

§1 Root systems and semisimple Lie algebras,
 • sl_2 and \mathfrak{sl}_3

§2 Root datum and reductive groups
 • SL_2 and PGL_2

§1 Local, classify semisimple Lie algebras and their irreducible representations,
 we work / & in this section.

Recall - $sl_n = \ker(\det)$
 - $d(\det)|_I = fr$

$$\text{so } sl_n = \ker(fr)$$

$[sl_2]$ we have a basis e, f, h
 $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

Consider first its adjoint representation
 $\text{ad}: sl_2 \longrightarrow gl(sl_2)$

$$\left. \begin{array}{l} [h, e] = 2e \\ [h, f] = -2f \\ [h, h] = 0 \end{array} \right\} \text{so } \text{ad}(h) \text{ acts } \underbrace{\text{diagonally}}_{\text{semisimply}}, \text{ and } e, f, h \text{ is an eigenbasis of } \text{ad}(h).$$

sl_2 is semisimple ($[sl_2, sl_2] = sl_2$), so h is diagonalizable on all f.d. reps (Jordan decomposition)

Let V be a fd irreducible repr. of sl_2

$$\text{Then } V = \bigoplus_{\alpha \in \mathbb{C}} V_\alpha, \quad V_\alpha = \{v \in V \mid h v = \alpha v\}$$

By ad(h) calculation, e.g., $V_\alpha \xrightarrow{\alpha} V_{\alpha+2}$
 f.e., $V_\alpha \xrightarrow{\alpha} V_{\alpha-2}$

Fact. The h -eigenvalues of V are integers.

Let $n \in \mathbb{N}$ maximal s.t. $V_n \neq 0$. Let $v \in V_n$, then

Let $n \in \mathbb{N}$ maximal s.t. $V_n \neq 0$, let $v \in V_n$, then

$\{v, fv, \dots, f^n v\}$ is a basis for V .

$$0 \xrightarrow{P} V_{-n} \xleftarrow{P} V_{-n+2} \xleftarrow{P} \dots \xrightarrow{P} V_{n-2} \xleftarrow{P} V_n \xrightarrow{P} 0$$

n is called the highest weight of V

Thm. fd irrs. of sl_2 are uniquely and totally classified by their highest weight.

Exifpr. is as follows. Let $SL(\mathbb{C})$ act on $\mathbb{C}[[x,y]]_n$, the degree n homogeneous polynomials. To the funcy, there are global sections of the line bundle $\mathcal{O}(n)$ on $SL_2(\mathbb{C})/\mathcal{B}(\mathbb{C})$ where $\mathcal{B} \subseteq SL_2$ is the set of upper triangular matrices

\mathfrak{sl}_3

Let $\mathfrak{g} = \mathfrak{sl}_3$. This is, again, semisimple.

3 embeddings $\mathfrak{sl}_2 \hookrightarrow \mathfrak{g}$

$$\begin{pmatrix} * & & \\ & * & \\ & & * \end{pmatrix} \quad h_{12} \quad e_{12} \quad f_{21}$$

$$\begin{pmatrix} * & & \\ & * & \\ & & * \end{pmatrix} \quad h_{13} \quad e_{13} \quad f_{21}$$

$$\begin{pmatrix} & & \\ & * & \\ & & * \end{pmatrix} \quad h_{23} \quad e_{23} \quad f_{32}$$

which h do we pick?

Def. $\mathfrak{h} \subseteq \mathfrak{g}$ is the subalgebra of diagonal matrices

Rmk. \mathfrak{h} is a small abelian subalgebra

$\text{ad}(h_{ij})$ will again be diagonal, result.

$[h_i, h_j] = 0$, so there are simultaneously diagonal

Let v be an eigenvector of \mathfrak{h} . Then

$$h \xrightarrow{\text{ } \mathbb{C}} \mathbb{C}$$

$$h \xrightarrow{\text{eigenvalue of } h \text{ on } v}$$

i.e. \mathbb{C} -linear

$$h^* = \langle L_1, L_2, L_3 \rangle / (L_1 + L_2 + L_3 = 0)$$

where $L_i(v) = v_{ii}$
we call elements of h eigenvalues

We compute

$$\text{ad}(h)(e_{ij}) = (L_i - L_j)(h) e_{ij}$$

$$\text{ad}(h)(f_{ji}) = (L_j - L_i)(h) f_{ji}$$

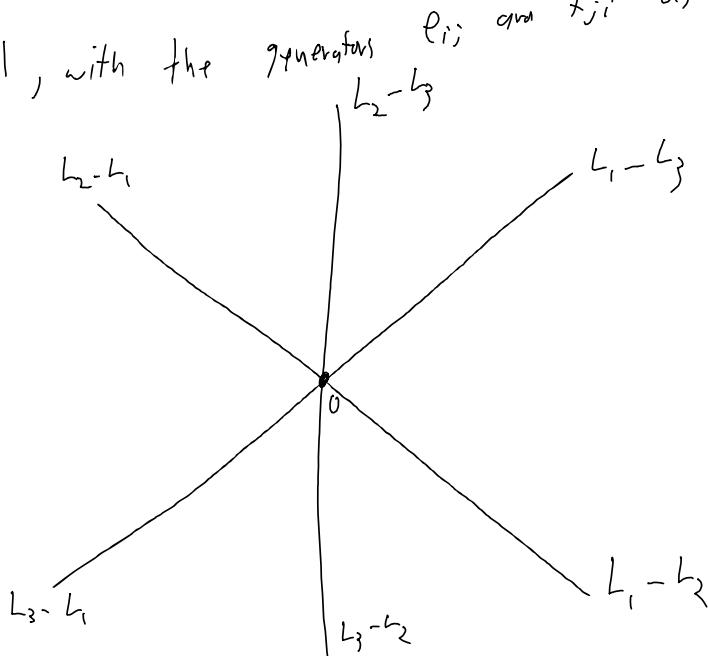
$$\text{ad}(h)(h') = 0, h' \in h$$

non-zero eigenvalues of $\text{ad}(h)$ $R = \{L_i - L_j, L_j - L_i\}_{i,j}$

Def. The non-zero eigenvalues of $\text{ad}(h)$ are called the roots of g (wrt h)

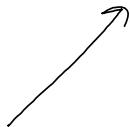
Then $g = h \oplus \bigoplus_{\alpha \in R} g_\alpha$ where $g_\alpha = \{v \in g | \text{ad}(h)v = \alpha(h)v \forall h \in h\}$
the α -eigenspace

$\dim g_\alpha = 1$, with the generators e_{ij} and f_{ji} as above

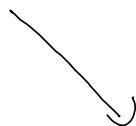


Compute $[g_\alpha, g_\beta] \subseteq \mathcal{G}_{\alpha+\beta}$

$$s_0 \quad \ell_{13} \quad \text{act}_3 \quad a_3$$



$$\ell_{12} \quad \text{act}_1 \quad a_3$$



$$e_{23} \quad \text{act}_1 \quad a_3$$



Why this drawing?

Def. Define a pairing $\langle \cdot, \cdot \rangle$ by $\langle x, y \rangle = \text{tr}(\text{ad}(x) \text{ad}(y))$

Fact. $\langle \cdot, \cdot \rangle$ is nondegenerate (this is equivalent to semisimplicity of \mathfrak{g})

Furthermore, for $h \in \mathfrak{h}$, $\langle h, h \rangle = \sum_{\alpha \in R} \alpha(h)^2$

Recall $\alpha(h) = 2$. Let $E = \text{IR}R$ the IR-space of the roots in \mathfrak{h}^* . Then $\langle \cdot, \cdot \rangle$ is positive definite on E and hence yields geometry on E .

$$\text{For a root } \alpha, \text{ let } R_\alpha = \text{span}(\alpha)^\perp$$

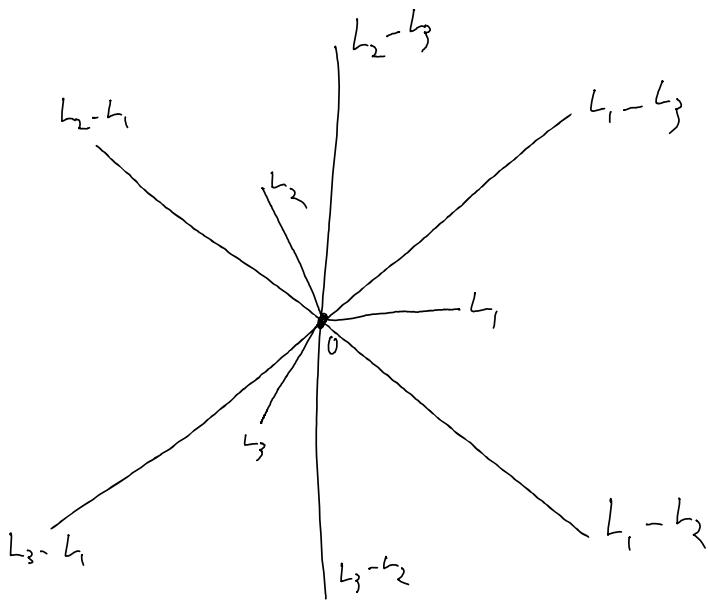
For a root α , let $R_\alpha = \{ \beta \in E \mid \beta(h_\alpha) = 0 \}$

\mathfrak{U} is chosen s.t. $R_\alpha = \{ \beta \in E \mid \beta(h_\alpha) = 0 \}$. R_α is the Weyl group generated by the simple reflections.

Def. Let s_α be reflection in E about R_α .

T_R e.g., $\alpha = L_2 - L_1$, $R_\alpha = \text{span } L_1$

$$\langle v, w \rangle = \|\|v\| \|w\| \cos \theta$$



The Weyl group acts on R , and in fact on L_1, L_2, L_3 here. This is faithful and all transpositions are achieved, so $W(\mathfrak{sl}_3) \cong S_3$.

As U is W -invariant, the angles here must all be 60°

Thm. Take $\frac{R}{U}$ a, before

i) Let $\alpha \in R$, $\lambda \in U$ $\Rightarrow \lambda = \pm 1$

ii) The reflection s_α preserves roots

iii) Let $\alpha, \beta \in R$. Then $\frac{U(\alpha, \beta)}{U(\alpha)} \subset \frac{1}{2} \mathbb{Z}$ (consider $\frac{U(\alpha, \beta)}{U(\alpha)} \frac{U(\beta, \alpha)}{U(\beta)}$
 $= U((\cos \theta)) \subset \mathbb{Z}$)

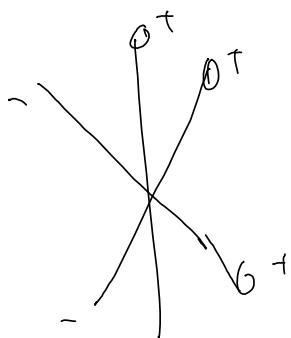
iv) $E = \text{span}(R)$

Des. That's a root system for E f.d.v.s./fl., $R \subseteq E$ finite, and U an inner product on E .

Theorem. This defines an equivalence between semi-simple Lie algebra / \mathbb{C} and root systems.

Dynkin diagram

We need to designate half of our roots as "positive" so that $\forall \alpha \in R$ only one of $\alpha, -\alpha$ are "positive".

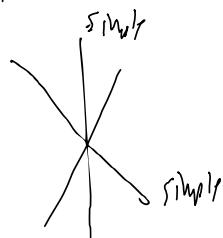


Systematically, these positive ones have α as eigenvectors, which lie in the subalgebra of upper triangular matrices.

$$\text{so } \alpha \in \mathfrak{g}_+ \Leftrightarrow g_\alpha \subseteq h$$

Rank 3 is called a Borel subalgebra or maximal solvable subalgebra.
Def. $\alpha \in R$ is simple if it's positive and not a sum of 2 positive roots.

$$\text{e.g., } L_1 - L_2 = (L_1 - L_2) + (L_2 - L_3)$$



Def, Let (E, R, κ) be a root system w/ a subset of positive roots R^+ .

The associated Dynkin diagram is an oriented multigraph with vertices the simple roots $\alpha \in R$. Let α, β be simple roots. Let $\theta = \text{angle between } \alpha, \beta$.

$$\alpha \quad \beta \quad \text{if } \theta = \frac{\pi}{2}$$



$$\text{if } \theta = \frac{2\pi}{3}$$



$$\text{if } \theta = \frac{3\pi}{4}, \text{ where } \not\rightarrow \text{ point towards the sharper end}$$



$$\text{if } \theta = \frac{5\pi}{6}, \text{ i.e. } \not\exists \text{ "}$$

Theorem, Root Systems are determined by their Dynkin diagrams,

$$\begin{array}{ll} \text{e.g., } \alpha_2 \text{ has } & \alpha_1 \\ \alpha_3 \text{ has } & \alpha_2 \end{array}$$

Representations of \mathfrak{sl}_3

Let V be a fd. irred. of \mathfrak{sl}_3

Def. A highest weight vector is an \mathfrak{h} -eigenvector killed by ℓ_{12}, ℓ_{23} and ℓ_{13} - the eisructur of the positive roots (wrt b)

Prop. Let λ be the highest weight of V . Then

$$\lambda = \sum a_i L_i$$

$$\text{w/ } a_i \in \mathbb{N}, \quad a_1 \geq a_2 \geq \dots$$

Thm. Such weight uniquely & totally determined for irreds of \mathfrak{sl}_3

Existence? $\mathfrak{sl}_2/\beta \cong \text{semisimple Lie algebras in } \mathcal{C}^?$

interv arises w/ line bundles on this space

§2. Reductive groups and root systems

Above was all for Lie algebras.

S.C. Lie grp \longrightarrow Lie Alg
is faithful, but S.C. is needed

Consider the double cover $SL_2 \longrightarrow PGL_2$. This is not iso, and let $SL_2 \xrightarrow{\sim} PGL_2$.

Reductive groups will be classified combinatorially over any acf (Chevalley 1958) also S.S. Lie algebras,

Def. Let G be a smooth connected algebraic group over a field k , Then radical $R(G)$ is a maximal smooth connected solvable normal subgroup.

G is called semisimple if $\underbrace{R(G_k^-)}_{\text{geometric radical}}$ is trivial

Rmk. $R(G)$ exists as solvability is closed under extension and quotient.

Def. An alg. group is unipotent if all nonzero nons having non-zero fixed vector. Equivalently, all representations, V of G have a basis where h acts via $\begin{pmatrix} 1 & * \\ 0 & 1 \end{pmatrix}$.

Def. G smooth, connected dg group / k a field.

Let $R_u(G)$ be a maximal smooth connected unipotent normal subgroup, called the unipotent radical

G is reductive if $\underbrace{R_u(G_{\bar{k}})}_{\text{geometric unipotent radical}}$ is trivial

Unipotent \Rightarrow solvable so minimal \Rightarrow reductive
Thus, GL_n, SL_n, PSL_n are all reductive,

Let G be SL_2 or PGL_2 .

Let $T \subseteq G$ be a maximal torus

$$\frac{SL_2}{T = \left\{ \begin{pmatrix} \alpha & 0 \\ 0 & \alpha^{-1} \end{pmatrix} \right\}} \quad \frac{PGL_2}{T = \left\{ \begin{pmatrix} \alpha & 0 \\ 0 & 1 \end{pmatrix}, \alpha \in \mathbb{C}^* \right\}}$$

Def. $\chi^*(T) = \text{Hom}(T, \mathbb{G}_m)$

This is a lattice.

$$\frac{SL_2}{\mathbb{Z} \xrightarrow{\sim} \chi^*(T)}$$
$$n \longmapsto \left(\begin{pmatrix} \alpha & 0 \\ 0 & 1 \end{pmatrix} \mapsto \alpha^n \right)$$

$$\frac{PGL_2}{\mathbb{Z} \xrightarrow{\sim} \chi^*(T)}$$
$$n \longmapsto \left(\begin{pmatrix} \alpha & 0 \\ 0 & 1 \end{pmatrix} \mapsto \alpha^n \right)$$

Rmk. Consider $T \hookrightarrow \mathfrak{sl}_2$. On Lie algebra,
 this yield $\mathfrak{h} \hookrightarrow \mathfrak{sl}_2$
 $\text{span} \begin{pmatrix} 1 & \\ & -1 \end{pmatrix}$

and $\text{Hom}(T, \mathfrak{g}_m) \hookrightarrow \text{Hom}(\mathfrak{h}, \mathfrak{g}_m)$

Def. $\mathbf{r} \subseteq \chi(T)$ are the characters corresponding to
 the roots of $\text{ad}(t)$ on \mathfrak{g}

$$\begin{array}{ccc} \mathfrak{sl}_2 & & \mathfrak{psl}_2 \\ \hline (\alpha_{\alpha^{-1}}) \mapsto \alpha^2 & & (\alpha_1) \mapsto \alpha \\ (\alpha_{\alpha^{-1}}) \mapsto \alpha^{-2} & & (\alpha_1) \mapsto \alpha^{-1} \end{array}$$

Def. $\chi_e(T) = \text{Hom}(\mathfrak{g}_m, T)$

$$\begin{array}{ccc} \mathfrak{sl}_2 & & \mathfrak{psl}_2 \\ \hline \mathbb{Z} \xrightarrow{\sim} \text{Hom}(\mathfrak{g}_m, T) & & \mathbb{Z} \xrightarrow{\sim} \text{Hom}(\mathfrak{g}_m, T) \\ n \mapsto (\alpha \mapsto \begin{pmatrix} \alpha^n & \\ & \alpha^{-n} \end{pmatrix}) & & n \mapsto (\alpha \mapsto (\alpha^n)_1) \end{array}$$

Def. $R^v \subseteq X_*(\mathbb{F})$ the coroots are the characters arising via

Prop. G reduction, T maximal torus, α a root,

$$\begin{array}{ccc} \exists & SL_2 \longrightarrow G & \text{S.y.} \\ & SL_2 \longrightarrow g & \text{Send } e \text{ to } g_\alpha - g_{\alpha^{-1}} \\ & & \text{a 2-eigenvector} \end{array}$$

Upon restriction to the (diagonal) maximal torus in SL_2

$$\begin{array}{ccc} SL_2 & & \overline{PL_2} \\ \overline{T \longrightarrow SL_2} & & \overline{T \longrightarrow PL_2} \\ (\alpha_{\alpha^{-1}}) \mapsto (\alpha_{\alpha^{-1}}) & & (\alpha_{\alpha^{-1}}) \mapsto (\alpha^3, 1) \\ (\alpha_{\alpha^{-1}}) \xrightarrow{\alpha^n} (\alpha^{-1}, \alpha) & & (\alpha_{\alpha^{-1}}) \xrightarrow{\alpha^n} (\alpha^{-3}, 1) \end{array}$$

There is a pairing $X^*(T) \otimes X_*(T) \xrightarrow{\langle \cdot, \cdot \rangle} \mathbb{Z}$

$$\downarrow \circ$$

$$\text{Hom}(G_m, G_m)$$

Observe that in both cases, there is a bijection $R \xrightarrow{\sim} R^v$
written $\alpha \mapsto \alpha^v$

We may verify

- $\langle \alpha, \alpha^\vee \rangle = 2$
- The reflection $S_{\alpha, \alpha^\vee}: X \rightarrow X$
 $x \mapsto x - \langle x, \alpha^\vee \rangle \alpha$

preserves R

- the reflection $S_{\alpha^\vee, \alpha}: X^\vee \rightarrow X^\vee$
 $y \mapsto y - \langle y, \alpha \rangle \alpha^\vee$

preserves R^\vee

Rmk. If α is Lie alg, $\alpha \subseteq g$ maximal abelian, $\alpha \in R$ a real. Then $\alpha^\vee \in \check{H}^*$ with $\alpha^\vee = 2 \frac{\alpha}{\kappa(\alpha, \alpha)}$ is the coroot, and $\kappa(\alpha, \alpha^\vee) = 2$, of course.

Def. (X^*, R, X^*, R^\vee) as above is called a root datum

Thm. $\{$ reduction groups $\}$ $\xrightarrow{\sim}$ Root datum

Rmk. {root datum} has an involution $\begin{matrix} (X^*, R, X^*, R^\vee) \\ \downarrow \\ (X_\alpha, R^\vee, X^*, R) \end{matrix}$

which yields an involution $G \xrightarrow{\sim} G^\vee$ on reduction groups,
this is called the Langlands dual.

e.g., \mathcal{SL}_2 had root datum

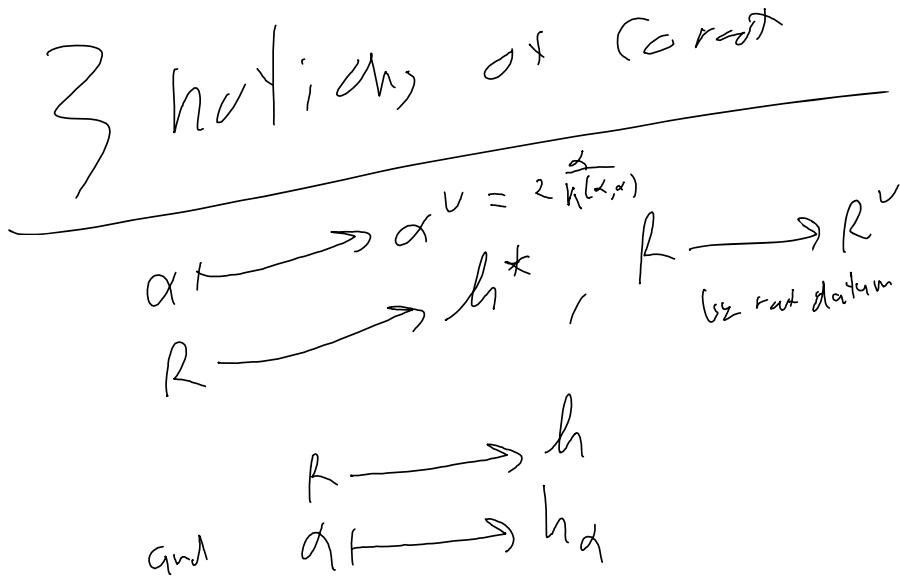
$$(\mathbb{Z}, \{\pm 2\}, \mathbb{Z}, \{\pm 3\})$$

and \mathcal{PGL}_2 had root datum

$$(\mathbb{Z}, \{\pm 3\}, \mathbb{Z}, \{\pm 2\})$$

so they are Langlands dual!

Fact, $\mathcal{SL}_n^V \cong \mathcal{SL}_n$



Connection??