

§, 1 - §. 4, 6.1 - 6.3

§, 1

Orthogonal projections / bases

Definitions

perpendicular

$$\vec{v} \cdot \vec{w} = 0$$

length

$$\|\vec{v}\| = \sqrt{\vec{v} \cdot \vec{v}}$$

unit

length?

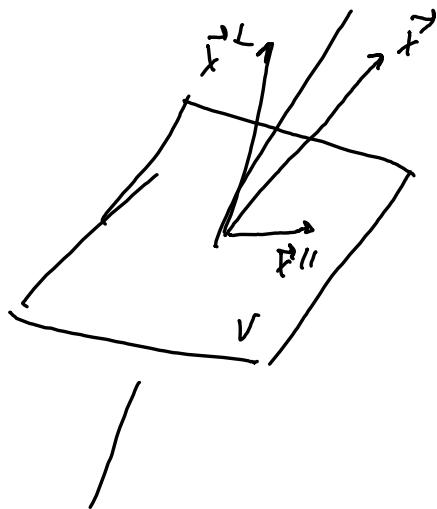
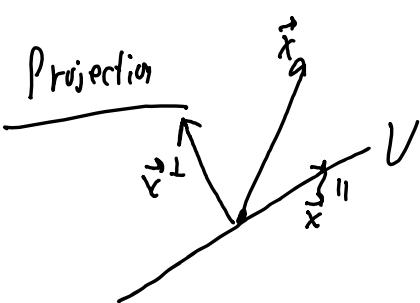
orthonormal

$\vec{q}_1, \vec{q}_m$  in  $\mathbb{R}^n$

$$\vec{q}_i \cdot \vec{q}_j = \begin{cases} 1 & i=j \\ 0 & \text{else} \end{cases}$$

all unit / orthog to another

Thought: Does orthonormal  $\Rightarrow$  lin indep?



Thm. For  $\vec{x}$  in  $\mathbb{R}^n$

$V$  a subspace of  $\mathbb{R}^n$

$$\vec{x} = \vec{x}^{||} + \vec{x}^{\perp} \text{ for } \vec{x}^{||} \in V$$

$\vec{x}^{\perp}$  perp to all vectors in  $V$

uniquely

$T(\vec{x}) = \vec{x}^{||}$  is called orthogonal projection onto  $V$

$$T = \text{proj}_V$$

This is linear

Let  $\vec{u}_1, \dots, \vec{u}_n$  be a basis for  $V$

$$\vec{x}^{||} = \sum (\vec{x} \cdot \vec{u}_i) \vec{u}_i$$

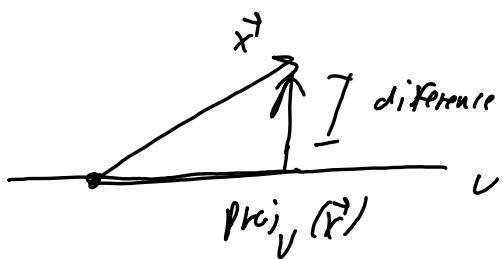
why does an O.P. exist?

what is  $\text{ker}(\text{proj}_V)$ ;  $\text{im}(\text{proj}_V)$ ?

what is  $\text{proj}_V^2$ ?

How do  $\text{proj}_V$  and  $\text{proj}_{V^\perp}$  relate? Their matrix forms?

Thm.  $\|\text{proj}_V \vec{x}\| \leq \|\vec{x}\|$   
equal if and only if  $\vec{x}$  in  $V$



Angles

$$\vec{v} \cdot \vec{w} = \|\vec{v}\| \|\vec{w}\| \cos \theta$$

$\theta$  in  $[-\pi, \pi]$

3. 2.

find  $\alpha \& \beta$ ?

Gram-Schmidt / G&F factorization

Theorem. Let  $\vec{v}_1, \dots, \vec{v}_n$  be linearly independent  
( $\Leftrightarrow$  a basis for a subspace)

$$\vec{u}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|}$$

$$\vec{u}_2 = \frac{\vec{v}_2 - \text{proj}_{\vec{u}_1}(\vec{v}_2)}{\|\vec{v}_2 - \text{proj}_{\vec{u}_1}(\vec{v}_2)\|} \quad \vec{v}_2 = \vec{u}_1 + \vec{u}_2^\perp \text{ w.r.t. } \text{Span}(\vec{v}_1)$$

$$\vec{u}_i = \frac{\vec{v}_i - \text{proj}_{\vec{u}_1, \dots, \vec{u}_{i-1}}(\vec{v}_i)}{\|\vec{v}_i - \text{proj}_{\vec{u}_1, \dots, \vec{u}_{i-1}}(\vec{v}_i)\|} \quad \vec{v}_i = \vec{u}_1 + \vec{u}_2 + \dots + \vec{u}_{i-1}^\perp \text{ w.r.t. } \text{Span}(\vec{v}_1, \dots, \vec{v}_{i-1})$$

Then for all  $i$ ,  $\text{Span}(\vec{u}_1, \dots, \vec{u}_i) = \text{Span}(\vec{v}_1, \dots, \vec{v}_i)$ .

And the  $\vec{u}_i$  are orthonormal.

Ques: Can always extend a basis of a subspace

of  $\mathbb{R}^n$  to all of  $\mathbb{R}^n$ .

With G-S, can convert bases to orthonormal ones.  
Hence, can find and extend orthonormal bases of a subspace  
of  $\mathbb{R}^n$  to all of  $\mathbb{R}^n$

QR factorization

$$\begin{pmatrix} 1 & & & \\ v_1 & \dots & v_n \\ | & & | \\ & \ddots & & \end{pmatrix} = \begin{pmatrix} 1 & & & \\ q_1 & \dots & q_n \\ | & & | \\ & \ddots & & \end{pmatrix} R$$

Q

R upper triangular

$$R_{ij} = \vec{q}_i \cdot \vec{v}_j \quad \text{for } i < j.$$

$$\therefore R_{ii} = \vec{q}_i \cdot \vec{v}_i = \frac{\vec{v}_i \perp \cdot (\vec{v}_i^{\perp\perp} + v_i^\perp)}{\|\vec{v}_i^\perp\|} = \|\vec{v}_i^\perp\|$$

Manj. Gram-Schmidt + QR factorization are the same process, just written differently. All the same computations are done.

## Orthogonal Matrices / Transformations

When is a matrix orthogonal?  
If any of the following hold:

- i)  $\|A\vec{x}\| = \|\vec{x}\|$  for all  $\vec{x}$
- ii) The columns of  $A$  are an orthonormal basis
- iii)  $A^{-1} = A^T$
- iv)  $(A\vec{x}) \cdot (A\vec{y}) = \vec{x} \cdot \vec{y}$  for all  $\vec{x}, \vec{y}$

Indeed, orthogonal matrices / transformations are "rigid," which is reflected in their length + angle preservation.

(why do they preserve angles?)

Anything you can do w/ a piece of paper is orthogonal!

## Orthogonal projection revisited

$$Q = \begin{pmatrix} \vec{q}_1 & \dots & \vec{q}_m \end{pmatrix}, \quad \vec{q}_1, \dots, \vec{q}_m \text{ an ONS for } V.$$

Then  $P_{\text{proj}}_V = Q Q^T$   
why? check how it acts on the  $\vec{q}_i$ !

## 5.4 Least Squares

Transpose and orthogonal constraints

$$(\text{im } A)^\perp = \ker(A^\top)$$

Recall that  $(A^\top)^\top = A$ ,  $(V^\perp)^\perp = V$

$$\begin{aligned} \text{Hence, } (\text{im}(A^\top))^\perp &= \ker((A^\top)^\top) \\ &= \ker(A) \end{aligned}$$

$$\text{im}(A) = \ker(A^\top)^\perp$$

$$\text{im}(A^\top) = \ker(A)^\perp$$

$$\ker(A) = \ker(A^\top A)$$

We can't always solve systems, so we'll get as close as possible.

Thm,  $\text{proj}_V(\vec{v})$  is the closest vector in  $V$  to  $\vec{v}$ .

Least squares;  $\vec{x}^*$  is a least squares solution

$$\text{to } A\vec{x} = \vec{b}$$

$$\text{if } \|b - A\vec{x}^*\| \leq \|b - A\vec{x}\| \text{ for all } \vec{x}$$

Hence,  $A\vec{x}^* = \text{proj}_{\text{im}(A)}(\vec{b})$

$$\vec{b} - A\vec{x}^* \in (\text{im } A)^\perp = \ker(A^\top)$$

$$A^\top \vec{b} = A^\top A\vec{x}^*$$

so  $\vec{x}^*$  is a least squares solution to  $A\vec{x} = \vec{b}$

$$\vec{x}^* \text{ solves } A^\top A\vec{x} = A^\top \vec{b}$$

# Determinants

(Sorry, this part is rushed)

6.1

Def.  $\det(A) = \sum_{\text{permutations } p} (\text{sgn } p) (\prod_{i=1}^n a_{p(i)i})$

If  $A$  upper  $\Delta$ ,  $\det(A) = \prod a_{ii}$

6.2

$$\det(A^+) = \det(A)$$

$$T(\vec{v}) = \det \begin{pmatrix} \vec{v}_1 \\ \vec{v}_2 \\ \vdots \\ \vec{v}_n \end{pmatrix} \rightarrow \text{linear}$$

(comparing w/ row reduction

$$A \xrightarrow{\text{swap}} B$$

$$\det(B) = -\det(A)$$

$$A \xrightarrow{R_i \mapsto R_i + kR_j} B$$

$$\det(B) = \det(A)$$

$$A \xrightarrow{R_i \mapsto \lambda R_i} B$$

$$\det(B) = \lambda \det(A)$$
$$\det(A) = \frac{1}{\lambda} \det(B)$$

$A$  invertible  
if

$\det A \neq 0$

$$\det(AB) = \det(A) \det(B)$$

$$A \text{ similar to } B \Rightarrow \det(A) = \det(B)$$

$\therefore \det(T)$  makes sense irrespective of basis

$$\det(A^{-1}) = \frac{1}{\det(A)}$$

Expansion by minors

$A_{ij} = \text{Minor of } A \text{ w.r.t. } i^{\text{th}} \text{ row + } j^{\text{th}} \text{ column}$

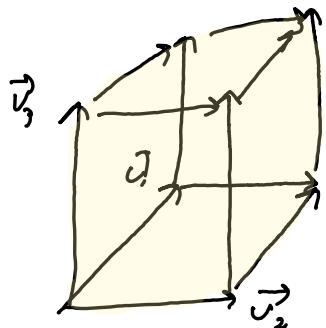
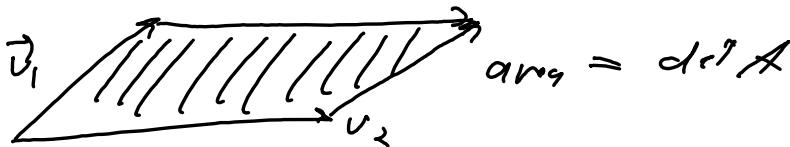
$$\det A = \sum_{i=1}^n (-1)^{i+j} a_{ii} \det(A_{i:i}) \quad \text{down col } j$$

$$\det A = \sum_{j=1}^n (-1)^{i+j} a_{ij} \det(A_{i:j}) \quad \text{across row } i$$

# Geometry of det + Cramer's rule

$$\text{Sos } A = \begin{pmatrix} \vec{v}_1 & \dots & \vec{v}_n \end{pmatrix}$$

$\det A$  = "Signed" volume of the parallelepiped  
formed by  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$



$$|\det(A)| = \frac{\text{volume of } T(S)}{\text{volume of } S}$$

Grammer's rule