

# Lecture 5 - More on Linear Maps

Last time we saw the rank-nullity theorem:

$$\dim U = \dim(\ker L) + \dim(\text{Im } L)$$

↑  
nullity                   ↑  
rank

The terms come from matrices. If  $A$  is a matrix, then the null-space of  $A$  is the set of solutions to the homogeneous system

$$A \cdot \bar{x} = \bar{0}.$$

The rank is the dimension of the space of those  $\bar{b}$  such that  $A \cdot \bar{x} = \bar{b}$  has a solution.

This has another name: the column space.

Our analysis shows that with a choice of basis, the column space of  $c[L]_B$  corresponds to the image of  $L$  & the null-space corresponds to the kernel. So these really do reproduce our earlier concepts.

Now let's see that our map  $e[-]_B$  is an isomorphism. It's mono: If  $L \in \ker()$ , then  $L(\bar{b}_i) = \bar{0}$  for all  $i$  (since this pulls out the coefficients). Thus  $L = 0$ .

It's epi: Consider  $\phi_e \circ A \circ \phi_B^{-1}: U \rightarrow V$ . This is a composite of linear maps. Then  $e[\phi_c \circ A \circ \phi_B^{-1}]_B = A$ .

We evaluate on  $\bar{b}_i$  & apply  $\phi_e^{-1}$  to get a column vector  $\phi_e^{-1}(\phi_c \circ A \circ \phi_B^{-1})(\bar{b}_i) = A(\bar{e}_i) = i^{\text{th}}$  column of  $A$ .  $\square$

Thus a choice of basis everywhere identifies  $U$  with  $\mathbb{F}^n$  and  $L(U, V)$  with  $m \times n$ -matrices.

Can ask how a choice of basis changes the form of this isomorphism.

Prop If  $L: U \rightarrow V$  is an isomorphism, then the image under  $L$  of a basis of  $U$  is a basis of  $V$ .

Remark: Can do better:  $L$  a monomorphism  $\Rightarrow (\text{lin ind in } U) \rightarrow (\text{lin ind in } V)$  &  $L$  an epimorphism  $\Rightarrow (\text{spanning in } U) \rightsquigarrow (\text{spanning in } V)$ .

Pf: Let  $a_1 L(\bar{v}_1) + \dots + a_n L(\bar{v}_n) = \bar{0}$ . Then by linearity,  
 $L(a_1 \bar{v}_1 + \dots + a_n \bar{v}_n) = \bar{0}$ , so  $a_1 \bar{v}_1 + \dots + a_n \bar{v}_n \in \ker(L) = \{\bar{0}\}$ .

Since the  $\bar{v}_i$  are linearly ind, we conclude that  
 $a_1 = \dots = a_n = 0$ .

If  $\bar{w} \in V$ , then since  $L$  is onto,  $\bar{w} = L(\bar{v})$ . Since  $\{\bar{v}_i\}$  spans,  $\bar{v} = a_1 \bar{v}_1 + \dots + a_n \bar{v}_n \Leftarrow \bar{w} = a_1 L(\bar{v}_1) + \dots + a_n L(\bar{v}_n)$ .  $\square$

In fact monomorphism  $\longleftrightarrow$  "takes linearly independent sets to linearly independent sets".

On the other hand, given two bases of  $V$ , we have an automorphism of  $V$ :  $b_i \longleftrightarrow c_i$

So we see a very close connection between pairs of bases and automorphisms:

basis + aut = new basis & basis + basis = aut.

Let's apply to a test case of matrices to see how to relate different bases.

Prop An  $n \times n$ -matrix is invertible iff nullity = 0 or iff rank =  $n$ .

This is a restatement of the above. We've just used that  $n$  linearly independent vectors in an  $n$ -dimensional space form a basis.

So  $(n \times n)$  invertible matrices  $\longleftrightarrow$  ordered bases of  $\mathbb{F}^n$ . But how does this work? Columns of matrix are our new basis elements. Problem: still expressed in the original basis!

So we are taking our new basis vectors  $(\bar{b}_1, \dots, \bar{b}_n)$  and writing them as a linear combination of the standard basis vectors.

Let's make this slightly fancier. We have

$$\begin{array}{ccc} \mathbb{F}^n & \longrightarrow & \mathbb{F}^n \\ \text{b-basis} & & \bar{\text{e}}\text{-basis} \\ \bar{b}_i & \longmapsto & \bar{b}_i \end{array} \quad \& \text{we are taking the associated matrix}$$

This is a very special linear transformation: the identity! (Take  $\bar{b}$  to  $\dots \bar{b}$ ).

Thus A is the matrix

$$\begin{bmatrix} \bar{b}_1 & \dots & \bar{b}_n \\ \bar{e}_1 & \vdots & \bar{e}_n \end{bmatrix} = e^{[I]_{\mathcal{B}}}$$

We'll call this a "change of basis" matrix and write it  $\mathcal{E}P_B$ .

Observation: For any  $\mathcal{B}, \mathcal{C}, \mathcal{D}$ ,

$$\mathcal{D}P_{\mathcal{C}} \mathcal{E}P_B = \mathcal{D}P_B.$$

Thus  $\mathcal{C}P_B = \mathcal{B}P_C^{-1}$  and

$$\mathcal{C}P_B = (\mathcal{E}P_{\mathcal{C}})^{-1} \mathcal{E}P_B.$$

The last part is the most useful. It is easy to compute  $\mathcal{E}P_B$  (it's normally given to us in a description of  $\mathcal{B}$ ), then we compute the inverses and multiply.

Why is this sort of thing true?

$\mathcal{E}P_B$  has columns which express  $\bar{b}$  in the  $\bar{c}$  basis.

$\mathcal{D}P_C$  does similar things. So we start in the  $\mathcal{B}$ -basis, write things in the  $\mathcal{C}$ -basis, then substitute for  $\bar{c}$ , the expression in the  $\mathcal{D}$ -basis. We still just have  $\bar{b}$ , but now in the  $\mathcal{D}$ -basis.

This holds more generally:

Thm If  $\mathcal{B}, \mathcal{B}'$  are ordered bases of  $U$  and  $\mathcal{C}, \mathcal{C}'$  ordered bases of  $V$ , then

$$[\mathcal{C}[L]]_{\mathcal{B}} = \mathcal{E}P_{\mathcal{C}'} \cdot \mathcal{C}'[L]_{\mathcal{B}'} \cdot \mathcal{B}'P_{\mathcal{B}}$$

We just look at what both give. The  $i$ th column of  $e[L]_B$  is the coefficient vector of  $L(\bar{b}_i)$  expressed in the  $C$ -basis.

Similarly,  $B'P_B$  expresses  $\bar{b}_i$  as a linear combination of the  $\bar{b}'$ 's.

$$\bar{b}_i = a_1 \bar{b}'_1 + \dots + a_n \bar{b}'_n$$

Then we multiply by  $e[L]_{B'}$ , which amounts to evaluating  $L$  on the vector and writing the result in the  $C'$  basis. This is still just  $L(\bar{b}_i)$ , but in the  $C'$  basis. Multiplying by  $eP_C$  amounts to substituting in the  $C$ -basis ie. expressing  $L(\bar{b}_i)$  in the  $C$  basis.

Now on aside.

Def An equivalence relation is a relation  $\sim$  on  $X$  s.t.

- 1)  $a \sim a$  (reflexive)
- 2)  $a \sim b \Rightarrow b \sim a$  (symmetric)
- 3)  $a \sim b, b \sim c \Rightarrow a \sim c$  (transitive)

These are "like" equality but in general a little weaker.

(Recall: a relation  $R$  is a subset of  $X \times X$  ?

$a R b$  means  $(a, b) \in R$ . So it's a truth statement).

Def The equivalence class of  $x \in X$  is

$$[x] = \{y \mid x \sim y\}.$$

The quotient  $X/\sim$  is the set of equivalence classes.

In general, equivalence classes are disjoint or equal:

$$\text{Prop } [x] \cap [y] = \begin{cases} [x] & x \sim y \\ \emptyset & x \not\sim y \end{cases}$$

This is obviously symmetric.

Assume  $x \sim y$ . Then  $y \sim x$  by symmetry &  $x \in [y]$ .

Now if  $z \in [x]$ , then  $x \sim z$ , so  $y \sim z \Rightarrow z \in [y]$ .

Thus  $[x] \subseteq [y]$ . Swapping roles gives  $[y] \subseteq [x]$ .

Conversely, if  $z \in [x] \cap [y]$ , then  $x \sim z \nRightarrow y \sim z$ , so

$x \sim y \nRightarrow$  in first case.  $\square$

Ex: On vector spaces, "is isomorphic to" is an equiv relation.

$\left\{ \begin{array}{l} \text{finite dimensional} \\ \text{V. spaces} \end{array} \right\} \xrightarrow{\dim} \mathbb{N}$  is a bijection,

since every f.d. vector space is isomorphic to  $\mathbb{F}^n$  for some  $n$  &  $\dim$  is the isomorphism invariant.

Ex: On  $M_{m \times n}(\mathbb{F})$ , say  $A$  and  $B$  are equivalent if we can find a  $P \in M_{m \times m}(\mathbb{F})$  and  $Q \in M_{n \times n}(\mathbb{F})$ , both invertible, such that

$$A = PBQ.$$

Prop This is an equivalence relation.

$$1) A = I \cdot A \cdot I, \text{ so } A \sim A$$

$$2) A = PBQ \Rightarrow P^{-1}AQ^{-1} = B \text{ so } A \sim B \Rightarrow B \sim A$$

$$3) A = PBQ \nmid B = RCT, \text{ then } A = (PR)C(TQ)$$

$$\nmid (PR)^{-1} = T^{-1}R^{-1}, \text{ etc, so } A \sim B, B \sim C \Rightarrow A \sim C. \quad \square$$

If we identify  $P$  and  $Q$  with change-of-basis matrices, then we see this equivalence relation identifies two matrices if they have the same underlying linear transformation.

We can find easy representatives of each equiv. class. Let  $L: U \rightarrow V$ , and as in the proof of the rank-nullity theorem, write  $U = U' \oplus \ker(L)$ , where  $L|_{U'}$  is an isomorphism onto the image. Choose bases  $\{\bar{u}_1, \dots, \bar{u}_k\}$  of  $U'$  and  $\{\bar{u}_{k+1}, \dots, \bar{u}_n\}$  of  $\ker(L)$ , and since  $L|_{U'}$  is injective,  $\{L\bar{u}_1, \dots, L\bar{u}_k\}$  is linearly independent. Extend this to a basis of  $V$ . Now

$$e^{[L]}_{\mathcal{B}} = \begin{bmatrix} L\bar{u}_1 & \cdots & L\bar{u}_k & L\bar{u}_{k+1} & \cdots & L\bar{u}_n \\ \vdots & & I_k & | & & \text{O} \\ L\bar{u}_n & - & \cdots & - & \cdots & - \\ \bar{u}_{k+1} & \vdots & \bar{u}_m & | & & \text{O} \end{bmatrix}.$$

From this we can easily read out everything.

Remark We can stay entirely in matrices and get this.

Elementary row operations = left mult by invertible things allows us to proceed to reduced row echelon form.

Elementary column ops = right mult  $\Rightarrow$  the form above.