

8/7/25 - (Partial) Derivative Review

Derivatives

given a function $f(x)$, its derivative gives the rate at which $f(x)$ changes as x is varied. This is denoted $f'(x)$ or $\frac{df}{dx}$.

example

- if $x(t)$ gives the position of an object at time t ,
then $x'(t)$ give the velocity of the object
and $x''(t)$ give the acceleration of the object

Formal definition

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

Basic derivatives

constants: $\frac{d}{dx} 5 = 0$ ← constant function

power rule: $\frac{d}{dx} x^n = n x^{n-1}$

trig functions: $\frac{d}{dx} \sin x = \cos x$

$$\frac{d}{dx} \cos x = -\sin x$$

exponentials: $\frac{d}{dx} e^x = e^x$

$$f' = f$$

logarithm: $\frac{d}{dx} \log x = 1/x$

Derivative Rules

constant multiple: $(a f(x))' = a f'$

sum: $(f(x) + g(x))' = f' + g'$

linearity of d/dx

product: $(f(x) \cdot g(x))' = f'g + fg'$

$$(fgh)' = f'gh + fg'h + fgh'$$

quotient: $\left(\frac{f(x)}{g(x)}\right)' = \frac{gf' - g'f}{g^2}$

composition (chain rule): $(f(g(x)))' = (f \circ g(x))' = f'(g(x)) g'(x)$

$$(f(g(h)))' = f'(g(h)) g'(h) h'$$

Fundamental Theorem of Calculus

$$\frac{d}{dx} \int_0^x f(y) dy = f(x)$$

$$\int_0^x \frac{df}{dy} dy = f(x) - f(0)$$

examples

$$\begin{aligned} \bullet \quad (5x^3 + 2x^2 + 3x + 6)' &= (\underline{5}x^3)' + (\underline{2}x^2)' + (\underline{3}x)' + (\underline{6})' \\ &= 5 \cdot 3x^2 + 2 \cdot 2x + 3 \\ &= 15x^2 + 4x + 3 \end{aligned}$$

$$\begin{aligned} \bullet \quad \frac{d}{dx} [\sin^2(x)] &= (\sin x \cdot \sin x)' = 2 \cos x \cdot \sin x \\ &= ((\sin x)^2)' = 2 \sin x \cdot (\sin x)' \\ &= 2 \sin x \cos x \end{aligned}$$

$$\bullet \quad \frac{d}{dx} (\sin x \cdot \cos x \cdot x) = x \cos^2 x - x \sin^2 x + \sin x \cdot \cos x$$

$$\bullet \quad \frac{d}{dx} [\tan(x)] = \frac{d}{dx} \left[\frac{\sin x}{\cos x} \right] = \frac{\overbrace{\cos^2 x + \sin^2 x}^1}{\cos^2 x} = \sec^2 x$$

$\swarrow$ $\exp(\sim) = e^{\sim}$

$$\begin{aligned} \bullet \quad \frac{d}{dx} [\exp(-x^2)] &= \exp(-x^2) (-x^2)' \\ &= \underline{-2x} \underline{\exp(-x^2)} \end{aligned}$$

Partial Derivatives

given a function of multiple variables $f(x, y)$, a partial derivative $\frac{\partial f}{\partial x}$ is the derivative of f w.r.t. x if y is treated as a constant.

Denoted $\frac{\partial f}{\partial x}$ or $\partial_x f$ or (sometimes) f_x .

examples

$$\begin{aligned} \cdot \frac{\partial}{\partial x} (y x^2 + y^2 x + \sin y) &= y \frac{\partial}{\partial x} (x^2) + y^2 \frac{\partial}{\partial x} (x) + 0 \\ &= 2yx + y^2 \end{aligned}$$

$\uparrow$ const $\uparrow$ const $\uparrow$ const

$$\cdot \frac{\partial}{\partial y} [\sin(\overset{\text{const}}{\downarrow} xy)] = \cos(xy) \frac{\partial}{\partial y} (xy) = x \cos(xy)$$

$$\begin{aligned} \cdot \frac{\partial}{\partial z} [\exp(\overset{\text{const}}{\downarrow} x^2 + \overset{\text{const}}{\downarrow} y^2 + z^2)] &= \exp(x^2 + y^2 + z^2) \frac{\partial}{\partial z} (x^2 + y^2 + z^2) \\ &= 2z \exp(x^2 + y^2 + z^2) \\ &\rightarrow \frac{\partial}{\partial z} (\underbrace{e^{x^2} e^{y^2}}_{\text{product}} e^{z^2}) = 2z \underbrace{e^{x^2} e^{y^2}}_{\text{product}} e^{z^2} = 2e \exp(\underbrace{x^2 + y^2 + z^2}_{\text{sum}}) \end{aligned}$$

Application to ODEs

Given a first order ODE in normal form,

$$x'(t) = \underbrace{f(x, t)}$$

how "nice"?

example Suppose $x'(t) = f(x, t) = t^2x + \sin t$.

Find $\frac{\partial f}{\partial x} = t^2$

$$\frac{\partial f}{\partial t} = 2tx + \cos t$$

Monday

Module 4

Separable ODEs $\leftarrow$ really useful for nonlinear ODEs

ODEs of the form

$$\boxed{\frac{dx}{dt}} = \underbrace{f(x)}_{\text{dep}} \underbrace{g(t)}_{\text{ind}}$$

can be separated like $\frac{dx/dt}{f(x)} = g(t)$

and then integrated to solve for $x(t)$.

$$\frac{dx/dt}{f(x)} = g(t) \Rightarrow \int \underbrace{\frac{dx}{f(x)}}_{\text{all } x \text{ dep.}} = \underbrace{\int g(t) dt}_{\text{all } t \text{ dep.}}$$

example:

$$\frac{dx}{dt} = x^2 \sin t$$

$$\int \frac{x'}{x^2} dt = \int \sin t dt$$

$$\int \frac{dx}{x^2} = \int \sin t dt$$

$$+x^{-1} = +\cos t + C$$

$$x(t) = \frac{1}{\cos t + C}$$

general solution

$$\int \frac{dx/dt}{f} dt = \int g(t) dt$$

$$\int \frac{1}{f(x)} dx =$$

Linear, first order ODEs

given

$$\frac{dy}{dx} = a(x)y + f(x)$$

we rearrange

$$\frac{dy}{dx} - a(x)y = f(x)$$

and introduce an integrating factor $\mu = \exp\left(-\int a(x)dx\right)$ as

$$\mu \frac{dy}{dx} - \mu a y = \mu f(x)$$

so that

$$\frac{d}{dx}(\mu y) = \mu f(x)$$

then

$$y = \frac{1}{\mu} \int \mu(x) f(x) dx$$

$$y' + by = f(x)$$

$$\mu = \exp\left(\int b(x)dx\right)$$

example: solve $\cos(x)y' + \sin(x)y = \cos^2(x)$

rearranging, $y' + \tan(x)y = \cos x$

then $\mu = \exp \int \tan x dx = \exp(-\log \cos x)$

so

$$\mu = 1/\cos x$$

Then $\frac{d}{dx}(y/\cos x) = 1$

$$y = a \cdot \cos x$$

for some constant a .

Differential forms

a differential form is an expression of the form

$$P(x,y)dx + Q(x,y)dy \quad (\text{or more variables})$$

Similarly, given a function $f(x,y)$, we define its differential as

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

If a differential form can be written as df for some f , then we say it is exact.

Given $P(x,y)dx + Q(x,y)dy = 0$, a solution is a function

$F(x,y)$ such that $dF = \mu(Pdx + Qdy)$ for some integrating factor μ . (More about this on Monday)

example find F s.t. $dF = (2xy - 9x^2)dx + (2y + x^2 + 1)dy$

one method: integrate both terms

$$\begin{aligned} \frac{\partial F}{\partial x} = 2xy - 9x^2 &\Rightarrow F(x,y) = \int (2xy - 9x^2) dx \\ &= x^2y - 3x^3 + g(y) \end{aligned}$$

important $\swarrow$

$$\text{and } \frac{\partial F}{\partial y} = 2y + x^2 + 1 \Rightarrow F(x,y) = y^2 + x^2y + y + h(x)$$

matching terms,

$$F(x,y) = x^2y - 3x^3 + y^2 + y + C$$

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Linear, first order ODEs

Suppose we have an ODE of the form

$$\tilde{y}' = a(x)y + b(x)$$

idea: product rule $(fg)' = \downarrow f'g + \downarrow fg'$

$$\mu \downarrow y' - \mu \downarrow a y = b\mu$$

$$\mu' = -a\mu \Rightarrow \mu = \exp(-\int a dx)$$

$$(\mu y)' = b\mu$$

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Roman: Thr 2-3pm

this zoom.

example

$$ty' + 2y = t^2 - t + 1 \quad \text{w/} \quad y(1) = 1/2, \quad t > 0$$

$$y' + \underbrace{\frac{2}{t}}_{-a} y = t - 1 + 1/t$$

$$\mu = \exp \int 2/t dt = \exp(2 \log t) = t^2$$

$$t^2 y' + 2ty = t^3 - t^2 + t$$

$$\int (t^2 y)' = \int t^3 - t^2 + t dt$$

$$y = \frac{1}{4}t^2 - \frac{1}{3}t + \frac{1}{2} + ct^{-2}$$

example

$$y' + (\log t)y = 0$$

Differential Forms

(warning: googling this may result in more advanced math)

a differential form is an expression of the form

$$\underline{P(x,y)dx + Q(x,y)dy} \quad (\text{or more variables})$$

Roughly, it is "something that can be integrated"

Given a function $f(x,y)$, we define its differential as

$$\underline{df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy}$$

If $Pdx + Qdy = df$ for some f , then we say that

$\underline{Pdx + Qdy}$ is exact.

Theorem (Condition for exactness)

If $P(x,y), Q(x,y)$ are nice functions (continuously differentiable)

on a region w/o holes, then $\underline{Pdx + Qdy}$ is exact if and only if

$$\underline{\partial P / \partial y = \partial Q / \partial x}$$

examples determine if the following are exact and find f if so

$$\begin{aligned} & (xy^2 + y + e^x)dx + (x^2y + x)dy = df = \frac{\partial f}{\partial x}dx + \frac{\partial f}{\partial y}dy \\ & \quad \downarrow \partial/\partial y \quad \quad \quad \downarrow \partial/\partial x \\ & 2xy + 1 + 0 = 2xy + 1 \quad \checkmark \quad \underline{\text{yes, it is exact.}} \end{aligned}$$

$$\times \int \frac{\partial f}{\partial x} dx = \int xy^2 + y + e^x dx \Rightarrow f = \underline{\frac{1}{2}x^2y^2} + \underline{xy} + \underline{e^x} + \underline{c(y)}$$

$$\int \frac{\partial f}{\partial y} dy = \int x^2y + x dy \Rightarrow f = \underline{\frac{1}{2}x^2y^2} + \underline{xy} + \underline{k(x)}$$

$$f = \frac{1}{2}x^2y^2 + xy + e^x$$

$$\begin{aligned} & (2e^x + y^3)dx + 3y^2dy \\ & \quad \downarrow \partial/\partial y \rightarrow 3y^2 \quad \downarrow \partial/\partial x \rightarrow 0 \quad 3y^2 \neq 0 \rightarrow \underline{\text{not exact}} \end{aligned}$$

Solving differential forms

Given an equation of the form

$$P + Q \frac{dy}{dx} = 0$$

$$w = \underline{P(x,y)dx + Q(x,y)dy = 0}$$

$$P \frac{dx}{dy} + Q = 0$$

a "solution" is a relationship $\underline{F(x,y) = 0}$ between x and y .

If w is exact, $w = dF = 0 \Rightarrow \boxed{F(x,y) = C}$ solution

If w is not exact, then we need to introduce an integrating

factor μ s.t. $\mu w = \underline{\mu P dx + \mu Q dy}$ is exact.

Then $\mu w = dF = 0 \rightarrow \boxed{F(x,y) = C}$ solution

① separable

given $\dot{a}(x) \dot{b}(y) dx + \dot{c}(x) \dot{f}(y) dy = 0$,

then $\frac{\dot{a}(x)}{\dot{c}(x)} dx + \frac{\dot{f}(y)}{\dot{b}(y)} dy = 0$, $\mu = \frac{1}{\dot{c}(x) \dot{b}(y)}$

$$dF = \frac{\partial F}{\partial x} dx + \frac{\partial F}{\partial y} dy$$

example solve $\frac{\sin x}{y} dx + \frac{y}{\cos x} dy = 0$

extra exercise

② linear

$$\frac{dy}{dx} + ay + b = 0$$

$$\frac{dx}{dy} + fx + g = 0$$

given

$$dy + (a(x)y + b(x))dx = 0 \quad \text{or} \quad dx + (f(y)x + g(y))dy = 0$$

then

$$\mu = \exp\left(\int a dx\right) \quad \text{or} \quad \mu = \exp\left(\int f dy\right)$$

example

$$dy + (e^t y - e^t)dt = 0$$

extra exercise

③ homogeneous

if $P(\lambda x, \lambda y) = \lambda^n P(x, y)$ and $Q(\lambda x, \lambda y) = \lambda^n Q(x, y)$ for some n

e.g. $x^2 \rightarrow \lambda^2 x^2$ $x^2 + xy + y^2 \rightarrow \lambda^2 (x^2 + xy + y^2)$

then make the change of variables $y(x) = xv(x)$ ($dy = vdx + xdv$)

so $P(x, xv)dx + Q(x, xv)(vdx + xdv)$ is exact

$$= \frac{\partial F}{\partial x} dx + \frac{\partial F}{\partial v} dv \quad \text{for some } F(x, v)$$

example

solve $x^3 dx + xy^2 dy = 0$

$y = xv \rightarrow \underbrace{x^3 dx}_{\text{ord } 3} + \underbrace{xy^2 dy}_{\text{ord } 3} = 0$
 $x^3 dx + x(xv)^2 (x dv + v dx) = 0$

$$\underline{x^3 dx} + x^4 v^2 dv \quad \underline{x^3 v^3 dx} = 0$$

$$x^3(1+v^3)dx + x^4 v^2 dv = 0$$

separable !!

$$\frac{\partial F}{\partial x} dx + \frac{\partial F}{\partial y} dy = \frac{1}{x} dx + \frac{v^2}{1+v^3} dv = 0$$

$$\boxed{m = \log x + \frac{1}{3} \log(1 + \frac{y^3}{x^3})}$$

$$\frac{\partial F}{\partial x} = 1/x \rightarrow F(x, y) = \log x + c(y)$$

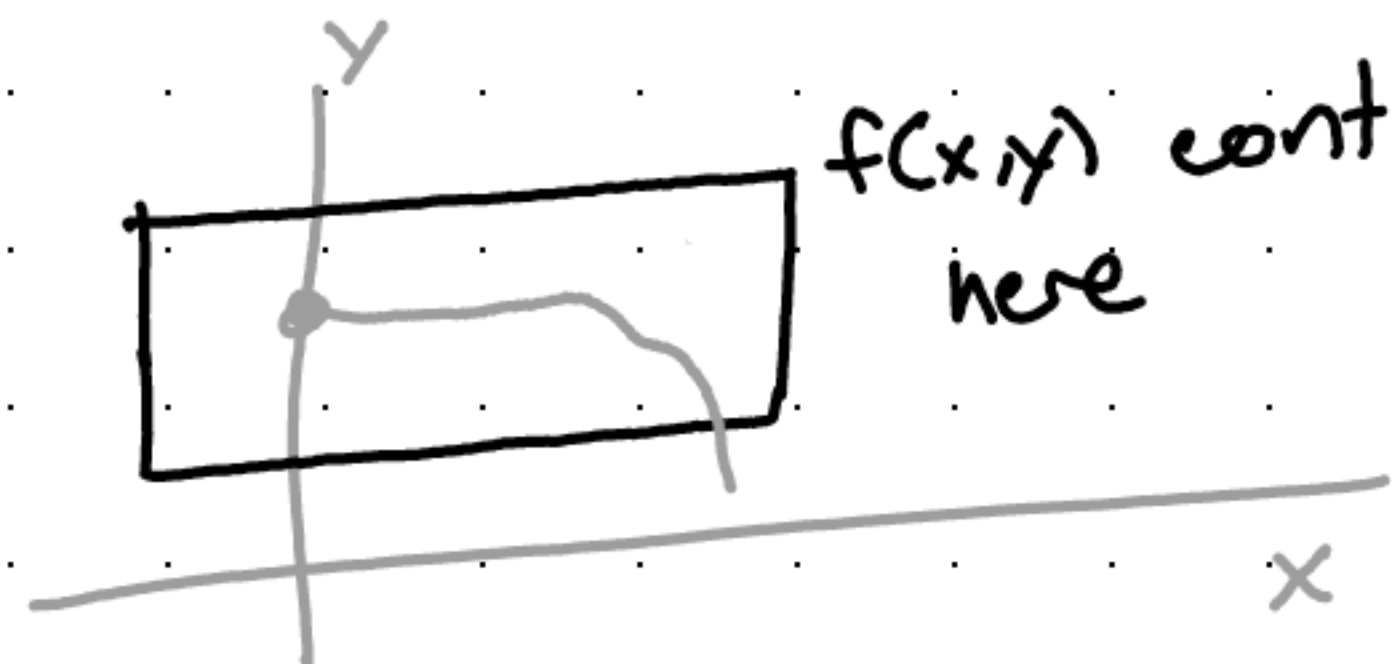
solution

$$\frac{\partial F}{\partial y} = \frac{v^2}{1+v^3} \rightarrow F(x, y) = \frac{1}{3} \log(1 + v^3) + k(x)$$

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Existence and Uniqueness

(well-posedness)



Consider the ODE $\frac{dy}{dx} = f(x,y)$ w/ an initial condition $y(0) = y_0$.

① if $f(x,y)$ is continuous on some rectangle containing $(0, y(0))$,

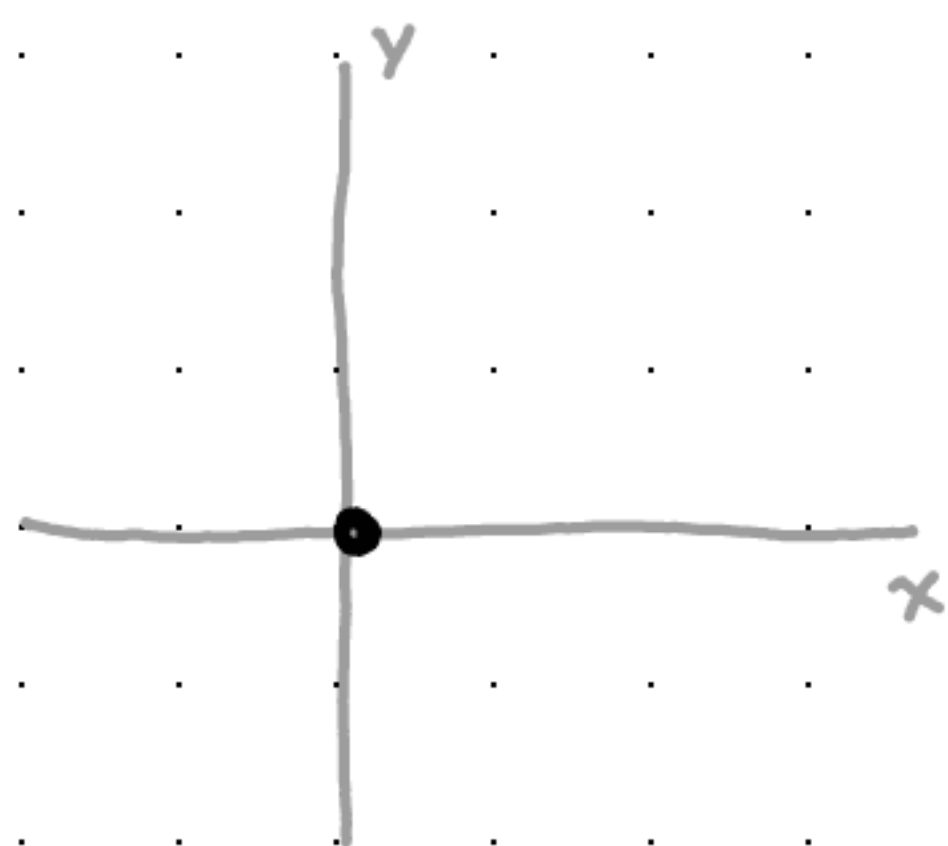
then a solution $y(x)$ exists as long as $(x, y(x))$ is in the rectangle

② if $\frac{\partial f}{\partial y}$ is continuous on some rectangle containing $(0, y(0))$,

then a solution $y(x)$ is unique

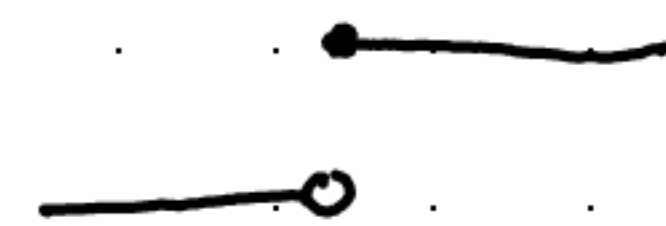
examples

• $y' = y^2, y(0) = 0$
 $f(x,y) = y^2$



$f(x,y)$ is cont ✓ exists ✓

look out for y/x



$$y' = y^2 \quad \int \frac{y'}{y^2} dx = \int 1 dx$$

$$-y^{-1} = \int \frac{dy}{y^2} = x + C$$

$$y(x) = \frac{1}{-x - C}$$

$$\frac{\partial f}{\partial y} = 2y \text{ cont} \rightarrow \text{unique sol} \checkmark$$

Non-Uniqueness (modified after discussion)

consider $y' = x\sqrt{|y|}$ w/ $y(0) = 0$

existence

the RHS $x\sqrt{|y|}$ is continuous in both x and y so a solution exists.

uniqueness

Using the fact that $|y| = \begin{cases} y, & \text{for } y \geq 0 \\ -y, & \text{for } y < 0 \end{cases}$

We calculate $\frac{\partial f}{\partial y} = \begin{cases} \frac{x}{2\sqrt{y}} & \text{for } y > 0 \\ \text{DNE} & \text{for } y = 0 \\ \frac{-x}{2\sqrt{-y}} & \text{for } y < 0 \end{cases}$

In particular, $\partial f / \partial y$ DNE (and is discont.) at $y = 0$.

So uniqueness is not guaranteed.

To show uniqueness fails, we construct 2 solutions.

① if $y(x) = 0$ then $y' = 0 = x\sqrt{|y|}$ and $y(0) = 0$.

So $y = 0$ is a solution.

② Assume $y > 0$ so that $|y| = y$. Then the eq is separable

so we can solve

$$y' = x\sqrt{y} \Leftrightarrow \frac{y'}{\sqrt{y}} = x$$

$$\Leftrightarrow \int \frac{dy}{\sqrt{y}} = \int x dx$$

$$\Leftrightarrow 2\sqrt{y} = \frac{1}{2}x^2 + C$$

$$\Leftrightarrow y = \left(C + \frac{1}{4}x^2\right)^2 \quad \leftarrow \text{different } C$$

$y(0) = 0$ then implies $C = 0$, so $y = \frac{1}{2}x^4$ is another solution.

Autonomous ODEs

$$\underline{y' = f(y)} \leftarrow \text{no dependence on } t,$$

pros: ① separable $\rightsquigarrow$ easily find solutions

② qualitatively easy

example: $y' = (y-1)^2 y$

fixed points: (equilibrium sols)

want solutions $y = c \iff y' = 0 \iff (y-1)^2 y = 0$

zeros: $y=1, y=0$

phase curve



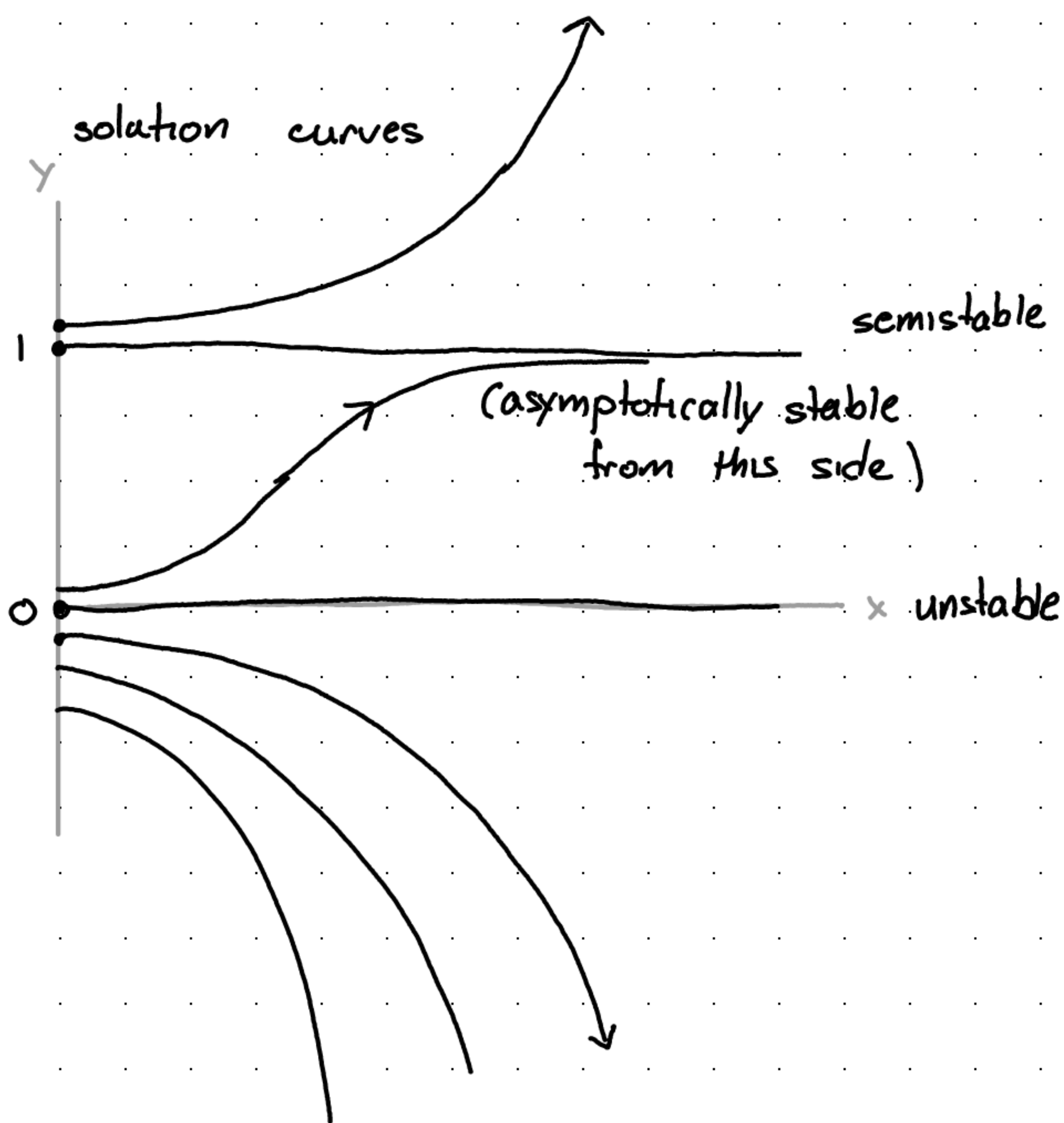
$$(y-1)^2 y = y' \\ + \quad + \quad +$$

$$(y-1)^2 y = y' \\ (-)^2 + \quad +$$

$$(y-1)^2 y = y' \\ (-)^2 - = -$$

stability

solution curves



extra examples

$$y' = \sin(y),$$

$$y' = \text{any polynomial}$$

2nd Order Linear ODEs

$$\downarrow \quad \downarrow \quad \downarrow$$
$$y'' + a(x)y' + b(x)y = c(x) \quad *$$

2nd order: b/c y''

linear: y_1, y_2 solutions $\Rightarrow y_1 + y_2$ is a solution

linearly independent solutions

given solutions y_1, y_2 to *, we know that

$$\underline{a_1 y_1 + a_2 y_2}$$

is a solution for all constants a_1, a_2

If y_1, y_2 are linearly independent, then all solutions can be written

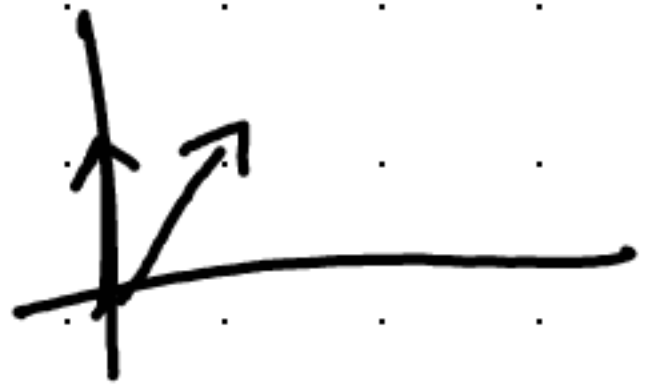
in this form. Then for all solns y , $y = a_1 y_1 + a_2 y_2$

example $y'' - 2y' + y = 0$ has solutions $y_1 = e^t$ and $y_2 = t e^t$

show that y_1, y_2 are linearly independent

the vectors $\begin{pmatrix} y_1 \\ y_1' \end{pmatrix}$ and $\begin{pmatrix} y_2 \\ y_2' \end{pmatrix}$ are linearly independent as vectors
(not parallel)

① $\begin{pmatrix} e^t \\ e^t \end{pmatrix} \quad \begin{pmatrix} t e^t \\ e^t + t e^t \end{pmatrix}$ choose specific t

$t=0 \quad \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 1 \end{pmatrix}$  not parallel $\Rightarrow$ linearly ind.

② Wronskian $\det \begin{pmatrix} y_1 & y_2 \\ y_1' & y_2' \end{pmatrix} \neq 0$ linearly independent

$$\det \begin{pmatrix} e^t & t e^t \\ e^t & e^t + t e^t \end{pmatrix} = \underbrace{e^t(e^t + t e^t) - t e^{2t}}_{t=0 \quad 1 \neq 0} = e^{2t} + \cancel{t e^{2t}} - t e^{2t} = e^{2t} \neq 0$$

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Constant Coefficients

example 1: $y'' - 9y' + 20y = 0$ w/ $y(0) = 0$ $y'(0) = 1$
homogeneous

guess: $y = e^{\lambda t}$

$$y' = \lambda e^{\lambda t}$$

$$y'' = \lambda^2 e^{\lambda t}$$

$$\lambda^2 e^{\lambda t} - 9\lambda e^{\lambda t} + 20e^{\lambda t} = 0$$

$$(\lambda^2 - 9\lambda + 20)e^{\lambda t} = 0$$

find roots of the char poly $\lambda_1, \lambda_2 \rightarrow e^{\lambda_1 t}, e^{\lambda_2 t}$

char poly: $\lambda^2 - 9\lambda + 20 = (\lambda - 4)(\lambda - 5) \rightarrow$ roots: 4, 5

solutions: e^{4t}, e^{5t} linearly independent $\checkmark$

general solution: $y = ae^{4t} + be^{5t}$ constants a, b .

example 2: $y'' - 6y' + 9y = 0$

char poly: $\lambda^2 - 6\lambda + 9 = (\lambda - 3)^2$

root: 3 w/ multiplicity 2

solutions: e^{3t} linearly independent

idea: make e^{3t} one step more complicated $\rightarrow te^{3t}$

general solution: $y = ae^{3t} + bte^{3t}$

example 3: $y'' - 2y' + 2 = 0$

char poly: $\lambda^2 - 2\lambda + 2$

roots: $\frac{2 \pm \sqrt{4-8}}{2} = \frac{2 \pm \sqrt{-4}}{2} = 1 \pm i$ complex roots.

solutions: $e^{(1+i)t}$ $e^{(1-i)t}$

general solution: $y = a e^{(1+i)t} + b e^{(1-i)t}$

$\swarrow$ real part $\swarrow$ imaginary part

Euler's id: $e^{i\theta} = \cos\theta + i\sin\theta$

expand out gen soln and Euler's identity

$y = e^t (a \cos t + b \sin t)$ (new constants a, b)

$\swarrow$ real part $\swarrow$ imaginary part

example: $3 \pm 2i \rightarrow$ gen soln $y = e^{3t} (a \cos 2t + b \sin 2t)$

Facts about (real) polynomials

① if $a+bi$ is a root then $a-bi$ is a root

② a deg n polynomial will always have n roots (counting multiplicity)

Inhomogeneous equations (undetermined coefficients)

example 1: $y'' - 9y' + 20y = \frac{x}{f(x)}$
linear ODE

idea: solve homogeneous equation: $y'' - 9y' + 20y = 0$

general solution: $y_h = ae^{4x} + be^{5x}$

find 1 particular solution to the full equation y_p

combine these $y = y_h + y_p$ is the general solution to the ODE

undetermined coefficients: informed guessing

RHS: deg 1 polynomial $\rightarrow$ guess $y_p = cx + d$

$$y_p' = c$$

$$y_p'' = 0$$

$$0 - 9c + 20(cx + d) = x$$

$$20d - 9/20 = 0$$

$$20cx + 20d - 9c = x \rightarrow c = 1/20$$

$$d = 9/400$$

$$y_p = \frac{x}{20} + \frac{9}{400}$$

$$\Rightarrow y = ae^{4x} + be^{5x} + \frac{x}{20} + \frac{9}{400}$$

example 2: $y'' - 9y' + 20y = \cos 3x$

guess $y_p = a \cos 3x + b \sin 3x$

example 3: $y'' - 9y' + 20y = \underline{x}e^x = (\text{deg 1 poly}) \cdot \text{exponential}$

guess $y_p = \underline{(ax+b)}e^x$

$$y'_p = ae^x + (ax+b)e^x = (a+b)e^x + axe^x$$

$$y''_p = ae^x + ae^x + (ax+b)e^x = (2a+b)e^x + axe^x$$

$$\underline{axe^x} + \underline{(2a+b)e^x} - \underline{9axe^x} - \underline{9(a+b)e^x} + \underline{20axe^x} + \underline{20be^x} = \underline{xe^x}$$

$$(a - 9a + 20a)xe^x = xe^x$$

$$12a = 1 \Rightarrow \underline{a = 1/12}$$

$$2a+b-9a-9b+20b =$$

$$-7a + 12b = 0$$

$$12b = 7/12 \Rightarrow \underline{b = 7/144}$$

$$\underline{y_p = \left(\frac{x}{12} + \frac{7}{144}\right)e^x}$$

Harmonic Oscillator

$$x'' + 2cx' + \omega_0^2 x = 0$$

char poly: $\lambda^2 + 2c\lambda + \omega_0^2$

roots: $\frac{-2c \pm \sqrt{4c^2 - 4\omega_0^2}}{2} = -c \pm \sqrt{c^2 - \omega_0^2}$

case 1: $c^2 - \omega_0^2 < 0$

case 2: $c^2 - \omega_0^2 > 0$

case 3: $c^2 - \omega_0^2 = 0$

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Midterm Tue 9:20 - 10:50

Secular Solutions

example 1: $y'' - 9y' + 20y = e^{4x}$ } in homogeneous
homogeneous part

$$y'' - 9y' + 20y = 0 \rightarrow \text{char poly: } \lambda^2 - 9\lambda + 20 = (\lambda - 4)(\lambda - 5)$$

roots: 4, 5

$$y_h = ae^{4x} + be^{5x} \quad \text{constants } a, b$$

undetermined coeffs: guess $y_p = cx e^{4x}$

$$y_p' = ce^{4x} + 4cxe^{4x} \quad y_p'' = 8ce^{4x} + 16cxe^{4x}$$

$$\cancel{16cxe^{4x}} + 8ce^{4x} - 9ce^{4x} - \cancel{36cxe^{4x}} + \cancel{20cxe^{4x}} = e^{4x}$$

$$-ce^{4x} = e^{4x} \Rightarrow c = -1$$

solution: $y = ae^{4x} + be^{5x} - xe^{4x}$

example 2: $y'' - 4y' + 4y = e^{2x}$

homogeneous: $\lambda^2 - 4\lambda + 4 = (\lambda - 2)^2$ roots 2 w/ mult 2

$$y_h = ae^{2x} + bxe^{2x}$$

particular: guess $y_p = cx^2 e^{2x}$

$$y_p' = 2cxe^{2x} + 2cx^2 e^{2x}$$

$$y_p'' = 2ce^{2x} + 8cxe^{2x} + 4cx^2 e^{2x}$$

$$2ce^{2x} + \cancel{8cxe^{2x}} + \cancel{4cx^2 e^{2x}} - \cancel{8cxe^{2x}} - \cancel{8cx^2 e^{2x}} + \cancel{4cx^2 e^{2x}} = e^{2x}$$

$$2ce^{2x} = e^{2x} \rightarrow c = 1/2$$

$$y = ae^{2x} + bxe^{2x} + \frac{1}{2}x^2 e^{2x}$$

Complex Formulation

example: $y'' - 4y' + 4y = e^t \sin t \rightarrow e^t \sin t = \underline{\text{Im}}(\underline{e^{(1+i)t}})$

easier: $y'' - 4y' + 4y = e^{(1+i)t}$

$$y_h = ae^{2t} + bte^{2t}$$

$$y_p = \underline{(c+di)e^{(1+i)t}}$$

$$y_p' = \underline{(c+di)(1+i)}e^{(1+i)t}$$

$$y_p'' = (c+di)(1+i)^2 e^{(1+i)t}$$

$$= (c+di)(1+2i-1)e^{(1+i)t}$$

$$= \underline{(c+di)(2i)}e^{(1+i)t}$$

$$(c+di) \cancel{e^{(1+i)t}} (2i - \cancel{4} - 4i + \cancel{4}) = \cancel{e^{(1+i)t}}$$

$$-2i(c+di) = 1$$

$$c+di = \frac{-1}{2i} = \frac{i}{2}$$

$$y_c = ae^{2t} + bte^{2t} + \frac{i}{2}e^{(1+i)t}$$

$$y_c = ae^{2t} + bte^{2t} + e^t \left(\underline{\frac{i}{2} \cos t} - \frac{1}{2} \sin t \right) \quad (\text{complex})$$

real solution:

$$y = ae^{2t} + bte^{2t} + \frac{1}{2}e^t \cos t$$

Variation of Parameters

example 1: find the general solution to

$$ty'' - (t+1)y' + y = t^2$$

given that $y_1 = e^t$ and $y_2 = t+1$ are homogeneous solutions

Idea: rewrite as $y'' + \underline{q(t)y' + r(t)y} = g(t)$

guess a solution of the form $y_p = v_1 y_1 + v_2 y_2$

$$\text{then } v_1' = \frac{-y_2 g}{w(t)} \quad \text{and} \quad v_2' = \frac{y_1 g}{w(t)}$$

where $w(t) = \det \begin{pmatrix} y_1 & y_2 \\ y_1' & y_2' \end{pmatrix}$ is the Wronskian

$$w(t) = \det \begin{pmatrix} e^t & t+1 \\ e^t & 1 \end{pmatrix} = e^t - (t+1)e^t = -te^t$$

$$y'' - \frac{(t+1)}{t} y' + \frac{y}{t} = t$$

$$y_p = v_1 e^t + v_2 (t+1)$$

$$v_1' = \frac{-(t+1)t}{-te^t} = (t+1)e^{-t}$$

$$v_1 = \int te^{-t} dt + \int e^{-t} dt$$

$$v_1 = -te^{-t} - 2e^{-t}$$

$$v_2' = \frac{e^t t}{-te^t} = -1$$

$$\underline{v_2 = -t}$$

$$y_p = v_1 y_1 + v_2 y_2$$

extra notes/problems

Paul's online math notes

example 2: find the general solution to $y'' - 2y' + y = \frac{e^t}{t^2+1}$

WARNING: don't guess:

$$\frac{ae^t}{bt^2+ct+d}$$

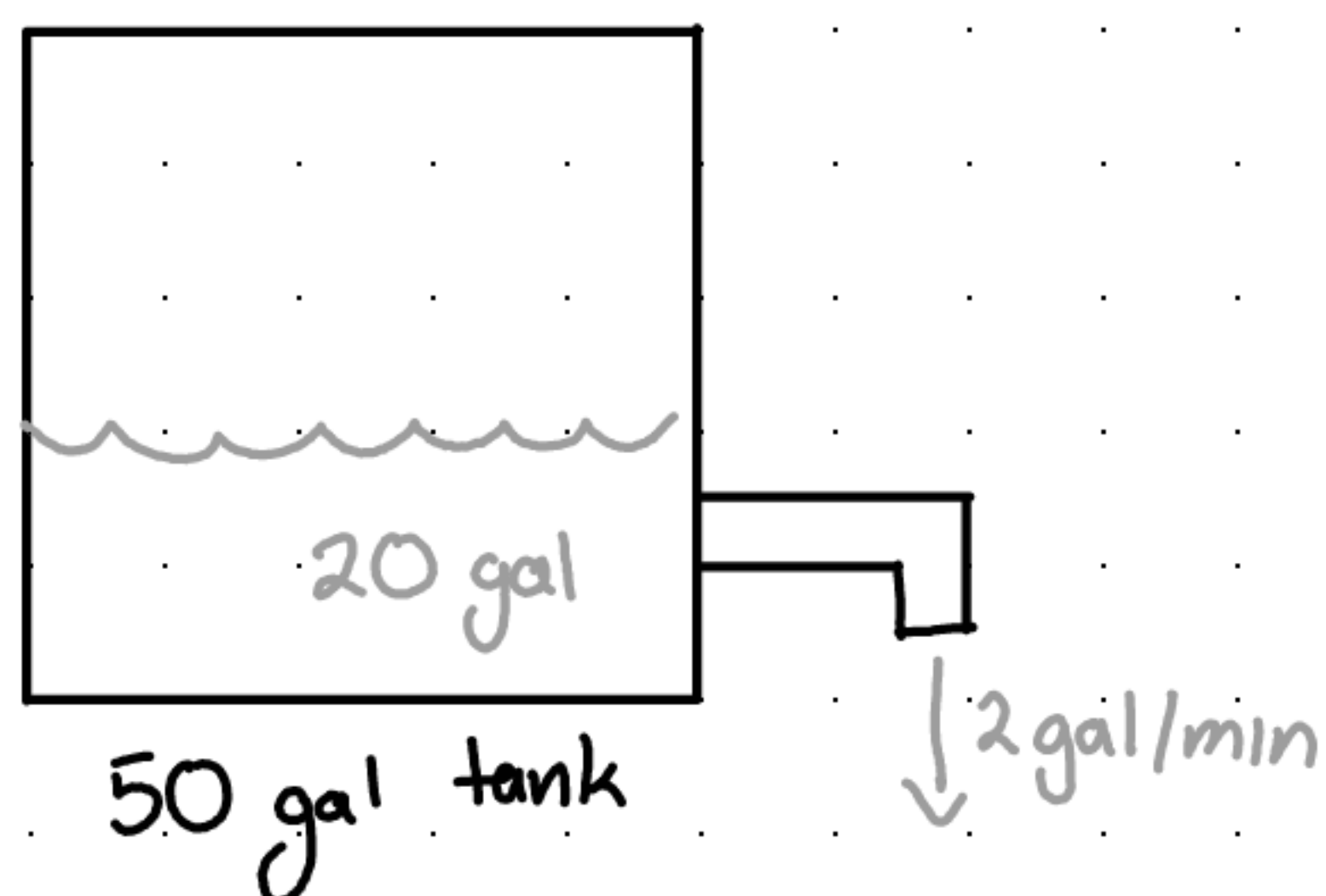
Extra time

Existence/Uniqueness

consider $y' = x\sqrt{|y|}$ w/ $y(0) = 0$. Does there exist a unique solution?

Mixing Problems

salt water @ 0.5 lb/gal
and 4 gal/min



What is the salt content when the tank is full?

8/28/25

Logistics: midterms are graded by Professor Roper and the TAs.

Should take ~1 week.

Note: problems 5+6 were intended to be challenging.

Eigenvalues + Eigenvectors

Given a matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, an eigenvalue is a constant λ s.t. there exists a vector $\vec{v} \neq \vec{0}$ which satisfies

$$A\vec{v} = \lambda\vec{v}.$$

The vector $\vec{v}$ is then an eigenvector of A w/ eigenvalue λ .

example find the eigenvalues/vectors of $A = \begin{bmatrix} 1 & 0 \\ 3 & -2 \end{bmatrix}$

$$\text{char poly: } \det \begin{bmatrix} 1-\lambda & 0 \\ 3 & -2-\lambda \end{bmatrix} = (1-\lambda)(-2-\lambda) - 3 \cdot 0 = -(1-\lambda)(2+\lambda)$$

roots: 1, -2 eigenvalues!

find $\vec{v}$ in the kernel of $A - \lambda I$

$$\lambda = 1 \quad \begin{bmatrix} 0 & 0 \\ 3 & -3 \end{bmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{matrix} 0a + 0b = 0 \\ 3a - 3b = 0 \end{matrix} \Leftrightarrow a = b \quad \begin{matrix} \text{eigenvector} \\ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \end{matrix}$$

$$\lambda = -2 \quad \begin{bmatrix} 3 & 0 \\ 3 & 0 \end{bmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{matrix} 3a = 0 \\ 3a = 0 \end{matrix} \quad a = 0 \quad \begin{matrix} \text{eigenvector} \\ \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{matrix}$$

example $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ real matrix

if a real matrix has eigenval $a+bi$ then $a-bi$ is an eigenval

$$\text{char poly: } \det \begin{bmatrix} -\lambda & 1 \\ -1 & -\lambda \end{bmatrix} = \lambda^2 + 1 = (\lambda - i)(\lambda + i)$$

eigenvals: $\pm i$

a, b are real numbers

$$\lambda = i \quad \begin{bmatrix} -i & 1 \\ -1 & -i \end{bmatrix} \begin{pmatrix} a+bi \\ c+di \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{pmatrix} -ia+b+c+di \\ -a-ib-ic+d \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$b+c=0 \quad -a+d=0$$

$$b=1 \quad c=-1 \quad a=1 \quad d=1$$

$$-a+d=0 \quad b+c=0$$

$$\vec{v} = \begin{pmatrix} 1+i \\ -1+i \end{pmatrix} \times i$$

$$\lambda = -i \quad \vec{v} = \begin{pmatrix} 1-i \\ -1-i \end{pmatrix}$$

idea: pick something easy

$$\begin{bmatrix} -i & 1 \\ -1 & -i \end{bmatrix} \begin{pmatrix} z \\ w \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$-iz + w = 0$$

$$z = 1$$

$$-i + w = 0$$

$$w = i$$

$$\lambda = i$$

$$\begin{pmatrix} 1 \\ i \end{pmatrix}$$

example: $A = \begin{bmatrix} 7 & 1 \\ -4 & 3 \end{bmatrix}$

$$A = \begin{bmatrix} a & 0 \\ 0 & a \end{bmatrix}$$

char poly: $\det \begin{pmatrix} 7-\lambda & 1 \\ -4 & 3-\lambda \end{pmatrix} = (7-\lambda)(3-\lambda) + 4$
 $= 21 - 10\lambda + \lambda^2 + 4 = 25 - 10\lambda + \lambda^2 = (\lambda - 5)^2$

$\lambda = 5$: $\begin{pmatrix} 2 & 1 \\ -4 & -2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{matrix} 2a + b = 0 & b = -2a \\ -4a - 2b = 0 & \Leftrightarrow -2(2a + b) = 0 \end{matrix}$

$a = 1 \quad b = -2$

$$\begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

example $A = \begin{bmatrix} -4 & -17 \\ 2 & 2 \end{bmatrix}$

again, pick something easy.

this one is extra!

Application to ODEs

eigenvals

$$\begin{matrix} 1 & w/ & \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ -2 & w/ & \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{matrix}$$

Eric!

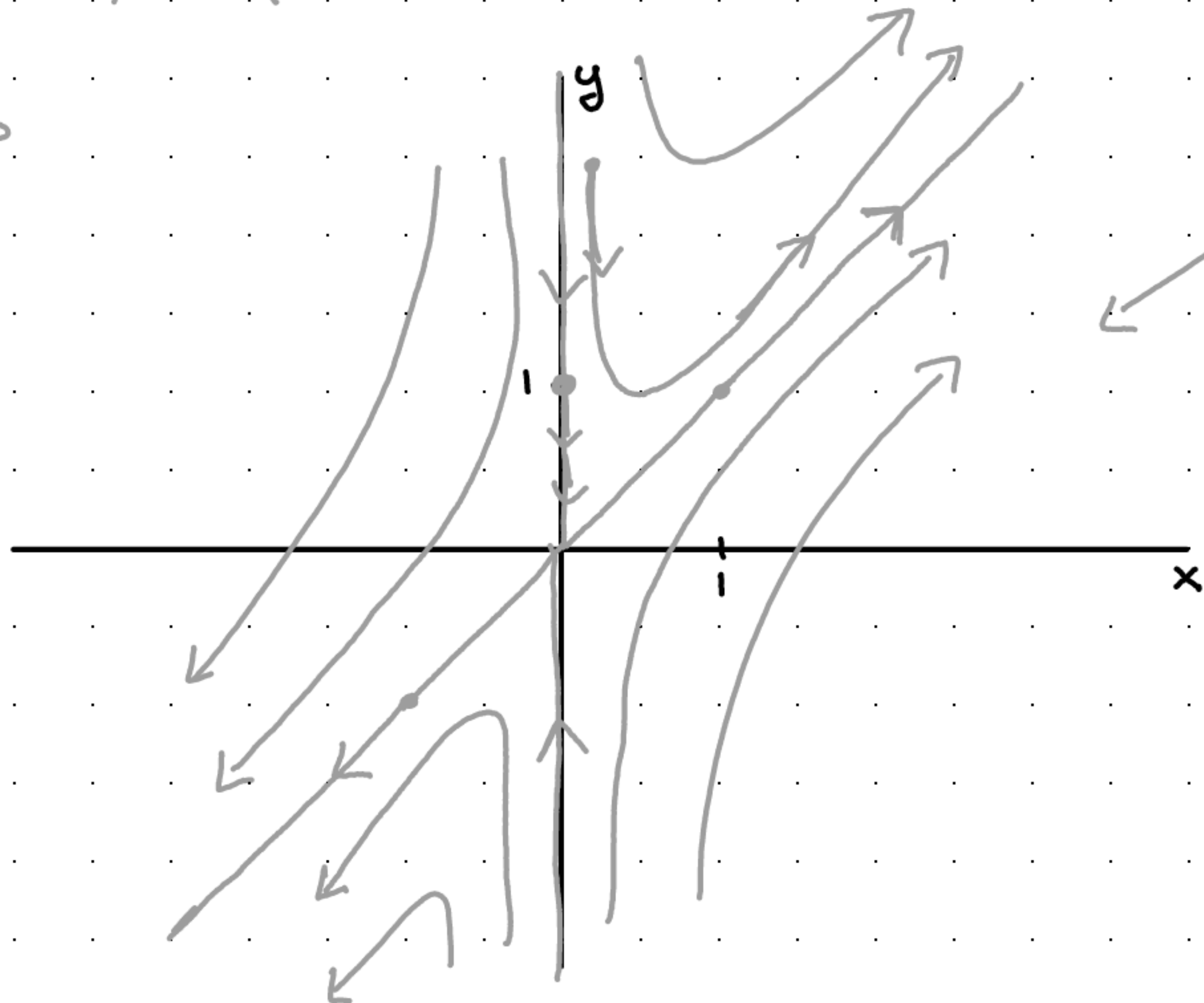
fun note: these kinds of diagrams are the main subject of math 134. It's a fun class!

$$\begin{cases} x' = x \\ y' = 3x - 2y \end{cases} \Leftrightarrow \begin{pmatrix} x \\ y \end{pmatrix}' = \begin{bmatrix} 1 & 0 \\ 3 & -2 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

if $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ then $\begin{pmatrix} x \\ y \end{pmatrix}' = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

if $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ then $\begin{pmatrix} x \\ y \end{pmatrix}' = -2 \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

so



generalized eigenvectors

$$(A - \lambda I) \vec{v} = \vec{0}$$

$$(A - \lambda I)^2 \vec{v} = \vec{0}$$

↑
generalized eigenvector

similar to constant coefficients, we may use these eigenvals/vectors to write the general solution

$e^{\lambda t} \vec{v}$... is a sol if $\lambda, \vec{v}$ eigenval/vec pair

general sol: $\vec{x} = a \underline{e^t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + b e^{-2t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

9/2/25

Logistics: midterms (probably) returned sometime this week

Same-sign real eigenvalues

Consider
$$\begin{cases} x' = 7x - y \\ y' = -x + 7y \end{cases}$$

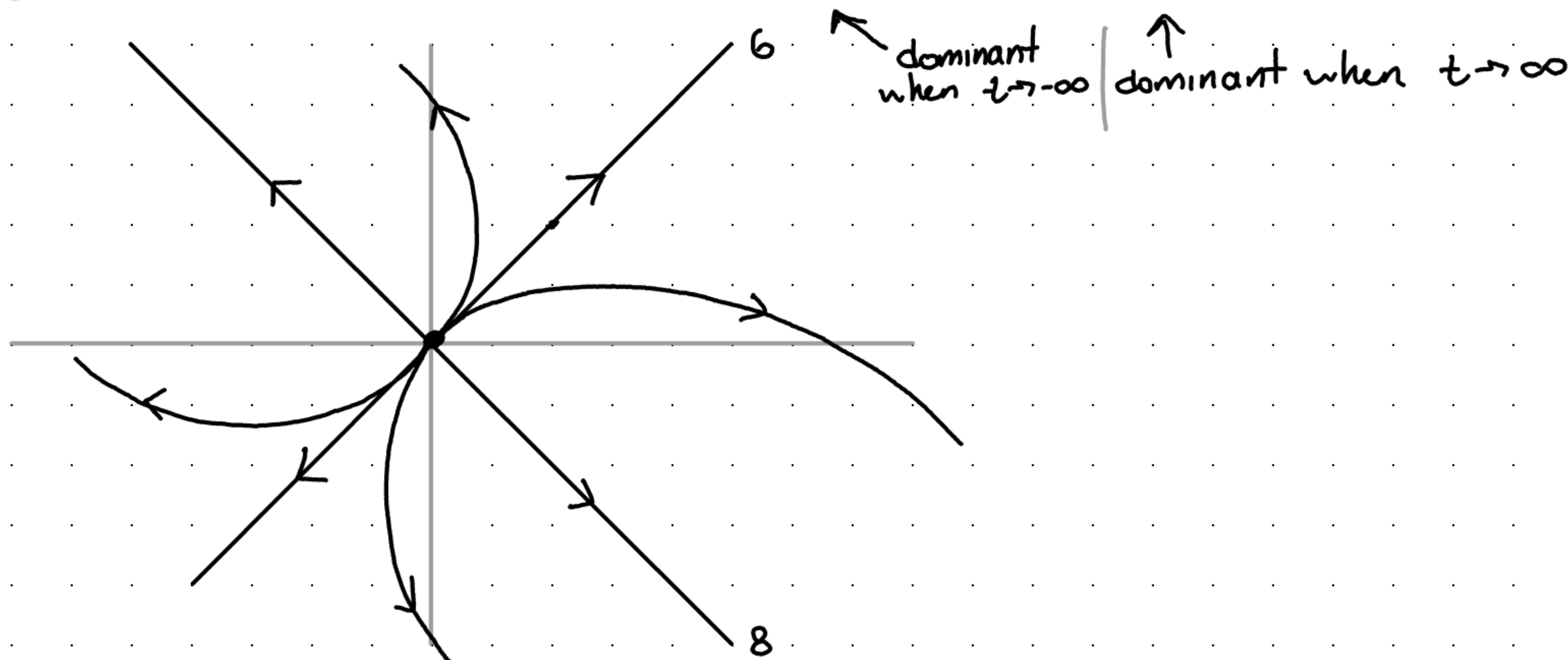
We will find the general solution and sketch.

$$\begin{aligned} \begin{bmatrix} 7 & -1 \\ -1 & 7 \end{bmatrix} &= A, \quad \det(A - \lambda I) = \det \begin{pmatrix} 7-\lambda & -1 \\ -1 & 7-\lambda \end{pmatrix} \\ &= (7-\lambda)^2 - 1 \\ &= 49 - 14\lambda + \lambda^2 - 1 \\ &= \lambda^2 - 14\lambda + 48 \\ &= (\lambda - 6)(\lambda - 8) \quad \text{eigenvals } 6, 8 \end{aligned}$$

$$\lambda = 6 \quad \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{matrix} a - b = 0 \\ -a + b = 0 \end{matrix} \rightarrow \underline{\begin{pmatrix} 1 \\ 1 \end{pmatrix}}$$

$$\lambda = 8 \quad \begin{pmatrix} -1 & -1 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{matrix} -a - b = 0 \\ -a - b = 0 \end{matrix} \rightarrow \underline{\begin{pmatrix} 1 \\ -1 \end{pmatrix}}$$

general solution: $\vec{x} = a e^{6t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + b e^{8t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$



Imaginary eigenvalues

$$\begin{cases} x' = y \\ y' = -x \end{cases}$$

$$A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

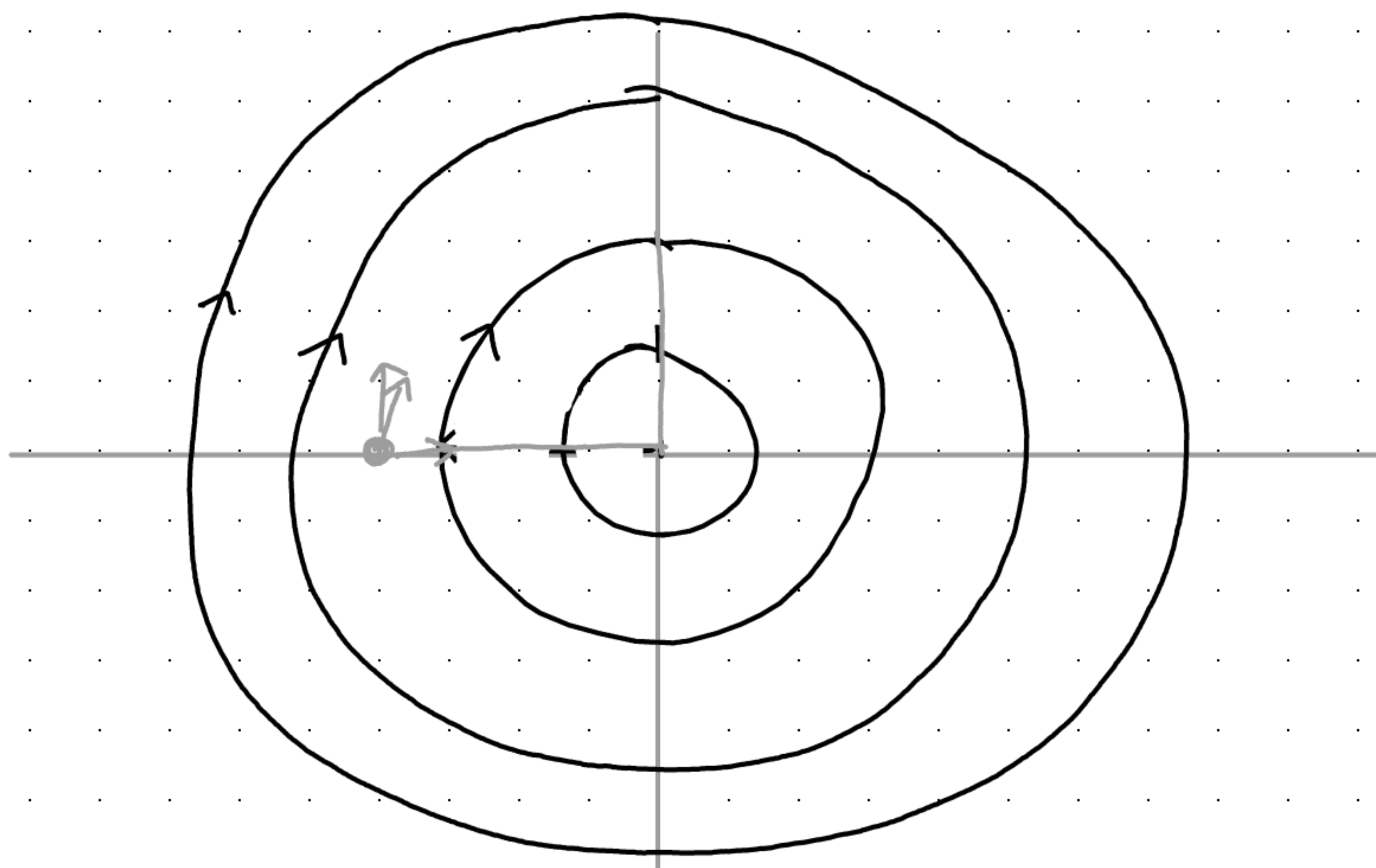
$$\begin{array}{l} i \quad \begin{pmatrix} -i \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} + i \begin{pmatrix} -1 \\ 0 \end{pmatrix} \\ -i \quad \begin{pmatrix} i \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} + i \begin{pmatrix} 1 \\ 0 \end{pmatrix} \end{array}$$

this has eigenvalues $\pm i$ w/ eigenvectors $\begin{pmatrix} \mp i \\ 1 \end{pmatrix}$

generally, eigenvalues $\underline{a \pm bi}$ w/ eigenvectors $\underline{\vec{v}_1 \pm i \vec{v}_2}$ will have solution

$$\underline{\vec{x}} = e^{at} \left((c_1 \cos bt + c_2 \sin bt) \vec{v}_1 + (-c_1 \sin bt + c_2 \cos bt) \vec{v}_2 \right)$$

$$\vec{x} = (c_1 \cos t + c_2 \sin t) \begin{pmatrix} 0 \\ 1 \end{pmatrix} + (-c_1 \sin t + c_2 \cos t) \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$



to find direction of rotation, check a point.

Complex eigenvalues

$$\begin{cases} x' = -4x - 17y \\ y' = 2x + 2y \end{cases}$$

eigenvalues

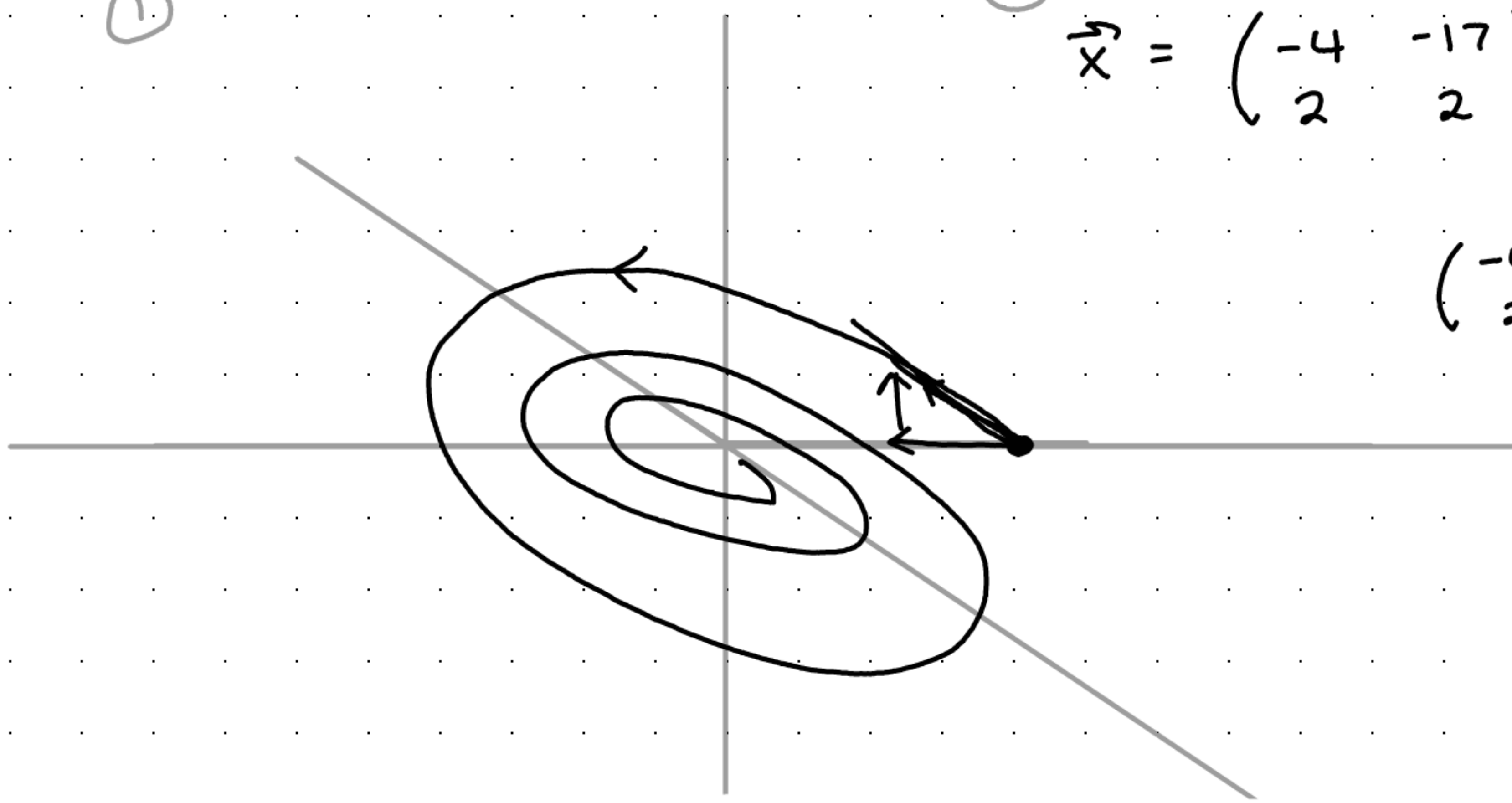
$$-1 \pm 5i \text{ w/ eigenvectors } \begin{pmatrix} -3 \\ 2 \end{pmatrix} \pm i \begin{pmatrix} 5 \\ 0 \end{pmatrix}$$

$$\vec{x} = e^{at} \left((c_1 \cos bt + c_2 \sin bt) \vec{v}_1 + (-c_1 \sin bt + c_2 \cos bt) \vec{v}_2 \right)$$

$$\vec{x} = \underbrace{e^{-t}}_{(1)} \left((c_1 \cos 5t + c_2 \sin 5t) \underbrace{\begin{pmatrix} -3 \\ 2 \end{pmatrix}}_{(2)} + (-c_1 \sin 5t + c_2 \cos 5t) \begin{pmatrix} 5 \\ 0 \end{pmatrix} \right)$$

$$\vec{x} = \begin{pmatrix} -4 & -17 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \quad (3)$$

$$\begin{pmatrix} -4 & -17 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -4 \\ 2 \end{pmatrix}$$



$$\begin{pmatrix} -4 & -17 \\ 2 & 2 \end{pmatrix}$$

$$\det \begin{pmatrix} -4-\lambda & -17 \\ 2 & 2-\lambda \end{pmatrix} = -8 + 4\lambda - 2\lambda + \lambda^2 + 34 = \lambda^2 + 2\lambda + 26$$

$$\lambda = \frac{-2 \pm \sqrt{4 - 104}}{2}$$

$$\boxed{\lambda = -1 \pm 5i} \rightarrow \begin{pmatrix} 17 \\ -3-5i \end{pmatrix}$$

$$\lambda = -1 + 5i$$

$$\begin{pmatrix} -4 - (-1+5i) & -17 \\ 2 & 2 - (-1+5i) \end{pmatrix} = \begin{pmatrix} -3-5i & -17 \\ 2 & 3-5i \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} -3-5i & -17 \\ 2 & 3-5i \end{pmatrix} \begin{pmatrix} 1 \\ w \end{pmatrix} \rightarrow$$

$$-3-5i - 17w \stackrel{=}{=} 0 \rightarrow w = \frac{-3-5i}{17}$$

$$2 + (3-5i) \frac{-3-5i}{17} = 0$$

$$34 + (3-5i)(-3-5i) = 34 - 9 + 15i - 15i - 25 = 0$$

9/4/25

Complex eigenvalues

$$\begin{cases} x' = 3x - 13y \\ y' = 5x + y \end{cases} \quad \text{w/} \quad \begin{cases} x(0) = 3 \\ y(0) = -10 \end{cases}$$

$$\vec{x}' = \begin{pmatrix} 3 & -13 \\ 5 & 1 \end{pmatrix} \vec{x}$$

$$\det \begin{pmatrix} 3-\lambda & -13 \\ 5 & 1-\lambda \end{pmatrix} = (3-\lambda)(1-\lambda) + 65 = 68 - 4\lambda + \lambda^2$$

$$\text{eigenvals: } \lambda = \frac{4 \pm \sqrt{16 - 272}}{2} = \frac{4 \pm \sqrt{-256}}{2} = 2 \pm 8i$$

$$\lambda = 2 - 8i$$

$$\begin{pmatrix} 1+8i & -13 \\ 5 & -1+8i \end{pmatrix} \begin{pmatrix} 1 \\ w \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$1+8i - 13w = 0$$

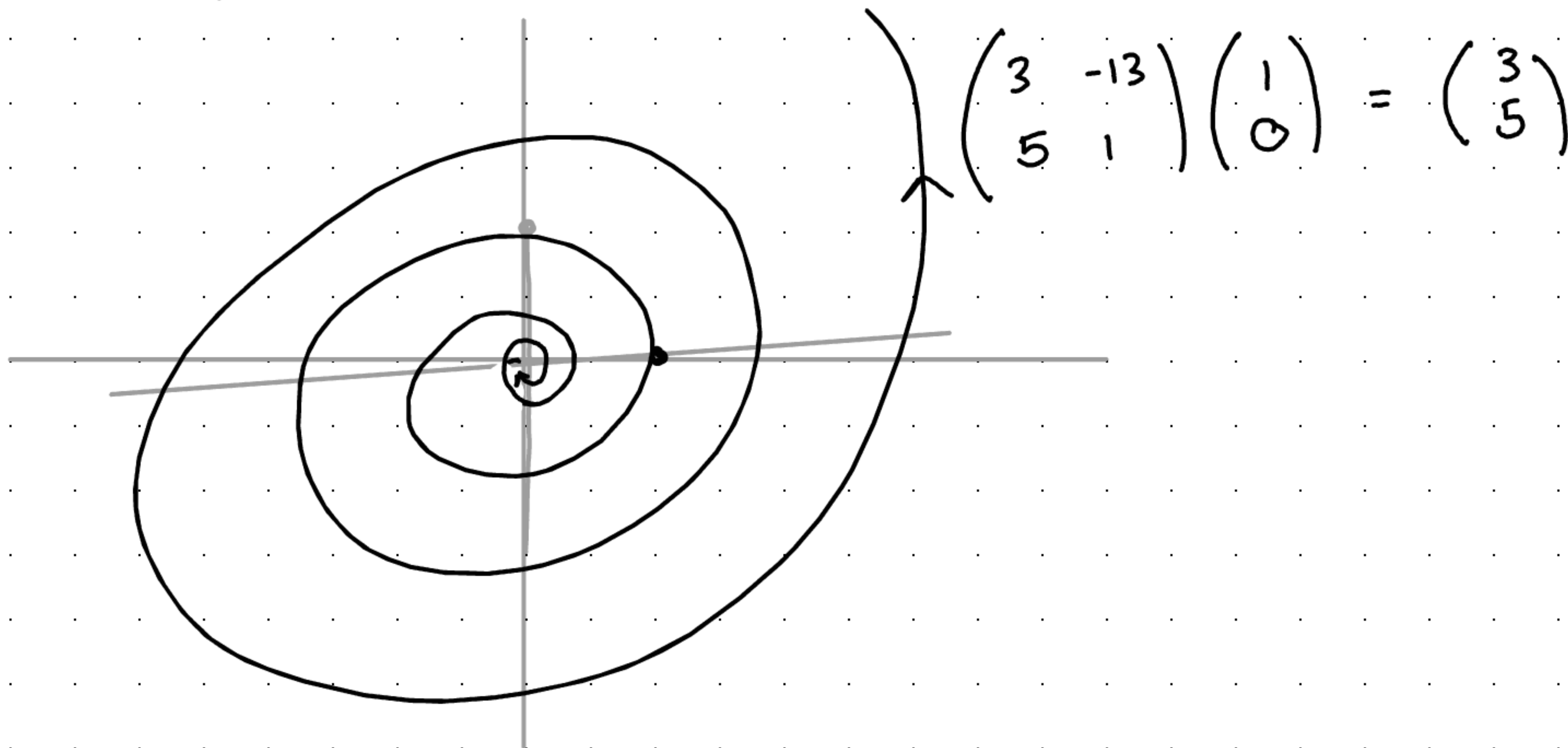
$$w = \frac{1}{13} (1+8i)$$

recommend checking 2nd row

$$\text{eigenvector: } \begin{pmatrix} 13 \\ 1+8i \end{pmatrix} = \begin{pmatrix} 13 \\ 1 \end{pmatrix} + i \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$2+8i \rightsquigarrow \begin{pmatrix} 13 \\ 1 \end{pmatrix} - i \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\vec{x} = e^{2t} \left((c_1 \cos 8t + c_2 \sin 8t) \begin{pmatrix} 13 \\ 1 \end{pmatrix} - (-c_1 \sin 8t + c_2 \cos 8t) \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right)$$



Repeated Eigenvalues - 2 eigenvector ($a_m = 2, g_m = 2$)

$$\begin{cases} x' = 4x \\ y' = 4y \end{cases}$$

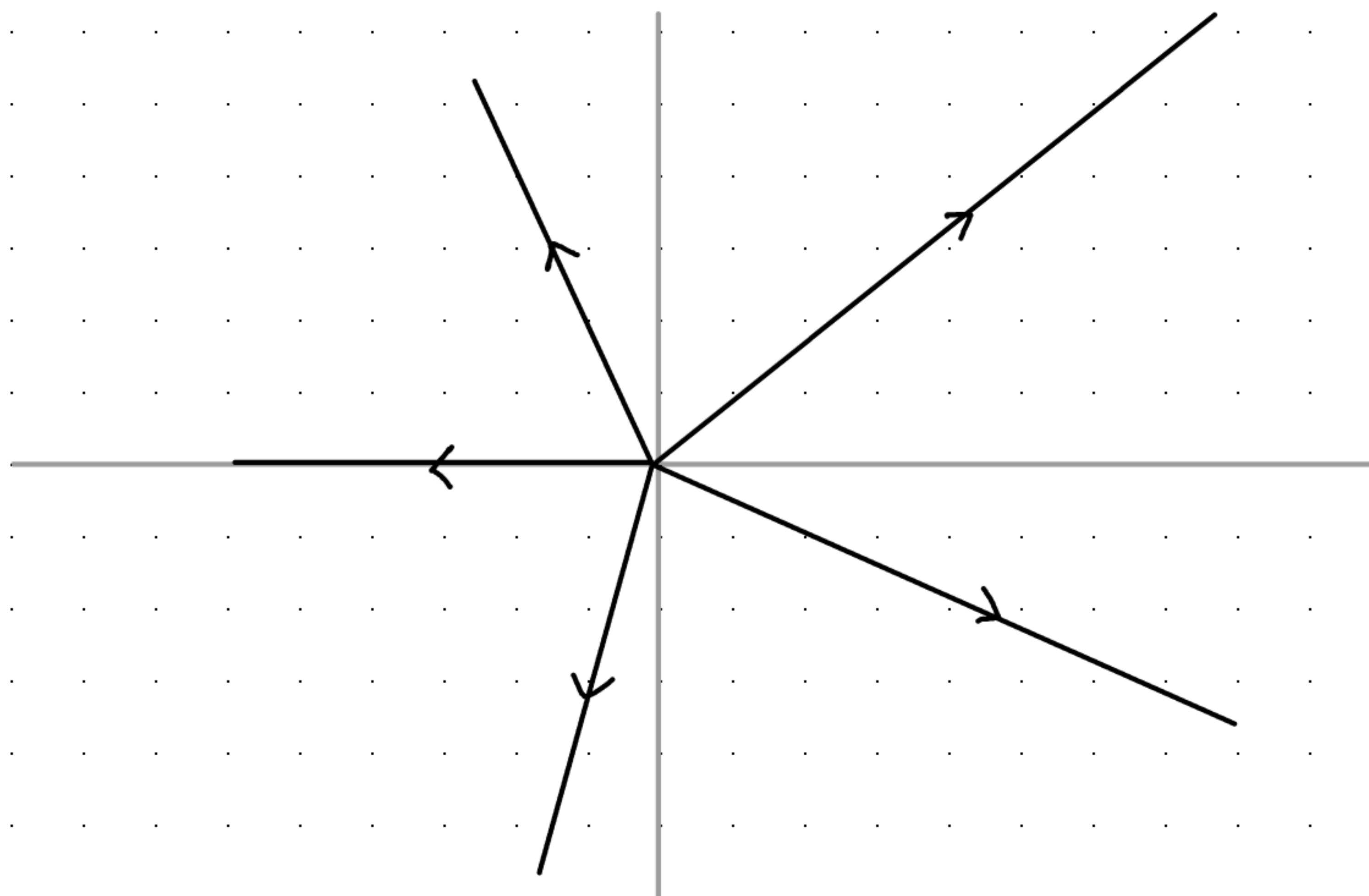
← this is the only such example

$$\begin{pmatrix} 4 & 0 \\ 0 & 4 \end{pmatrix}, \quad \det \begin{pmatrix} 4-\lambda & 0 \\ 0 & 4-\lambda \end{pmatrix} = (4-\lambda)^2 \quad \text{eigenvals: } 4$$

$$\lambda = 4 \quad \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\text{general sol: } \vec{x} = a e^{4t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + b e^{4t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\vec{x} = e^{4t} \begin{pmatrix} a \\ b \end{pmatrix}$$



Repeated Eigenvalues - 1 eigenvector

$$(a_m=2, g_m=1)$$

$$\begin{cases} x' = 7x + y \\ y' = -4x + 3y \end{cases}$$

$$\begin{pmatrix} 7 & 1 \\ -4 & 3 \end{pmatrix}$$

eigenval 5

$$\det \begin{pmatrix} 7-\lambda & 1 \\ -4 & 3-\lambda \end{pmatrix} = 21 - 10\lambda + \lambda^2 + 4 = (\lambda-5)^2$$

$$\begin{pmatrix} 2 & 1 \\ -4 & -2 \end{pmatrix} \begin{pmatrix} 1 \\ -2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\underline{\underline{\begin{pmatrix} 1 \\ -2 \end{pmatrix}}}$$

to find general solution:

① pick any non-eigenvector

$\vec{w}$

generalized eigenvector

$$\vec{w} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$(A - 5I)^2 \vec{w} = \vec{0}$$

② calculate $\vec{v}_1 = (A - \lambda I) \vec{w}$ (which is an eigenvector)

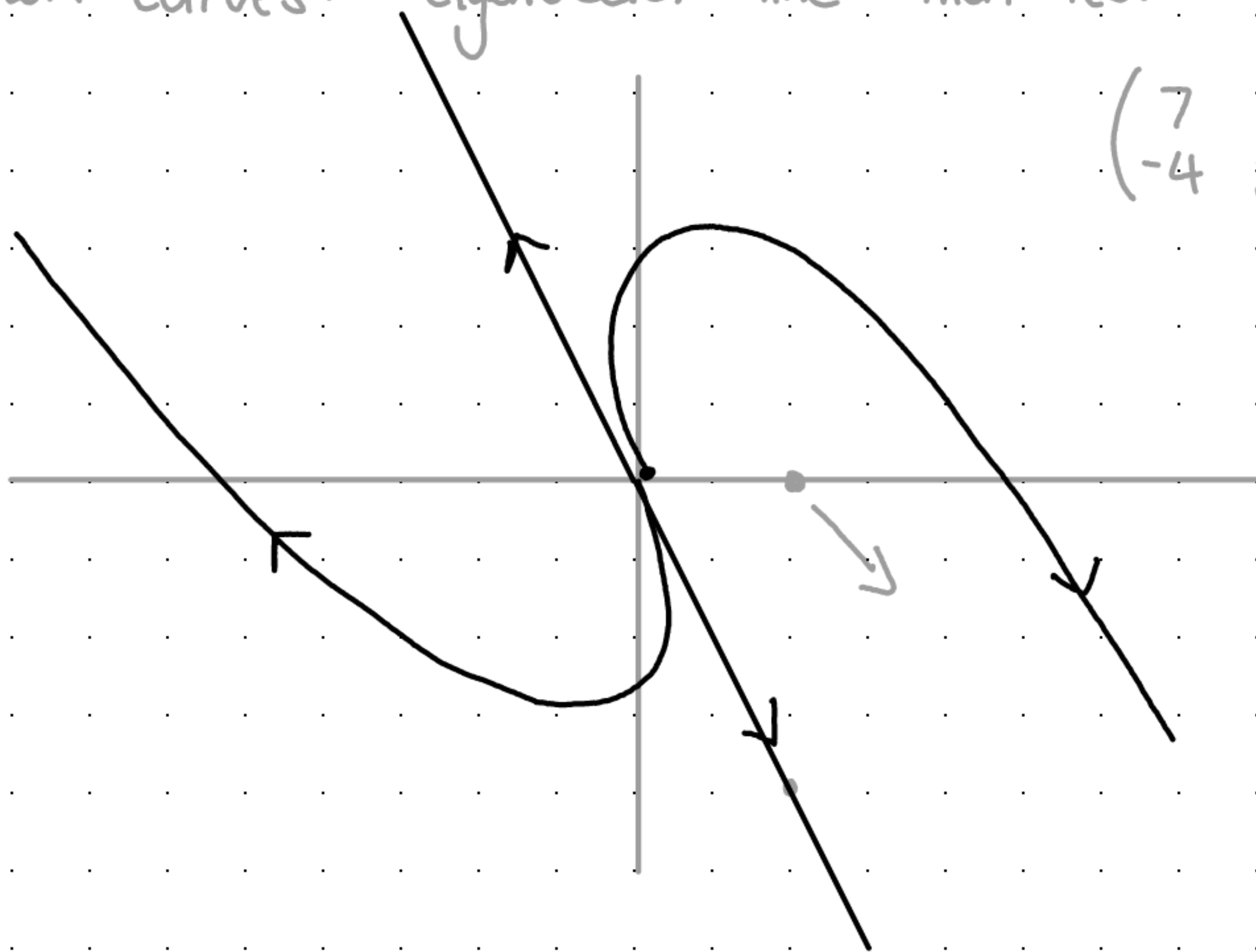
$$\begin{pmatrix} 2 & 1 \\ -4 & -2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ -4 \end{pmatrix} = \vec{v}_1$$

③ general solution: $\vec{x} = ae^{\lambda t} \vec{v}_1 + be^{\lambda t} (t \vec{v}_1 + \vec{w})$

$$\vec{x} = ae^{5t} \begin{pmatrix} 2 \\ -4 \end{pmatrix} + be^{5t} \left(t \begin{pmatrix} 2 \\ -4 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right)$$

④ solution curves: eigenvector line then test

$$\begin{pmatrix} 7 & 1 \\ -4 & 3 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 7 \\ -4 \end{pmatrix}$$



Repeated eigenvalue (again)

$$\begin{cases} x' = -6x + 9y \\ y' = -x - 12y \end{cases}$$

Bonus: non-homogeneous systems (non-examinable unless otherwise stated).

$$\vec{x}' = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix} \vec{x} + t \begin{pmatrix} 2 \\ -4 \end{pmatrix}$$

idea: undetermined coefficients, but vectors.

homogeneous: $\det \begin{pmatrix} 1-\lambda & 2 \\ 3 & 2-\lambda \end{pmatrix} = 2-3\lambda+\lambda^2-6 = \lambda^2-3\lambda-4$
 $= (\lambda-4)(\lambda+1)$

$$\lambda=4 \quad \begin{pmatrix} -3 & 2 \\ 3 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 2 \\ 3 \end{pmatrix} \quad \vec{x}_h = ae^{4t} \begin{pmatrix} 2 \\ 3 \end{pmatrix} + be^{-t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\lambda=-1 \quad \begin{pmatrix} 2 & 2 \\ 3 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

particular: $\vec{x}_p = \vec{v}t + \vec{u}$

$$\vec{x}' - A\vec{x} = t \begin{pmatrix} 2 \\ -4 \end{pmatrix}$$

$$\underline{\vec{v}} - \underline{A\vec{v}}t - \underline{A\vec{u}} = \underline{t \begin{pmatrix} 2 \\ -4 \end{pmatrix}}$$

$$-A\vec{v} = \begin{pmatrix} 2 \\ -4 \end{pmatrix}$$

$$\vec{v} = A\vec{u}$$

$$-A^2\vec{u} = \begin{pmatrix} 2 \\ -4 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix}$$

$$A^2 = \begin{pmatrix} 7 & 6 \\ 9 & 10 \end{pmatrix}$$

$$A^2\vec{u} = \begin{pmatrix} -2 \\ 4 \end{pmatrix} \rightarrow \begin{pmatrix} 7 & 6 \\ 9 & 10 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} -2 \\ 4 \end{pmatrix} \rightarrow \vec{u} = \frac{1}{8} \begin{pmatrix} -22 \\ 23 \end{pmatrix}$$

$$\text{so } \vec{x}_p = \frac{t}{8} A \begin{pmatrix} -22 \\ 23 \end{pmatrix} + \frac{1}{8} \begin{pmatrix} -22 \\ 23 \end{pmatrix}$$

general: $\vec{x} = ae^{4t} \begin{pmatrix} 2 \\ 3 \end{pmatrix} + be^{-t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} + \frac{t}{8} A \begin{pmatrix} -22 \\ 23 \end{pmatrix} + \frac{1}{8} \begin{pmatrix} -22 \\ 23 \end{pmatrix}$

Bonus: higher order constant coefficients

example: $y'''' - y''' + y'' - y' = x$ (challenging)

extra: $y''' - 3y'' - y' + 3y = e^{2x}$

9/9/25

- ① systems of linear ODEs Ⓢ
- ② linear first order ODE Ⓢ
- ③ modelling / related rates Ⓢ
- ④ constant coefficients Ⓢ + variation of parameters
- ⑤ reduction of order Ⓢ complete
- ⑥ existence/uniqueness Ⓢ see notes from 8/14
- ⑦ homogeneous equations Ⓢ
- ⑧ complex eigenvalues Ⓢ complete

① systems of linear ODEs

$$\begin{cases} x' = -6x + 9y \\ y' = -x - 12y \end{cases}$$

w/

$$x(0) = 1$$

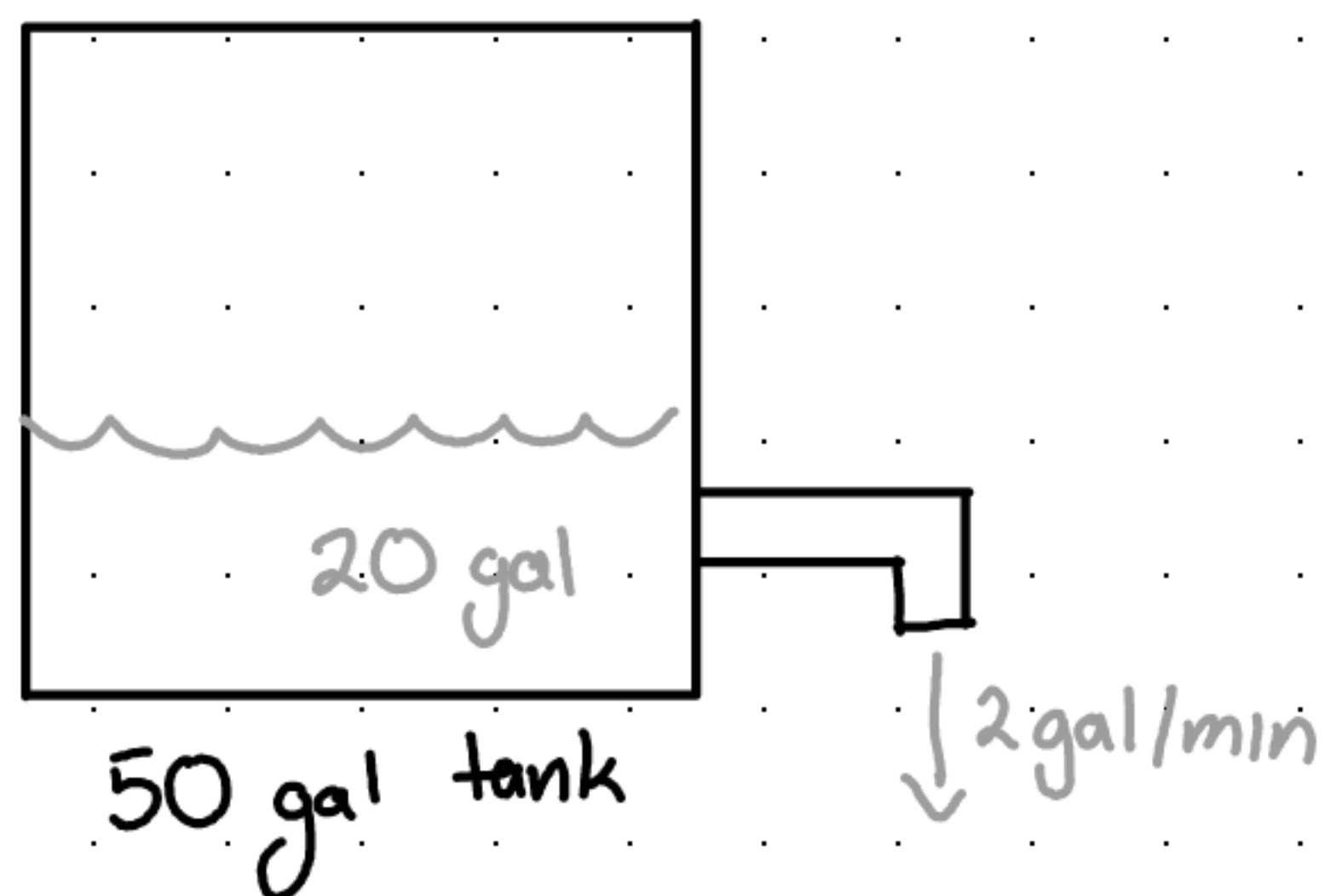
$$y(0) = 1$$

② linear first order ODE

solve $\cos(x) y' + \sin(x) y = 2 \cos^3(x) \sin(x) - 1$ $y(0) = 5$

③ related rates

salt water @ 0.5 lb/gal
and 4 gal/min



What is the salt content when the tank is full?

④ Constant coefficients

find the general solution to $y'' - 2y' + y = \frac{e^t}{t^2 + 1}$

recall: $y_p = v_1 y_1 + v_2 y_2$ w/

$$v_1' = \frac{-y_2 g}{w(t)} \quad \text{and} \quad v_2' = \frac{y_1 g}{w(t)}$$

where $w(t) = \det \begin{pmatrix} y_1 & y_2 \\ y_1' & y_2' \end{pmatrix}$ is the Wronskian

⑤ Reduction of Order

find the general solution to $\checkmark$
 $2t^2 y'' + ty' - 3y = 0, t > 0$

given that $y_1 = t^{-1}$ is a solution

hint: guess $y_2 = vy_1$

$$y_2 = \frac{v}{t} \quad \leftarrow vy_1$$

$$y_2' = \frac{v'}{t} - \frac{v}{t^2}$$

$$y_2'' = \frac{v''}{t} - 2\frac{v'}{t^2} + 2\frac{v}{t^3}$$

$$4\cancel{\frac{v}{t}} - 4v' + 2tv'' + v' - \cancel{\frac{v}{t}} - 3\cancel{\frac{v}{t}} = 0$$

$$\underline{2tv'' - 3v' = 0}$$

$$w = v'$$

$$2tw' - 3w = 0$$

$$\frac{w'}{w} = \frac{3}{2} \frac{1}{t}$$

$$\int \frac{dw}{w} = \frac{3}{2} \int \frac{1}{t} dt$$

$$\ln w = \frac{3}{2} \ln t + c$$

$$w = c t^{3/2}$$

$$v' = c t^{3/2}$$

$$\boxed{v = c' t^{5/2} + b}$$

$$y_2 = c t^{3/2} + b t^{-1}$$

⑥ existence/uniqueness

consider $y' = x\sqrt{|y|}$ w/ $y(0) = 0$

does a sol exist? Is it unique?

⑦ homogeneous equations

solve $xyy' + 4x^2 + y^2 = 0$ w/ $y(2) = -7$

⑧ Complex eigenvalues

$$\begin{cases} x' = 3x - 13y \\ y' = 5x + y \end{cases} \quad \vec{x}(0) = \begin{pmatrix} 3 \\ -10 \end{pmatrix} \quad \vec{x} = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\vec{x}' = \underbrace{\begin{pmatrix} 3 & -13 \\ 5 & 1 \end{pmatrix}}_A \vec{x} \quad \leftarrow \text{real}$$

$$\det(A - \lambda I) = \det \begin{pmatrix} 3-\lambda & -13 \\ 5 & 1-\lambda \end{pmatrix} = (3-\lambda)(1-\lambda) + 65$$

$$= 3 - 4\lambda + \lambda^2 + 65 = \lambda^2 - 4\lambda + 68$$

$$\lambda = \frac{4 \pm \sqrt{16 - 272}}{2}$$

$$= \frac{4 \pm \sqrt{-256}}{2}$$

$$= 2 \pm 8i$$

$$\lambda = 2 - 8i \quad \begin{pmatrix} 1+8i & -13 \\ 5 & -1+8i \end{pmatrix} \begin{pmatrix} 1 \\ w \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad \begin{matrix} \text{complex} \\ \downarrow \end{matrix}$$

$$1+8i - 13w = 0$$

$$5 + (-1+8i)w = 0 \quad \checkmark$$

$$\vec{v} = \begin{pmatrix} 13 \\ 1+8i \end{pmatrix} = \begin{pmatrix} 13 \\ 1 \end{pmatrix} + i \begin{pmatrix} 0 \\ 8 \end{pmatrix}$$

$$\underline{\lambda = 2+8i} \rightarrow \vec{u} = \begin{pmatrix} 13 \\ 1 \end{pmatrix} - i \begin{pmatrix} 0 \\ 8 \end{pmatrix}$$

$$\vec{x} = e^{at} \left((c_1 \cos bt + c_2 \sin bt) \vec{v}_1 + (-c_1 \sin bt + c_2 \cos bt) \vec{v}_2 \right)$$

$$\vec{x} = e^{2t} \left((c_1 \cos 8t + c_2 \sin 8t) \begin{pmatrix} 13 \\ 1 \end{pmatrix} + (-c_1 \sin 8t + c_2 \cos 8t) \begin{pmatrix} 0 \\ -8 \end{pmatrix} \right)$$

$$\vec{x} = e^{2t} \left(\underbrace{(c_1 \cos 8t + c_2 \sin 8t)}_{\textcircled{1}} \underbrace{\begin{pmatrix} 13 \\ 1 \end{pmatrix}}_{\textcircled{2}} + \underbrace{(-c_1 \sin 8t + c_2 \cos 8t)}_{\textcircled{3}} \underbrace{\begin{pmatrix} 0 \\ -8 \end{pmatrix}}_{\textcircled{4}} \right)$$

$$\begin{pmatrix} 3 & -13 \\ 5 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ 5 \end{pmatrix}$$

$\textcircled{3}$

