## The Frenet-Serret Formulas

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We start with the formula we know by the definition:

$$\frac{d\mathbf{T}}{ds} = \kappa \mathbf{N}.$$

We also defined

$$\mathbf{B} = \mathbf{T} \times \mathbf{N}$$

We know that **B** is a unit vector, since **T** and **N** are orthogonal unit vectors. This means, just as for **T**, that

$$\mathbf{B} \cdot \frac{d\mathbf{B}}{ds} = 0.$$

Now we differentiate:

$$\frac{d}{ds}\mathbf{B} = \frac{d}{ds}(\mathbf{T} \times \mathbf{N}) = \left(\frac{d\mathbf{T}}{ds}\right) \times \mathbf{N} + \mathbf{T} \times \left(\frac{d\mathbf{N}}{dx}\right).$$

Since the derivative on  $\mathbf{T}$  is in the same direction as  $\mathbf{N}$ , we know that the first cross product is  $\mathbf{0}$ . The second one we can't say much about. We do, however, know that it is orthogonal to  $\mathbf{T}$ , since  $\mathbf{T}$  is one of the factors. In other words, we know that

$$\frac{d}{ds}\mathbf{B}\cdot\mathbf{B} = 0 = \frac{d}{ds}\mathbf{B}\cdot\mathbf{T}.$$

This means that it has to be in the direction of N, and we just define the magnitude to be  $-\tau$ . In other words, we see that

$$\frac{d}{ds}\mathbf{B} = -\tau\mathbf{N}.$$

Now we approach the derivative of **N**. We can write  $\mathbf{N} = \mathbf{B} \times \mathbf{T}$ , just by thinking about the right hand rule. Now we differentiate this, using the previous rules:

$$\frac{d\mathbf{N}}{ds} = \left(\frac{d\mathbf{B}}{ds}\right) \times \mathbf{T} + \mathbf{B} \times \left(\frac{d\mathbf{T}}{ds}\right) = -\tau \mathbf{N} \times \mathbf{T} + \mathbf{B} \times \kappa \mathbf{N}$$

Now we just rewrite the cross products using the right hand rule:

$$-\tau \mathbf{N} \times \mathbf{T} + \mathbf{B} \times \kappa \mathbf{N} = \tau \mathbf{B} - \kappa \mathbf{T}.$$