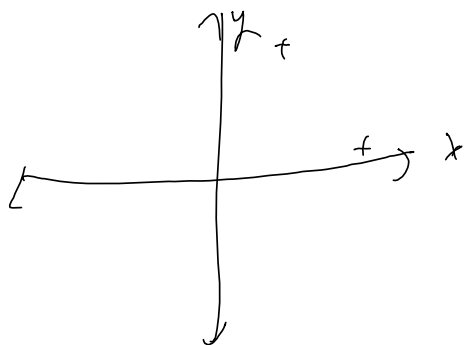


Right Handedness

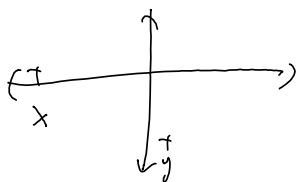
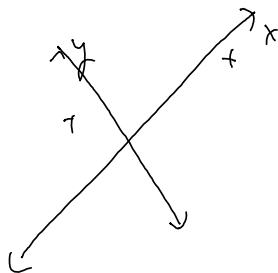
Consider the usual axes in $\mathbb{R}^2$



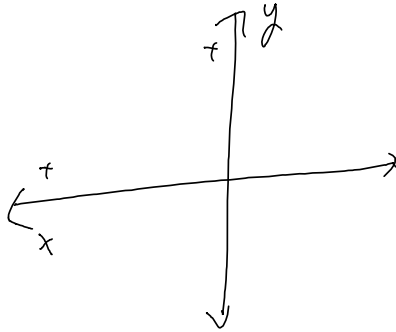
Here the positive x-axis is to the right of the positive y-axis.

If I rotate the axes, this orientation is

unchanged.

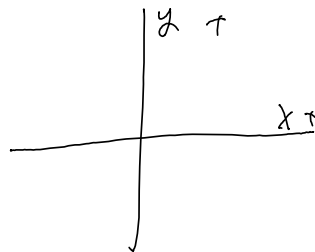


However, if I reflect the axes, this orientation flips,



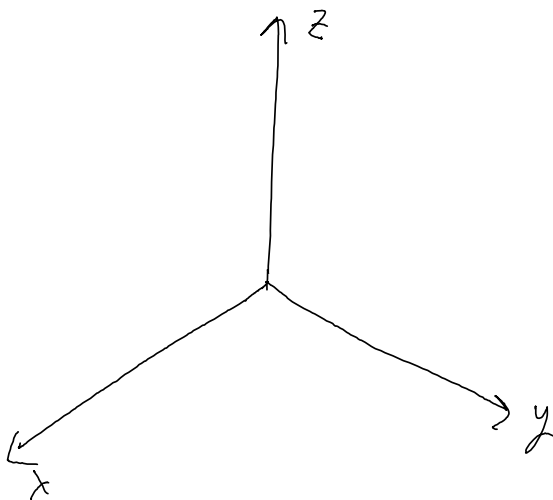
Now the positive x -axis is left of the positive y -axis,

The choice between the two is arbitrary, but we will choose the first one,



This motivates the situation in $\mathbb{R}^3$,

The standard axes are

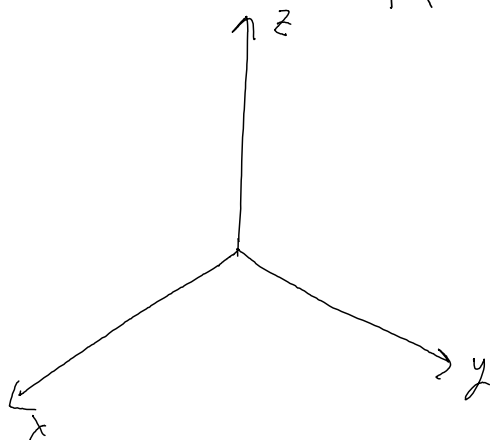


where the rays drawn are the positive directions

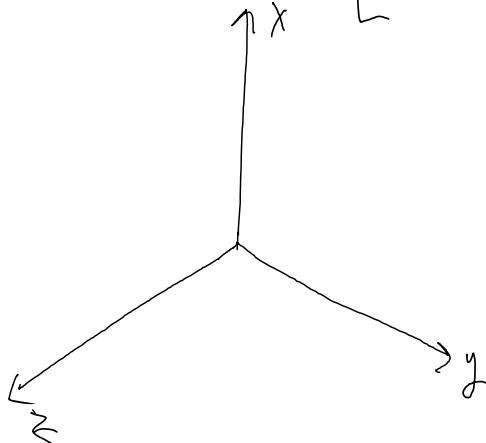
This is a right-handed system.

Examples

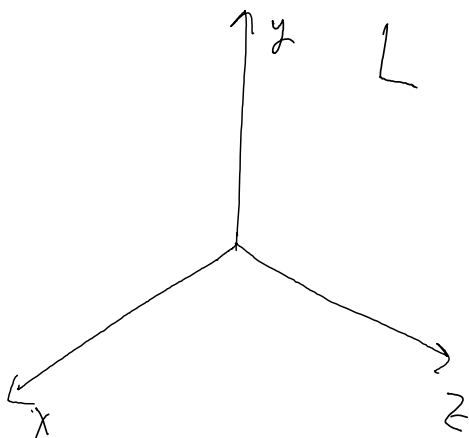
R



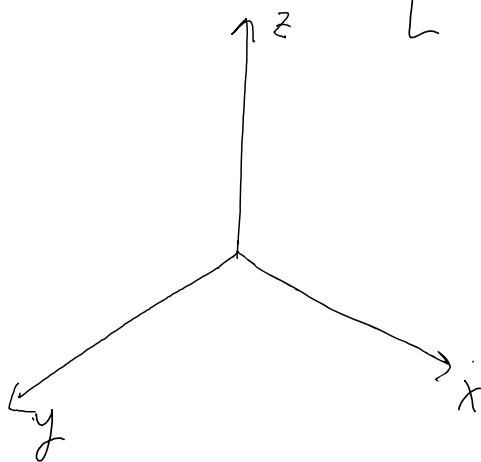
L



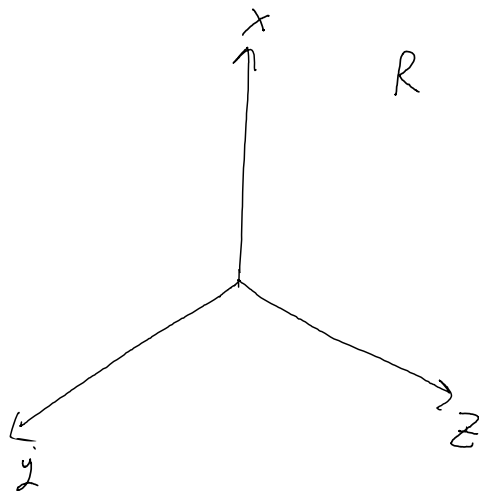
L



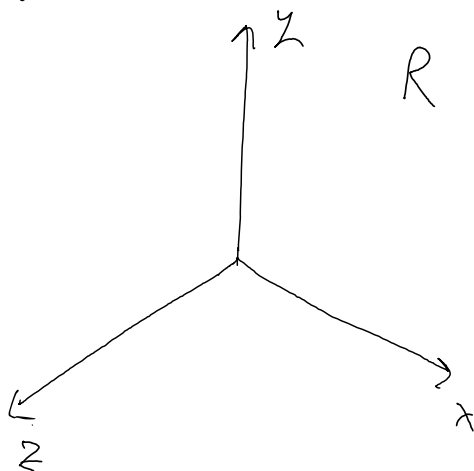
L



R



R



Cross products

First, an example

$$\langle 1, 2, 3 \rangle \times \langle -1, 0, 5 \rangle$$

$$\begin{aligned}\text{Method 1. } \det \begin{pmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 2 & 3 \\ -1 & 0 & 5 \end{pmatrix} &= \vec{i} \det \begin{pmatrix} 2 & 3 \\ 0 & 5 \end{pmatrix} - \vec{j} \det \begin{pmatrix} 1 & 3 \\ -1 & 5 \end{pmatrix} + \vec{k} \det \begin{pmatrix} 1 & 2 \\ -1 & 0 \end{pmatrix} \\ &= 10\vec{i} - 8\vec{j} + 2\vec{k} \\ &= \langle 10, -8, 2 \rangle\end{aligned}$$

$$\begin{aligned}\text{Method 2. } (\vec{i} + 2\vec{j} + 3\vec{k}) \times (-\vec{i} + 5\vec{k}) &= (-\cancel{\vec{i}} \times \vec{i} - 2\vec{j} \times \vec{i} - 3\vec{k} \times \vec{i}) \\ &\quad + (5\vec{i} \times \vec{k} + 10\vec{j} \times \vec{k} - 15\cancel{\vec{k}} \times \vec{k}) \\ &= 2\vec{k} - 3\vec{j} - 5\vec{j} + 10\vec{i} \\ &= \langle 10, -8, 2 \rangle\end{aligned}$$

Try: $\langle -1, 1, -1 \rangle \times \langle 0, 1, 2 \rangle$ with either method

$$A. \langle 3, 2, -1 \rangle$$

$$- \langle 0, -1, -2 \rangle \times \langle 1, 2, 0 \rangle$$

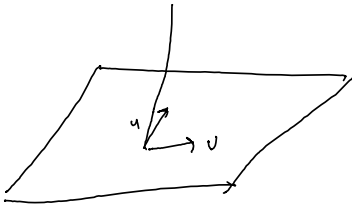
$$A. \langle 4, -2, 1 \rangle$$

Geometry of cross products

Facts, let $\vec{u}, \vec{v}$ be vectors in $\mathbb{R}^3$

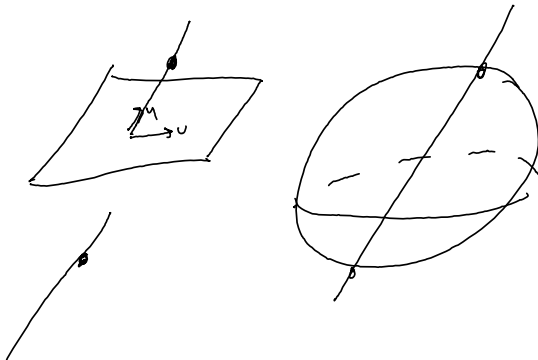
- i. $\vec{u} \times \vec{v}$ is orthogonal to $\vec{u}$ and $\vec{v}$
- ii. $\|\vec{u} \times \vec{v}\| = \|\vec{u}\| \|\vec{v}\| \sin(\theta)$
- iii. $\{\vec{u}, \vec{v}, \vec{u} \times \vec{v}\}$ is right handed

i.



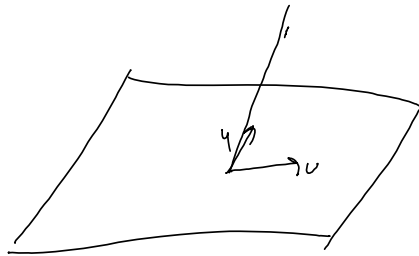
$\vec{u} \times \vec{v}$ is on this line

ii.



$\vec{u} \times \vec{v}$ is one of these 2 pts

iii.



$\swarrow \vec{u} \times \vec{v}$ is down here

Scalar Triple product

Can we algebraically check right handedness of
 $\rightarrow$ i.e. rough drawing
 3 vectors $\{\vec{u}, \vec{v}, \vec{w}\}$?

Yes! This is precisely when $\vec{w}$ is the same direction as $\vec{u} \times \vec{v}$

$$\text{when } \underbrace{(\vec{u} \times \vec{v}) \cdot \vec{w}} > 0$$

"Scalar triple product
 of $\vec{u}, \vec{v}, \vec{w}$ "

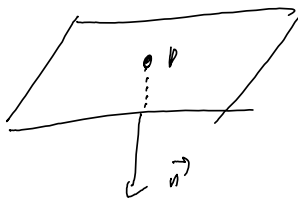
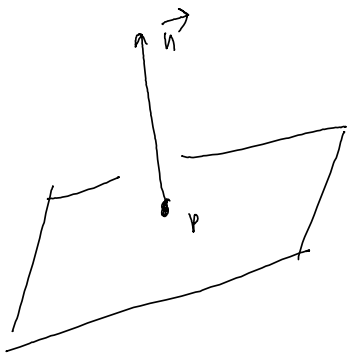
e.g. Is $\{\langle -1, 1, -1 \rangle, \langle 0, 1, 2 \rangle, \langle 0, 1, 3 \rangle\}$ right handed?

$\langle -1, 1, -1 \rangle \times \langle 0, 1, 2 \rangle = \langle 3, 2, -1 \rangle$ from before, $\langle 3, 2, -1 \rangle \cdot \langle 0, 1, 3 \rangle = -1$, so no

Planes

A plane is a flat 2d object in $\mathbb{R}^3$.

This is described by a point p and a normal vector $\vec{n}$.



The plane is the all the points q in $\mathbb{R}^3$ so that $\vec{pq}$ is orthogonal to $\vec{n}$.

Algebraically, this is equivalent to $\vec{pq} \cdot \vec{n} = 0$.

If $p = (p_1, p_2, p_3)$, $q = (x, y, z)$, $\vec{n} = \langle a, b, c \rangle$, this equation

simplifies to $0 = \langle x - p_1, y - p_2, z - p_3 \rangle \cdot \langle a, b, c \rangle$

$$0 = a(x - p_1) + b(y - p_2) + c(z - p_3)$$

This can be simplified to $ax+by+cz=d$ if needed,

e.g. $\vec{n} = \langle -1, 2, 1 \rangle$, $p = (4, 1, 5)$, what is the equation for the plane?

$$-1(x-4) + 2(y-1) + 1(z-5) = 0$$

$$-x + 4 + 2y - 2 + z - 5 = 0$$

$$-x + 2y + z = 3$$

$$- \vec{n} = \langle 1, 0, 0 \rangle, \quad p = (1, 2, 3)$$

$$(\hat{=} \vec{i})$$

$$x = 1$$

$$- \text{If the eqn for a plane is } 3x + 7y + 15z = -20,$$

what is a normal vector? $\langle 3, 7, 15 \rangle$

what is a point on the plane? $(0, 0, -\frac{20}{15})$.

Note the coefficients in front of x, y, z determine a normal vector.

- Find a plane through $(0, 5, 7)$ parallel to the xz plane,

xz plane is $y=0$, $\vec{n} = \langle 0, 1, 0 \rangle$,

so $y=5$ works

- Are $\underline{2x+3y+4z=1}$ and $4x+6y+8z=-10$ parallel? $\checkmark$

How about $\downarrow$ and $-2x-3y-4z=0$? $\checkmark$

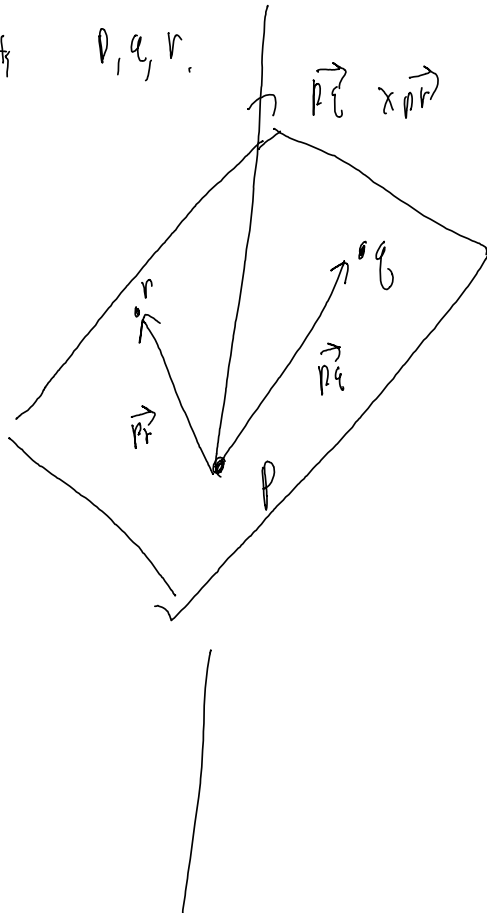
$$2x-3y+4z=10? \quad \times$$

Fact. Two planes are parallel precisely when they have parallel normal vectors

Recall that any two distinct points in $\mathbb{R}^2$
determine a unique line,

In $\mathbb{R}^3$, any three non-collinear points determine a
unique plane

Take points p, q, r . $\vec{pq} \times \vec{pr}$ is a normal vector!



$$t, q, \quad p = (1, 0, 0)$$

$$q = (2, 2, 3)$$

$$r = (0, 0, 5)$$

$$\vec{p} = \langle 1, 2, 3 \rangle$$

$$\vec{r} = \langle -1, 0, 5 \rangle$$

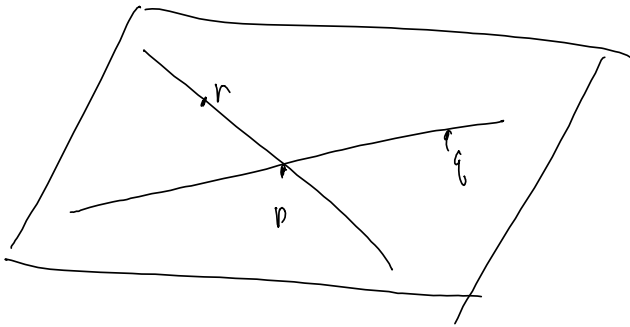
$$\vec{n} \times \vec{r} = \langle 10, -8, 2 \rangle, \text{ or, better}$$

to the plane is given by

$$10(x-1) - 8y + 2z = 0$$

$$10x - 8y + 2z = 10$$

Finally, if we have two distinct lines in $\mathbb{R}^3$ which intersect, there is a unique plane containing both lines.



Method. Find the intersection point. That's p

Find q, r , one on each line and distinct from p

Proceed as above, i.e. compute $\vec{n} = \vec{pq} \times \vec{pr}$.