

$$A, B$$

2×2 2×2

$$A(Bx)$$

2×2

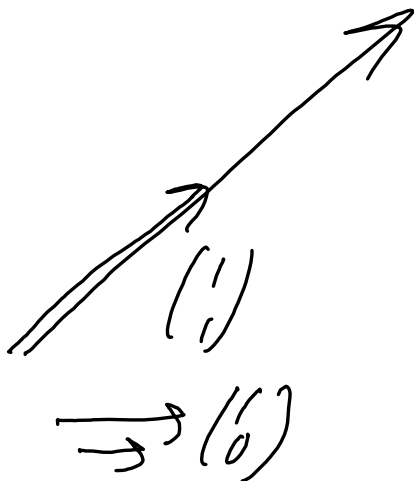
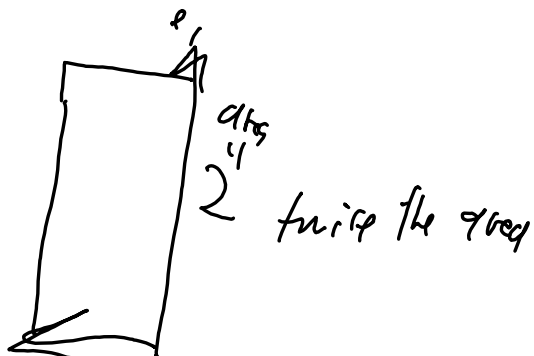
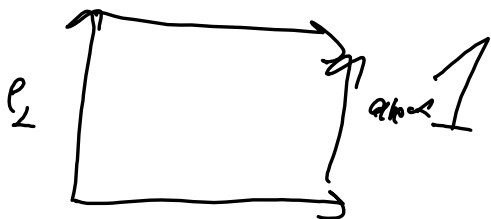
$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

90° rotation
?

$$T, \quad \underline{T(\vec{e}_1)}, \quad \underline{T(\vec{e}_2)}$$

$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$\begin{pmatrix} 0 & -1 \\ 2 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$



$$\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

why is this rotation?

T is linear

$$: \mathbb{R}^n \longrightarrow \mathbb{R}^m$$

there is some matrix A
 $m \times n$

so that $T(\vec{x}) = A\vec{x}$

↓
function eval

↓
matrix product

$T: \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ ↖ 90° rotation counter

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$T(\vec{x}) = \begin{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} & \begin{pmatrix} 1 \\ 0 \end{pmatrix} \end{pmatrix} \vec{x}$$

$$T \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \checkmark$$

$$T \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ \parallel \\ \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$



$$\vec{e}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad \vec{e}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = x \begin{pmatrix} 1 \\ 0 \end{pmatrix} + y \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ = x \vec{e}_1 + y \vec{e}_2$$

$$T(x \vec{e}_1 + y \vec{e}_2)$$

(Thm 2.1.3)

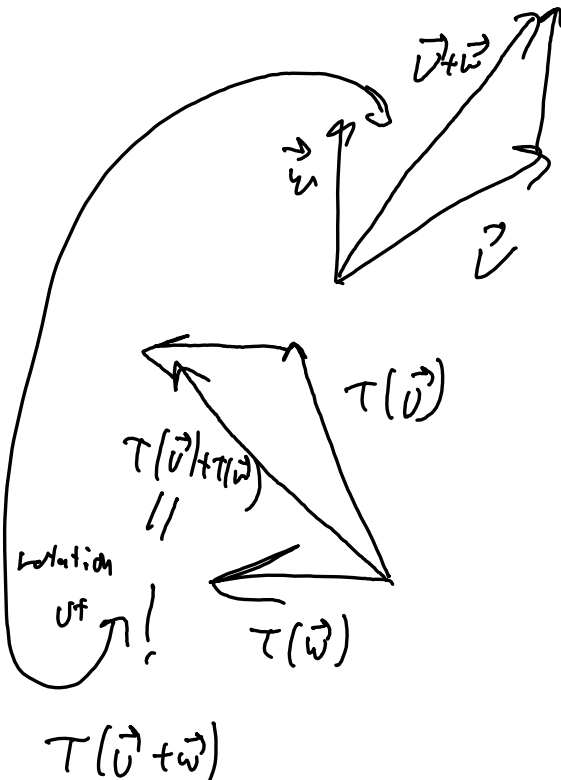
$$= x T(\vec{e}_1) + y T(\vec{e}_2) \\ \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$= x \begin{pmatrix} 0 \\ 1 \end{pmatrix} + y \begin{pmatrix} -1 \\ 0 \end{pmatrix} = \begin{pmatrix} -y \\ x \end{pmatrix}$$

$$= \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\underline{\tau(x\vec{e}_1 + y\vec{e}_2)} = \underline{x\tau(\vec{e}_1) + y\tau(\vec{e}_2)}$$

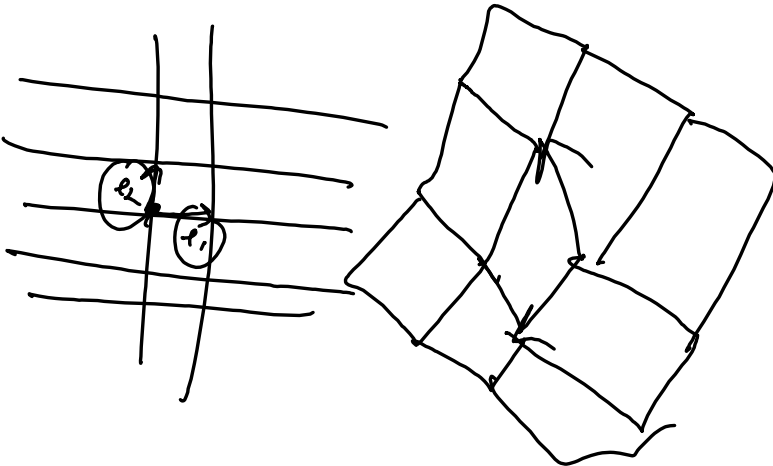
rotating
↓
 $\tau(\vec{v} + \vec{w})$

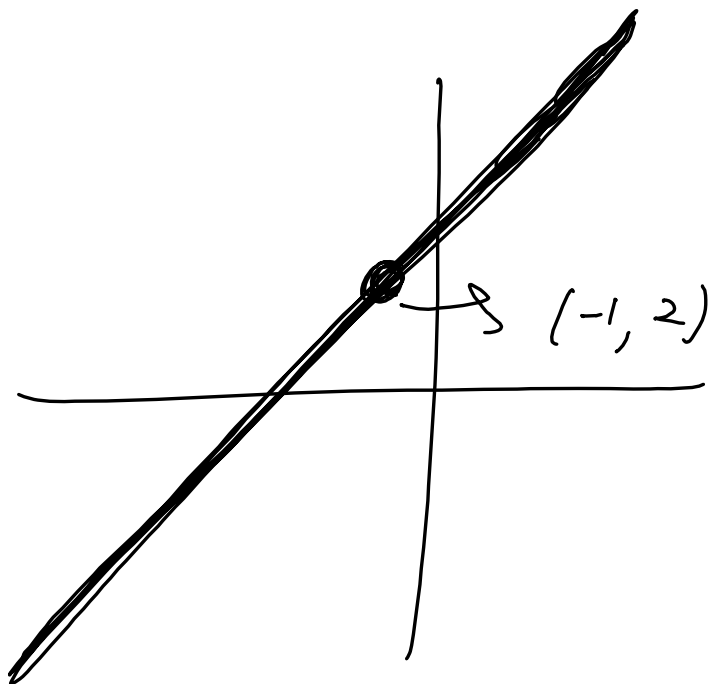


T , repr by $A = \begin{pmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_n \end{pmatrix}$
 $T \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \stackrel{(?)}{=} x_1 \boxed{\vec{v}_1} + \dots + x_n \boxed{\vec{v}_n}$
 $\vec{v}_i = T(\underline{e_i})$

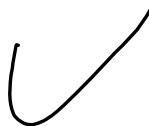
$\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \stackrel{(?)}{=} \underline{x_1 \vec{e}_1} + \dots + \underline{x_n \vec{e}_n}$

$\underline{T(a\vec{v} + b\vec{w}) = aT(\vec{v}) + bT(\vec{w})}$





$$T: \mathbb{R}^1 \rightarrow \mathbb{R}^1$$

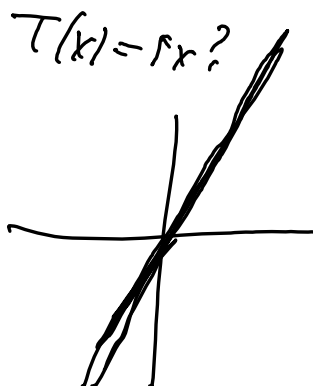


$$\frac{|x|}{\text{motiv}}$$

$$\text{erz} \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}$$

$$|x| \quad (5) \leftarrow$$

$$T(x) = Ax = \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix} x$$

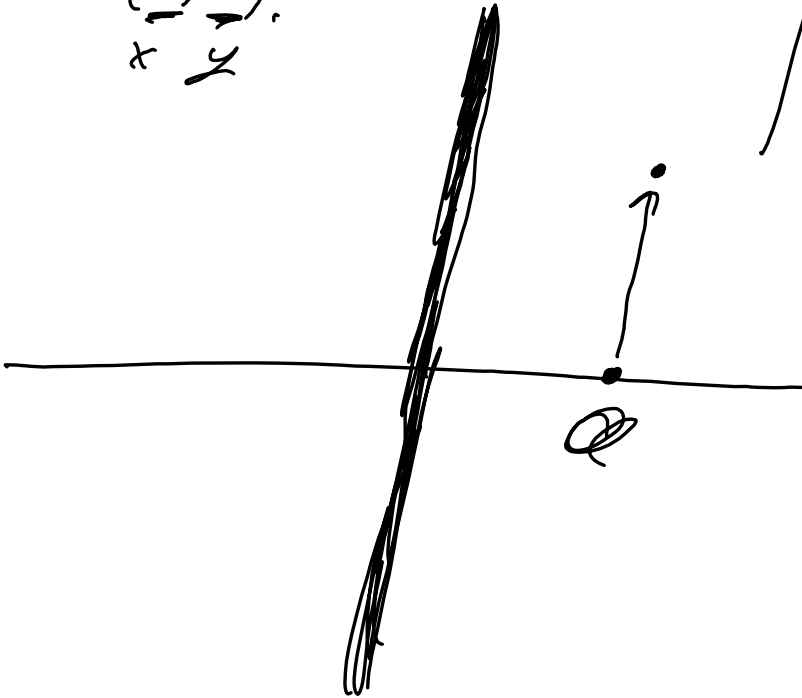
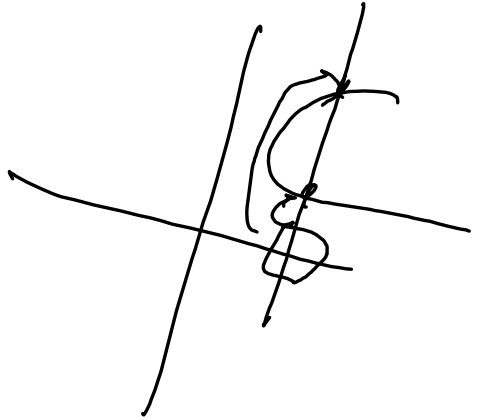


$$T(\vec{0}) = \vec{0}$$

$$A \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

origin $\longleftrightarrow$ origin

$(\underline{0}, \underline{0})$
x y



$$T \begin{pmatrix} x \\ y \end{pmatrix} = \underline{x}$$

$$\left\{ (\vec{x}, T(\vec{x})) \mid \vec{x} \in \mathbb{R}^n \right\}$$

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

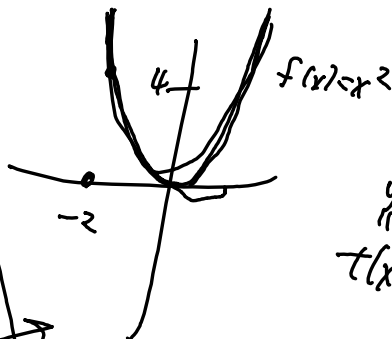
$$T(\vec{x}) \in \mathbb{R}^m$$

$$\vec{x} \in \mathbb{R}^n$$

$$(\vec{x}, T(\vec{x})) \in \mathbb{R}^{n+m}$$

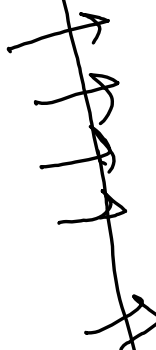
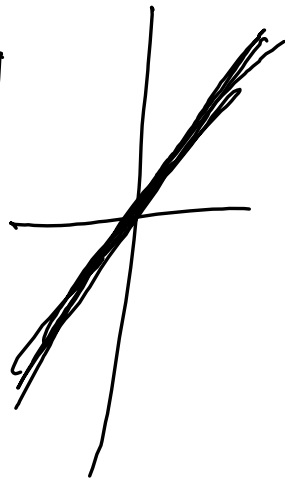
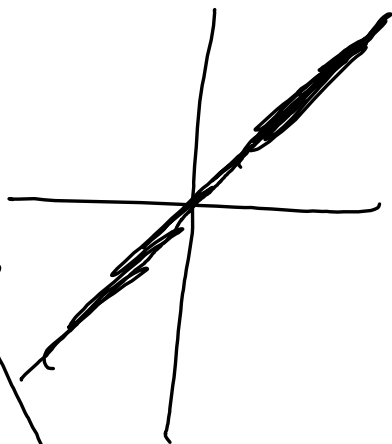
$$T: \mathbb{R} \rightarrow \mathbb{R} \quad \text{for } c \in \mathbb{R}$$

$$T(x) = (cx)$$

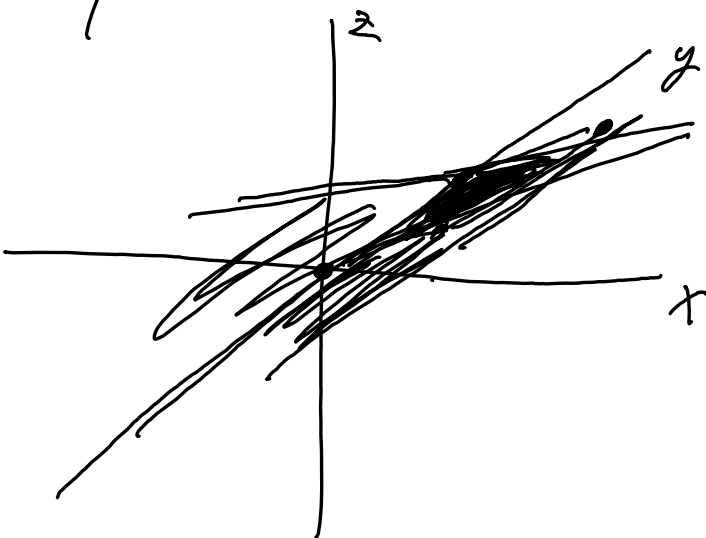


$$y$$

$$t(x) = x$$



T



$$T \begin{pmatrix} x \\ y \end{pmatrix} = 0$$

$$(0 \ 0)$$

