0$. Thus our original equality was

$$a_{k-1} A^{k-1} \bar{v} = \bar{o}. \text{ Since } \bar{v} \notin \ker(A^{k-1}),$$

we conclude $a_{k-1} = 0$ & so $\{\bar{v}, \dots, A^{k-1}\bar{v}\}$ is linearly independent.

□

On the subspace $\langle \bar{v}, \dots, A^{k-1}\bar{v} \rangle$, we have an easy matrix for A :

$$A \simeq \begin{bmatrix} A^{k-1}\vec{v} & A^k\vec{v} & \cdots & \vec{v} \\ 0 & 1 & & 0 \\ \vdots & 0 & \ddots & \vdots \\ 0 & \ddots & \ddots & 1 \\ 0 & 0 & 0 & \vec{v} \end{bmatrix}$$

Def The $k \times k$ - Jordan Block matrix (w/ eigenvalue λ) is

$$J_k(\lambda) = \begin{bmatrix} \lambda & & & 0 \\ & \lambda & & \\ & & \ddots & \\ 0 & & & \lambda \end{bmatrix}$$

So on a space like $\langle \vec{v}, A\vec{v}, \dots, A^{k-1}\vec{v} \rangle$, with the obvious basis, $A \sim J_k(\lambda)$.

We can do better.

Prop Let $\vec{v}_1, \dots, \vec{v}_s \in \ker(A^k)$ be such that

$\{A^{k-1}\vec{v}_1, \dots, A^{k-1}\vec{v}_s\}$ is linearly independent. Then

$\{\vec{v}_1, \dots, \vec{v}_s, A\vec{v}_1, \dots, A\vec{v}_s, \dots, A^{k-1}\vec{v}_1, \dots, A^{k-1}\vec{v}_s\}$ is lin. ind.

Pf By induction on k , and the base case is again obvious.

Consider the linear dependence relation

$$(*) \quad a_{11}\vec{v}_1 + \dots + a_{1s}\vec{v}_s + a_{21}A\vec{v}_1 + \dots + a_{ij}A^{i-1}\vec{v}_j + \dots = \vec{0}.$$

If we apply A and let $\vec{w}_i = A\vec{v}_i$, then $(*)$ becomes

$$a_{11}\vec{w}_1 + \dots + a_{1s}\vec{w}_s + \dots = \vec{0}. \quad \text{Our inductive}$$

$+ a_{k-1,1}A^{k-2}\vec{w}_1 + \dots + a_{k-1,s}A^{k-2}\vec{w}_s$ hypothesis ensures

that $\{\vec{w}_1, \dots, A^{k-2}\vec{w}_s\}$ is independent. Thus

$a_{ij} = 0$ for $i < k$. Now (*) is

$a_{k1} A^{k-1} \bar{v}_1 + \dots + a_{ks} A^{k-1} \bar{v}_s = \bar{0}$, and we assumed
 $\{A^{k-1} \bar{v}_1, \dots, A^{k-1} \bar{v}_s\}$ was lin. ind. Thus $a_{ki} = 0$ for all i .
And hence $\{\bar{v}_1, \dots, A^{k-1} \bar{v}_s\}$ is lin. independent. \square