

Yet another example of how the Poincaré Lemma proof construction works out: closed 2-form on \mathbb{R}^3 (in general)

$$\omega = P(x, y, z) dy \wedge dz - Q(x, y, z) dx \wedge dz + R(x, y, z) dx \wedge dy$$

$$d\omega = 0 \iff \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = 0.$$

$$H((x, y, z), t) = (tx, ty, tz) \quad (\text{contraction to } (0, 0, 0))$$

$$\text{Then } H_*(\frac{\partial}{\partial x}) = t \frac{\partial}{\partial x} \quad H_*(\frac{\partial}{\partial y}) = t \frac{\partial}{\partial y} \quad H_*(\frac{\partial}{\partial z}) = t \frac{\partial}{\partial z}$$

$$H_*(\frac{\partial}{\partial t}) = x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z}$$

We are interested in $i_{\frac{\partial}{\partial t}} H^* \omega$ (as usual)

$$\text{To compute this, we find } (i_{\frac{\partial}{\partial t}} H^* \omega)(\frac{\partial}{\partial x}), (i_{\frac{\partial}{\partial t}} H^* \omega)(\frac{\partial}{\partial y}), (i_{\frac{\partial}{\partial t}} H^* \omega)(\frac{\partial}{\partial z})$$

$$(i_{\frac{\partial}{\partial t}} H^* \omega)(\frac{\partial}{\partial x}) = \omega(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z}, \frac{\partial}{\partial x}) = zt Q \Big|_{(tx, ty, tz)} - yt R \Big|_{(tx, ty, tz)}$$

$$(i_{\frac{\partial}{\partial t}} H^* \omega)(\frac{\partial}{\partial y}) = -zt P + Rxz, \quad P, R \text{ evaluated at } (tx, ty, tz)$$

$$(i_{\frac{\partial}{\partial t}} H^* \omega)(\frac{\partial}{\partial z}) = yt P - xt Q, \quad P, Q \text{ evaluated at } (tx, ty, tz)$$

$$\begin{aligned} \text{So } i_{\frac{\partial}{\partial t}} H^* \omega &= t \left(zt Q \Big|_{(tx, ty, tz)} - yt R \Big|_{(tx, ty, tz)} \right) dx \\ &\quad + \left(xt R \Big|_{(tx, ty, tz)} - zt P \Big|_{(tx, ty, tz)} \right) dy \\ &\quad + \left(yt P \Big|_{(tx, ty, tz)} - xt Q \Big|_{(tx, ty, tz)} \right) dz \end{aligned}$$

The "Poincaré expectation" is that ($F_t \cdot \cdot$) = $H(\cdot, t)$ as usual

$$\omega = F_t^* \omega - F_0^* \omega = \int_0^1 d \left(i_{\frac{\partial}{\partial t}} H^* \omega \right) dt$$

We shall check this now: it is simply a matter of differentiating carefully and integrating by parts

First, we check that the coefficient of $dx \wedge dy$ in
 $\int_0^1 d_{R^3} (i_{\frac{\partial}{\partial t}} H^* \omega)$ actually is $R(x, y, z)$ when evaluated at (x, y, z) . For this, we note that

$\frac{\partial(Q|_{(tx, ty, tz)})}{\partial x} = t \left(\frac{\partial Q}{\partial x} \Big|_{(tx, ty, tz)} \right)$ and similarly for other "space" derivatives of P, Q , or R , each evaluated at (tx, ty, tz) , i.e. $\frac{\partial}{\partial(x \text{ or } y \text{ or } z)} (P|_{(tx, ty, tz)} \text{ or } Q|_{(tx, ty, tz)} \text{ or } R|_{(tx, ty, tz)})$.

$$\begin{aligned} \text{Now the coefficient in } d_{R^3} (i_{\frac{\partial}{\partial t}} H^* \omega) \text{ of } dx \wedge dy &= \\ &= -\frac{\partial}{\partial y} (\text{coeff. of } dx \text{ in } i_{\frac{\partial}{\partial t}} H^* \omega) + \frac{\partial}{\partial x} (\text{coeff. of } dy \text{ in } i_{\frac{\partial}{\partial t}} H^* \omega) \\ &= t \left(-\frac{\partial}{\partial y} (z Q|_{(tx, ty, tz)} - y R|_{(tx, ty, tz)} \right. \\ &\quad \left. + \frac{\partial}{\partial x} (x R|_{(tx, ty, tz)} - z P|_{(tx, ty, tz)}) \right) \\ &= t \left(R|_{(tx, ty, tz)} + y \frac{\partial}{\partial y} (R|_{(tx, ty, tz)}) - z \frac{\partial}{\partial y} (Q|_{(tx, ty, tz)}) \right. \\ &\quad \left. + R|_{(tx, ty, tz)} + x \frac{\partial}{\partial x} (R|_{(tx, ty, tz)}) - z \frac{\partial}{\partial x} (P|_{(tx, ty, tz)}) \right) \\ &= 2t R|_{(tx, ty, tz)} + t^2 y \frac{\partial R}{\partial y}|_{(tx, ty, tz)} \\ &\quad + t^2 x \frac{\partial R}{\partial x}|_{(tx, ty, tz)} + t^2 z \frac{\partial R}{\partial z}|_{(tx, ty, tz)} \end{aligned}$$

where we used $-z \frac{\partial}{\partial y} (Q|_{(tx, ty, tz)}) - z \frac{\partial}{\partial x} (P|_{(tx, ty, tz)})$

$$\begin{aligned} &= -tz \left(\frac{\partial Q}{\partial y}|_{(tx, ty, tz)} + \frac{\partial P}{\partial x}|_{(tx, ty, tz)} \right) \\ &= t + z \frac{\partial R}{\partial z}|_{(tx, ty, tz)} \end{aligned}$$

(here we use ω is closed!
- we had to use it somewhere!)

$$\text{Next note that } t^2 \times \frac{\partial R}{\partial y} \Big|_{(tx, ty, tz)} + t^2 y \frac{\partial R}{\partial y} \Big|_{(tx, ty, tz)} + t^2 z \frac{\partial R}{\partial z} \Big|_{(tx, ty, tz)} \\ = t^2 \frac{\partial}{\partial t} (R \Big|_{(tx, ty, tz)}) \text{ by the Chain Rule.}$$

$$\text{So } \int_0^1 (\text{dx} \wedge \text{dy} \text{ coef of } d_{\mathbb{R}^3} \left(i_0 \frac{\partial}{\partial t} H^t \omega \right) dt = \\ \int_0^1 [2t R \Big|_{(tx, ty, tz)} + t^2 \frac{\partial}{\partial t} (R \Big|_{(tx, ty, tz)})] dt \\ = \int_0^1 \frac{\partial}{\partial t} (t^2 R \Big|_{(tx, ty, tz)}) dt = t^2 R \Big|_{(x, y, z)} - 0^2 R \Big|_{(0, 0, 0)} \\ = R(x, y, z), \text{ as we hoped.}$$

The calculations that the coefficient of $dy \wedge dz$ is P and of $dx \wedge dt$ is $-Q$ are similar and are left as exercises.

Note that the pattern here suggests a way to prove by direct calculation the Poincaré Lemma (for $1 \leq k \leq n$) for \mathbb{R}^n (or a ball in \mathbb{R}^n) in the case of the contraction to a point being multiplication by $t \in [0, 1]$ (k forms). We do not really need this direct proof since we have the general proof using $\mathcal{L}_X = dix + i_X d$, but it is interesting to note that the direct proof could be developed from this example. (One supposes that something like this was what Volterra used in the first place).