

Systems of linear equations

$$\underline{1x + 1y + 1z = 1}$$

$$\underline{2x + 3y + 4z = 2}$$

$$\underline{x - y + z = 5}$$

$$\begin{pmatrix} 1 & 1 & 1 & ; & 1 \\ 2 & 3 & 4 & ; & 2 \\ 1 & -1 & 1 & ; & 5 \end{pmatrix}$$

x y z

row reduction

Gauss - Jordan elimination

consistent? $\rightarrow$ 1 solution $\rightarrow$ what are they?
 $\rightarrow$ inf many
 inconsistent?

1 equation

1 unknown

$$ax = b$$

$$x = \frac{b}{a}$$

$a \neq 0$ ✓

$a = 0$

$\rightarrow 1 = 0$ ✓

$\rightarrow b \neq 0$

$\rightarrow$ inconsistent

$$\begin{pmatrix} 1 & 1 & 1 \\ 2 & 3 & 4 \\ 1 & -1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 5 \end{pmatrix}$$

A

$\vec{x}$

$\vec{b}$

$$A\vec{x} = \vec{b}$$

$$A \vec{x} = \vec{b}$$

$$\vec{x} = A^{-1} \vec{b} \quad (\text{caveats})$$

1 equation (multidimensional)

1 unknown $\vec{x}$ (multidimensional)

subtleties: $\vec{b}$ can't always be reached

could be the solution
 $\vec{x}$ is not always unique

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} c \\ 1 \end{pmatrix}$$

" $\begin{pmatrix} x \\ 0 \end{pmatrix} \leftarrow$

no solution

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$c = 1, x$

$$\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Everything is a solution

$A \vec{x} = \vec{b}$ inconsistent if $\text{rank}(A) < \text{rank}(\begin{bmatrix} A & \vec{b} \end{bmatrix})$

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\vec{b} = \vec{0}$$

$\vec{x} = \vec{0}$

False

$$\left(\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 4 & 5 & 6 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$x \ y \ z \ w$ → out variable is missing

$$- x + 2y + 3z = 1$$

$$- 4x + 5y + 6z = 2$$

$$- 0 = 0$$

how

eq w/ no variables → trivially true $0=0$
 → trivially false $0=1, 0=3$

$$\rightarrow \left(\begin{array}{cc|c} 1 & 1 & 1 \\ 2 & 2 & 2 \end{array} \right)$$

$$\xrightarrow{\text{swap}} \left(\begin{array}{cc|c} 2 & 2 & 3 \\ 1 & 1 & 1 \end{array} \right) R_1/2$$

$$\uparrow$$

$$R_2 - 2R_1$$

$$\begin{cases} x+y=1 \\ 2x+2y=2 \end{cases}$$

$$\rightarrow \begin{cases} x+y=1 \\ y=0 \end{cases}$$

$$\rightarrow \begin{cases} 2x+y=2 \\ y=0 \end{cases}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ \vdots & \ddots & \vdots \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 & : & 9 \\ 0 & 1 & 0 & : & 6 \\ 0 & 0 & 1 & : & 6 \end{pmatrix}$$

$$I_n \vec{x} = \vec{b}$$

// unique solution

$\vec{x}$

$$\vec{x} = \vec{b}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} (100) \left(\frac{1}{3} \right) = 1 \\ (010) \left(\frac{1}{3} \right) = 2 \\ (001) \left(\frac{1}{3} \right) = 2 \end{pmatrix}$$

A

$m \times n$

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$\text{im}(A) = \text{span cols of } A$$

$$A = \begin{pmatrix} \vec{v}_1 & \dots & \vec{v}_n \\ \vdots & & \vdots \end{pmatrix}$$

$$A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \underline{x_1 \vec{v}_1 + \dots + x_n \vec{v}_n}$$

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$$

$$\text{im}(A) = \text{span} \left\{ \begin{pmatrix} 1 \\ 4 \end{pmatrix}, \begin{pmatrix} 2 \\ 5 \end{pmatrix}, \begin{pmatrix} 3 \\ 6 \end{pmatrix} \right\}$$

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -4 & 1 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\vec{c} = \vec{c} + 2\vec{b}$$

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix} = -1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 2 \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 3 \\ 6 \end{pmatrix} = -1 \begin{pmatrix} 1 \\ 4 \end{pmatrix} + 2 \begin{pmatrix} 2 \\ 5 \end{pmatrix}$$

basis im(A)

rref(A)

algorithm

find cols w/ pivots = leading 1
these corresponding columns are the basis

basis?

ker(A)?

$A\vec{x} = \vec{0}$

kernel
Null
pligins

$$\begin{pmatrix} 2 & \\ & 1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 2a & 2b \\ c & d \end{pmatrix}$$

multiplied
row of 1
by 2

$$R_1 \mapsto 3R_2 + R_1$$

$$\begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a+3c & b+3d \\ c & d \end{pmatrix}$$

ref(A)

$$\underline{E_n \dots E_1 E_2 E_1 A}$$

$$\text{ref}(A) = EA \quad E \text{ invertible matrix}$$

$\swarrow \downarrow \downarrow \searrow$
 same kernel

6. Let $\vec{v}$ be in $\mathbb{R}^3$

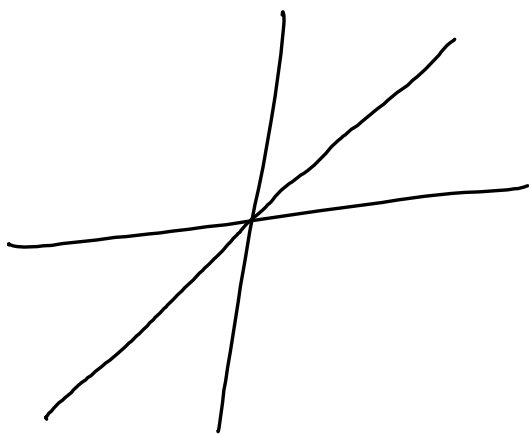
$$T(\vec{w}) = \vec{v} \cdot \vec{w} = v_1 w_1 + v_2 w_2 + v_3 w_3$$

$\ker(T)$? $\text{im}(T)$?

geometrically and algebraically
 describe the
 picture

"formula"

starting from
 basis



xy-plane in $\mathbb{R}^3$

basis $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$
 spans $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$
 $\left\{ \begin{pmatrix} x \\ y \\ 0 \end{pmatrix} \right\}$ $x, y \in \mathbb{R}$
 "formula"

$T(\vec{e}_1)$
 $\vec{v} \cdot \vec{e}_1$

v_1

$T(\vec{e}_2)$ $T(\vec{e}_3)$
 v_2 v_3

matrix

"abstract reasoning"

"mechanical"

$$\begin{pmatrix} \underline{v_1} & \underline{v_2} & \underline{v_3} \end{pmatrix}$$

rank-nullity thm

$$T \vec{v} = \vec{0}$$

$$\vec{v} \neq \vec{0}$$

$$\mathbb{R}^3 \xrightarrow{T} \mathbb{R}^1$$

dimension counting

$$3 = \text{null}(T) + \text{rank}(T)$$

$$\begin{matrix} 0 & 1 \\ \hline \end{matrix}$$

$$\text{rank}(T) = 0$$

$$\text{null}(T) = 3$$

$$\begin{aligned} \{ \vec{0} \} &= \text{im}(T) \\ \text{ker}(T) &= \mathbb{R}^3 \end{aligned}$$

ϕ

$$\text{rank}(T) = 1$$

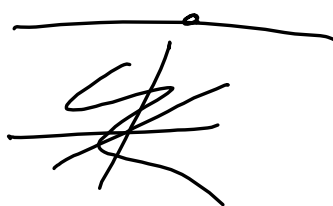
$$\vec{p}_1, \vec{p}_2, \vec{p}_3$$

$$\vec{v} \neq \vec{0}$$

$$T(\vec{v}) = \|\vec{v}\|^2 \neq 0$$

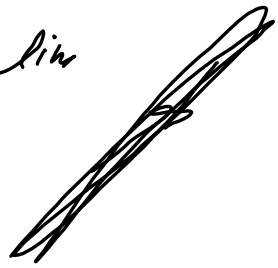
ker

im



$\text{rank}(T) = 1$, $\text{im}(T)$ is line

$\text{im}(T)$ contained in $\mathbb{R}^2$



1 d subspace of $\mathbb{R}^n$ must be all of $\mathbb{R}^n$

$\hookrightarrow$ V subspace $\mathbb{R}^n$

$$\dim V = k$$

W contains V $\dim W = \dim V$

V contains in W

$$\underline{W = V}$$

$$\text{im}(T) = \mathbb{R}^2$$

$\{1\}$

$\{2\}$

$\{-1\}$

$\{1, 1, 2\}$

$\{2\}$

$\text{Ker}(T)?$

$$\dim(\text{im}(T))$$

$$= \dim \text{Ker}(T)$$

1
2

$$\text{Ker}(T) \subseteq \mathbb{R}^3$$

$\downarrow$
contained
in

plane

what plane is this?

$\text{ker}(T)$

$$\vec{w} \mid -T(\vec{w}) = 0$$



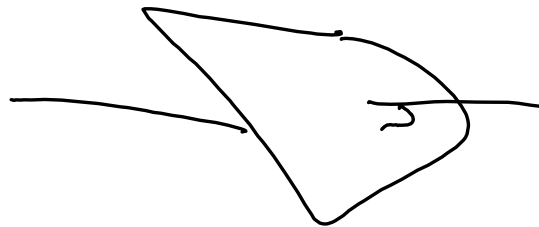
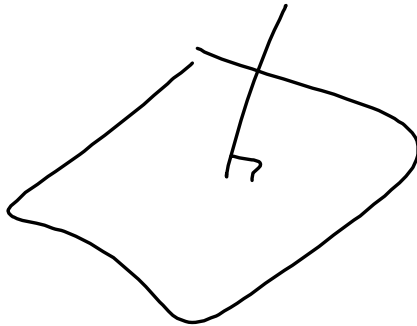
$$\vec{v} \cdot \vec{w}$$

$$\vec{w} \text{ s.t. } \vec{v} \cdot \vec{w} = 0$$

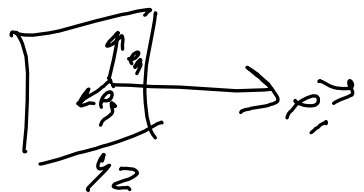
$$\vec{v} \perp \vec{w}$$



the plane perpendicular to $\vec{v}$ geometry



$\vec{w} = \vec{e}_1$, what is $\text{ker}(T)$
 γ_2 - plane
 basis $(\vec{e}_2, \vec{e}_3)$



basis $\ker(T)$?

$\vec{x}$, $\vec{y}$

$$\vec{y} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

$$T(\vec{w}) = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \cdot \underline{\vec{w}}$$

$$T(\vec{w}) = w_1 + 2w_2 + 3w_3$$

$$\underline{T(\vec{w}) = 0}$$

$$\underline{w_1 + 2w_2 + 3w_3 = 0}$$

$$(1 \quad 2 \quad 3 \mid 0)$$

$$\underline{w_1 = -2w_2 - 3w_3}$$

$$\boxed{w_3 = 0}$$

$$\underline{w_1 = -2w_2}$$

$$w_2 = 0 \Rightarrow w_1 = 0$$

$$\rightarrow w_2 = 1 \quad w_1 = -2$$

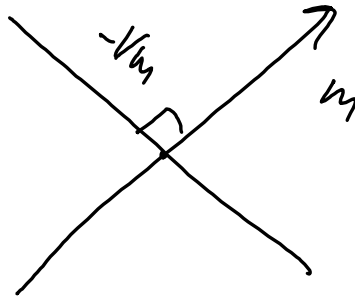
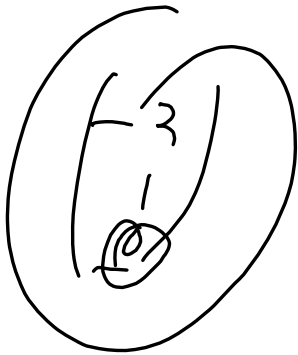
in $\ker(T)$

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -2 \\ 2 & 6 \end{pmatrix} = 0$$

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} -2 \\ 6 \end{pmatrix}$$



$$w_1 = 0, \quad 2w_2 + 3w_3 = 0$$

$$w_1 = 1, \quad 2w_2 + 3 = 0$$

$$\begin{pmatrix} 0 & 1 \\ -2/3 & 1 \end{pmatrix} = 0$$



$$\begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \\ 1 \end{pmatrix}$$

in $\text{ker}(T)$

$$\dim \text{ker } T = 2$$

basis!

general?

$$\vec{v} \neq 0$$

solve this for $\vec{w}$:

$$\hookrightarrow v_1 w_1 + v_2 w_2 + v_3 w_3 = 0$$

$$w_3 = 0?$$

$$v_1 w_1 + v_2 w_2 = 0$$

$$w_2 = /$$

$$v_1 w_1 + v_2 = 0$$

$$w_1 = \frac{-v_2}{v_1}$$

$$\vec{w} = \begin{pmatrix} -v_2/v_1 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -v_2/v_1 \\ 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = 0$$

Case 1. $v_1 \neq 0$

as before $\vec{w} = \begin{pmatrix} -v_2/v_1 \\ 0 \end{pmatrix}$

$w_2 = 0$

$v_1 w_1 + v_3 w_3 = 0$

$w_3 = 1$

$v_1 w_1 + v_3 = 0$

$w_1 = \frac{-v_3}{v_1}$

$\begin{pmatrix} -v_3/v_1 \\ 0 \\ 1 \end{pmatrix}$

lin indep

Case 2. $v_1 = 0$

$w_2 v_2 + w_3 v_3 = 0$

$\begin{pmatrix} 0 \\ v_2 \\ v_3 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ -v_3 \\ v_2 \end{pmatrix} = 0$

$v_2 \neq 0, w_3 = 1$

$w_3 = 1$

$w_2 v_2 + w_3 = 0$

$w_2 = \frac{-v_3}{v_2}$

$\rightarrow$

$\begin{pmatrix} 0 \\ -v_3/v_2 \\ 1 \end{pmatrix}$

$v_2 = 0$

$w_2 v_2 = 0$

w_2 free

$\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$

$\begin{pmatrix} 0 \\ v_3 \\ -v_3 \end{pmatrix}$

4. reflection $\mathbb{R}^3 \rightarrow \mathbb{R}^3$
 about plane $y = z$

find the matrix for the linear
transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

given by reflection about plane $y = z$

what is the matrix for T ?

$\{x\}$ matrix, $\mathbb{R}^2 \rightarrow \mathbb{R}^2$ $\begin{pmatrix} \mathbb{R}^n \rightarrow \mathbb{R}^m \\ m \times n \end{pmatrix}$

first col

second

third

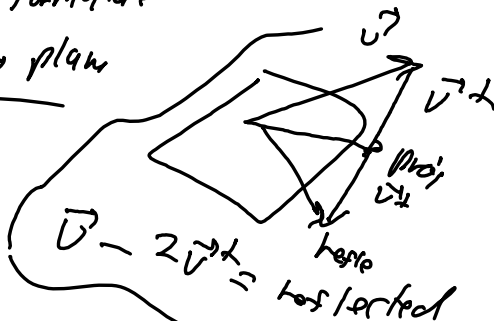
$T(\underline{e}_1)$
 $T(\underline{e}_2)$
 $T(\underline{e}_3)$

$T(\underline{x}) = A\underline{x}$
 formula

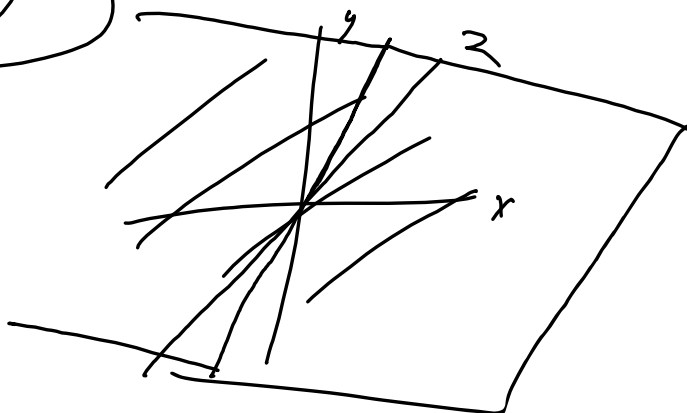
Strategy: Find $T(\underline{e}_i)$ $i = 1, 2, 3$.

Another approach: remember familiar

Proj onto plane



$$(x, y, z)$$



$$\begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

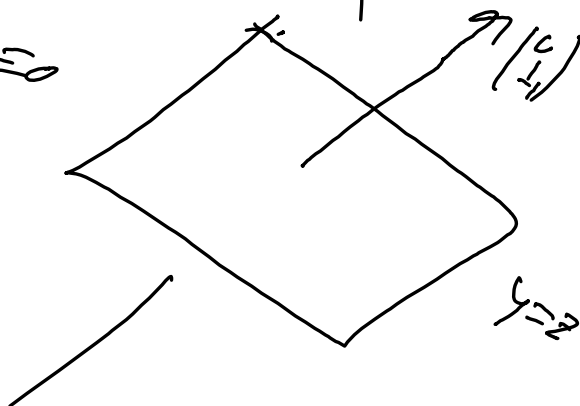
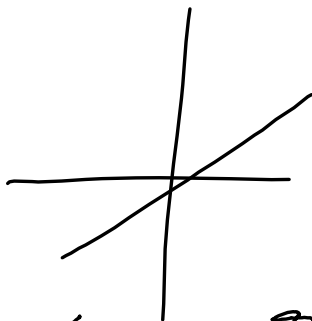
normal vector

$$\begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0$$

$$y = z$$

$$y - z = 0$$

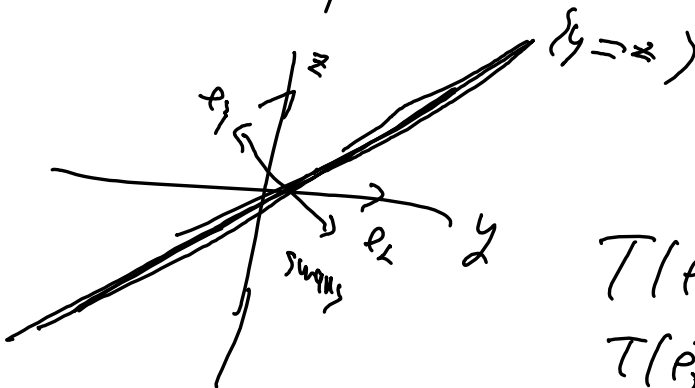
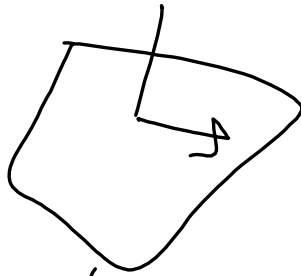
$$0x + y - z = 0$$



$x = \text{orig}$ on $y = \text{axis}$ $y = z$

$$\begin{pmatrix} x \\ 0 \\ 0 \end{pmatrix}$$

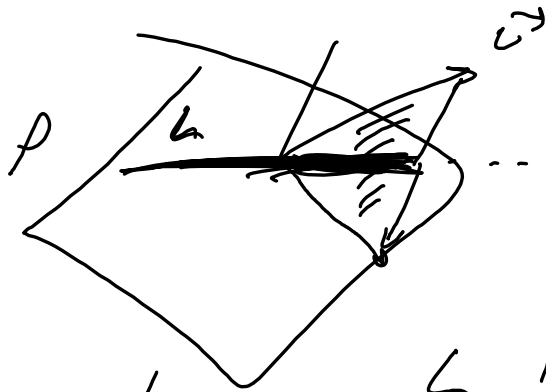
$\vec{e}_1$ in plane, $T(\vec{e}_1) = \vec{e}_1$



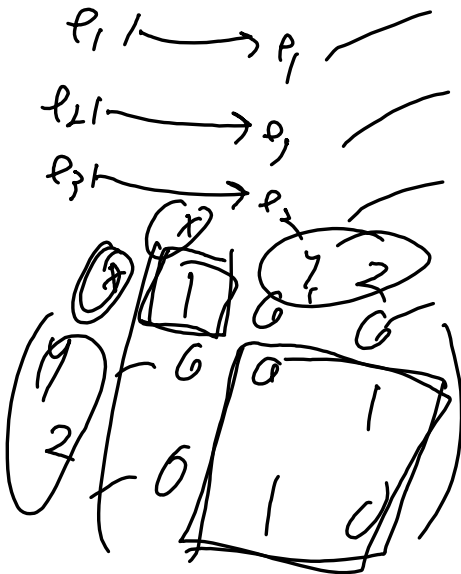
cross section

$$T(\vec{e}_2) = \vec{e}_3$$

$$T(\vec{e}_3) = \vec{e}_2$$



L "shoda"
 Pr_i
 $or \rightarrow or + P$
 reflection $\rightarrow$ about P
 $\uparrow$
 reflection $\rightarrow$ about L



"block diagram"

$$\sqrt{2}x + \sqrt{2}y + \sqrt{2}z = 0$$

$$\vec{p}_1 \mapsto ??$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \end{pmatrix}$$

$$\begin{matrix} -p_1 \\ -p_2 \\ -p_3 \end{matrix}$$

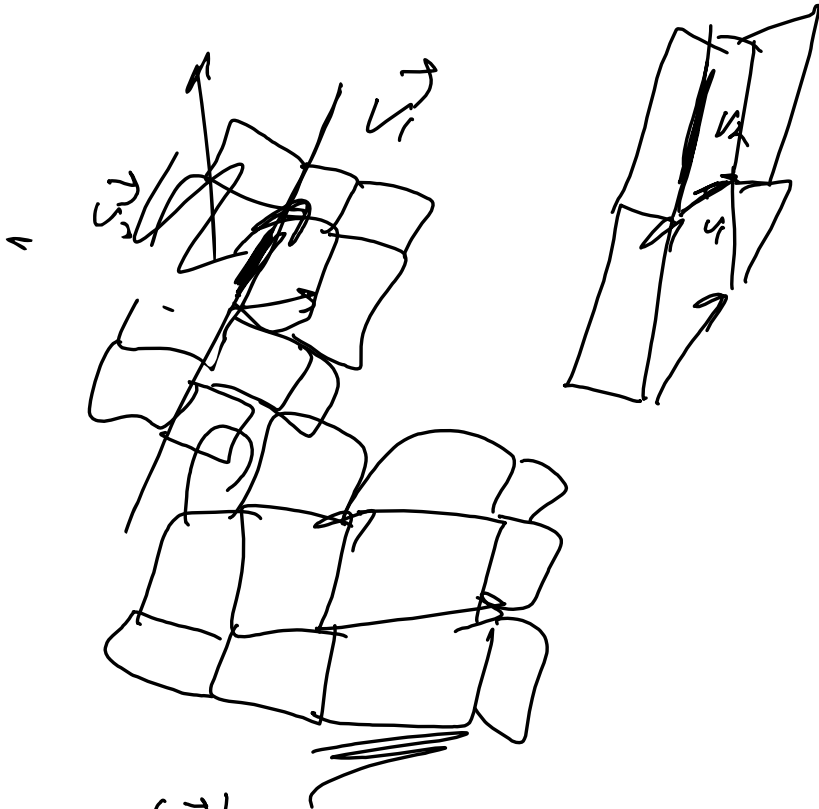


T_{ref} about x -axis

$$T\left(\frac{\pi}{2}\right) = \begin{pmatrix} \cos \frac{\pi}{2} & \sin \frac{\pi}{2} \\ -\sin \frac{\pi}{2} & \cos \frac{\pi}{2} \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$





$$T(\vec{v}_1) = \vec{v}_1$$

$$T(\vec{v}_2) = -\vec{v}_2$$

reflection about $\vec{v}_1$

in basis $\mathcal{B} = (\vec{v}_1, \vec{v}_2)$

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}_{\mathcal{B}}$$

$$\begin{pmatrix} 1 & & \\ & 1 & \\ & & -1 \end{pmatrix}_{\mathcal{B}}$$

8

d)

$A \text{ comm } B$

$B \text{ comm } C$

$A \text{ comm } C$

A "commutes" w/ B

$$17 \quad \underbrace{AB = BA}$$

~~$$A^3 B C B A$$~~

$$\begin{array}{l} A \quad \overline{n \times m} \\ B \quad \overline{k \times l} \end{array}$$

$$A \circ B$$

$$n=k$$

$$n \times l$$

$$(n \times n)(n \times l) = n \times l$$

$$n \times l$$

$$\begin{array}{l} BA \\ n=l \end{array}$$

$$k \times n$$

$$\overline{n \times l} \quad \overline{AB}$$

$$n=n$$

$$n=l$$

$$=$$

$$\overline{k \times n} \quad \overline{BA}$$

A, B, C square matrices
same dimension

$$\left(\begin{array}{l} AB = BA \\ \vdots \\ BC = CB \end{array} \right) \text{ hypotheses}$$

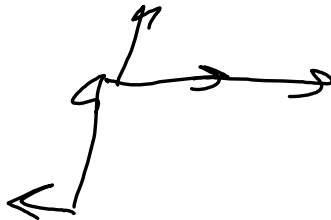
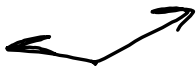
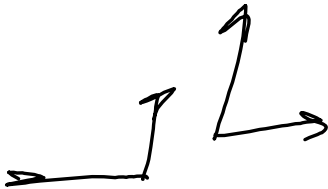
$\Downarrow$

$$\underline{AC = CA} \text{ goal}$$

$\left(\begin{array}{l} A \text{ rot} \\ B \text{ scale} \\ C \text{ shear (?)} \end{array} \right) \rightarrow (!!)$

fact: A commutes w/
every matrix B

$$A \text{ scale} \\ A = cI$$



Say true

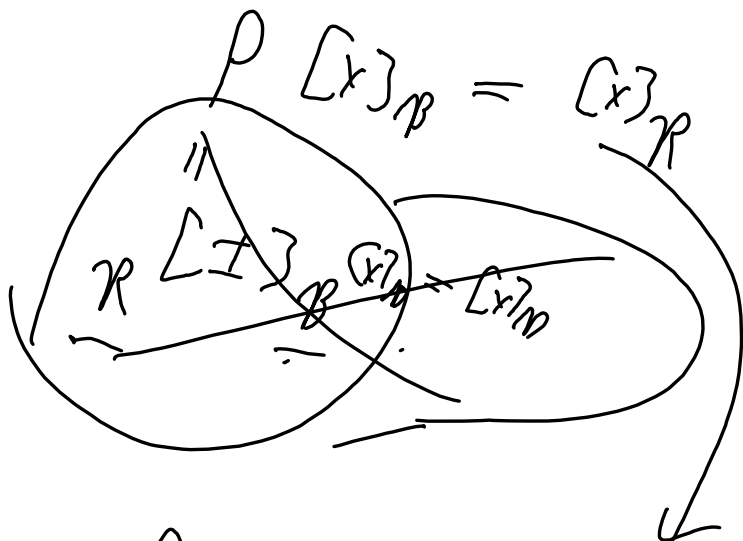
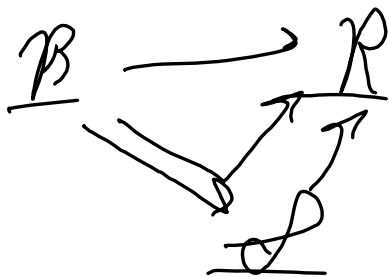
$B = \mathbb{Z}$, or any set

$A \cap B = B \cap A$ true for all A

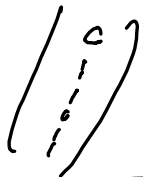
$(B \cap C) = C \cap (B \cap C)$ true for all C

$\Downarrow$ given true

A commutes w/ C



$P \vec{e}_i$ in class P



$P \vec{e}_i$



$$\underline{[\vec{x}]_{\mathcal{B}} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}}$$

$$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

$$\vec{x} = 1\vec{v}_1 + 0\vec{v}_2 = \vec{v}_1$$

$$\mathcal{B} = (\vec{v}_1, \vec{v}_2)$$

$$[\vec{v}_1]_{\mathcal{B}} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$P \underset{\parallel}{[\vec{v}_1]_{\mathcal{B}}} = \underset{P \begin{pmatrix} 1 \\ 0 \end{pmatrix}}{[\vec{v}_1]_{\mathcal{R}}}$$

find
coeff P

$$P \underset{\parallel}{[\vec{v}_2]_{\mathcal{B}}} = [\vec{v}_2]_{\mathcal{R}}$$

$$\underset{2^{nd} col}{P \begin{pmatrix} 0 \\ 1 \end{pmatrix}}$$

$$P = \left(\begin{array}{c|c} [\vec{v}_1]_{\mathcal{R}} & [\vec{v}_2]_{\mathcal{R}} \\ \hline 1 & 1 \end{array} \right)$$

$$[\vec{v}_i]_R = \begin{pmatrix} 9 \\ 6 \end{pmatrix}$$

$$R = (\vec{u}_1, \vec{u}_2)$$

$$\vec{v}_1 = \underbrace{9\vec{u}_1}_{\text{old } 9,6} + \underbrace{6\vec{u}_2}$$

$$\begin{pmatrix} \vec{u}_1 & \vec{u}_2 \end{pmatrix} \begin{pmatrix} 9 \\ 6 \end{pmatrix} = \vec{v}_1$$

$$\begin{pmatrix} a_1 \\ b_1 \end{pmatrix} = \underbrace{\begin{pmatrix} \vec{u}_1 & \vec{u}_2 \end{pmatrix}^{-1}}_{\vec{v}_i}$$

$$\begin{pmatrix} a_1 & a_2 \\ b_1 & b_2 \end{pmatrix} = P$$

P

$$R P R$$

$$R \begin{pmatrix} \vec{v}_1 \\ \vec{v}_2 \end{pmatrix} R$$

$$\begin{pmatrix} P & R \\ R & P \end{pmatrix} \begin{pmatrix} P & R \\ R & P \end{pmatrix}^{-1} = \begin{pmatrix} P & R \\ R & P \end{pmatrix}^{-1}$$

$$P P$$

$$\begin{pmatrix} P & R \\ R & P \end{pmatrix}^{-1}$$

$$P = (\vec{v}_1, \dots, \vec{v}_n) \quad \mathcal{S}$$

$$P = \begin{pmatrix} \vec{v}_1 & \dots & \vec{v}_n \\ 1 & & 1 \end{pmatrix}$$

$$P \vec{p}_i = \vec{v}_i$$

$$P([v_i]_B) = \vec{v}_i = [v_i]_{\mathcal{S}}$$

p_i within B can

$$[p_i]_B \neq \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix} \mathcal{S}$$

$$\mathcal{S} P_B [v_i]_B = [v_i]_{\mathcal{S}}$$

$$\begin{pmatrix} 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 1 \\ 3 & 4 & 5 & 1 \\ 0 & 0 & 6 & 1 \end{pmatrix}$$

$rk \Rightarrow$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

4×4
 $b=0$

$if \quad rk \leq ?$

$$\begin{pmatrix} 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 1 \\ 3 & 4 & 5 & 1 \\ 0 & 0 & 6 & 1 \end{pmatrix}$$

$$\begin{matrix} b=0 \\ 2b=0 \end{matrix}$$

$rk \Rightarrow 4$

$$\begin{pmatrix} 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 1 \\ 3 & 4 & 5 & 1 \\ 0 & 0 & 6 & 1 \end{pmatrix}$$

$rk=4$
 $b \neq 0$

$$\begin{pmatrix} 0 & 1 & 2 & 1 \\ 3 & 4 & 5 & 1 \\ 0 & 0 & 6 & 1 \end{pmatrix}$$

g, c, d for
 $Sol \rightarrow G(r)$

$$\sim \begin{pmatrix} 3 & 4 & 5 \\ 0 & 1 & 2 \\ 0 & 0 & 6 \end{pmatrix} \quad \det = 18$$

$$b=0$$

$$\dim \ker(4r3 \text{ I wrote}) = 1$$

$$V = \left\{ \begin{pmatrix} a \\ 0 \\ d \end{pmatrix} \mid 124 \right\} \quad \dim V = 3$$

im(flat 944) contain is V

$$\begin{pmatrix} a \\ c \\ d \end{pmatrix} \rightarrow \times$$