

Constrained Optimization

$$\begin{aligned} \min & f(x) \\ \text{s.t.} & h(x) = 0 \\ & g(x) \leq 0 \end{aligned}$$

Lagrangian

$$L(x, \lambda, \mu) = f(x) + \lambda^T h(x) + \mu^T g(x)$$

KKT Conditions:

(Under certain conditions),
At an optimizer x^* , there exist λ^*, μ^* ,
such that the following conditions hold:

$$\left. \begin{aligned} (1) & h(x) = 0 \\ (2) & g(x) \leq 0 \end{aligned} \right\} \text{Primal Feasibility}$$

$$(3) \nabla_x L(x, \lambda, \mu) = \nabla_x f(x^*) + \lambda^{*T} D_x h(x^*) + \mu^{*T} D_x g(x^*) = 0$$

$$(4) \mu^* \geq 0 \quad \left. \right\} \text{Dual Feasibility}$$

$$\left. \begin{aligned} (5) & \mu_i^* g(x_i^*) = 0 \\ & \mu_p^* g(x_p^*) = 0 \end{aligned} \right\} \begin{array}{l} \text{Complementary} \\ \text{Slackness} \end{array}$$

$$\min x_1 x_2^2$$

$$\text{s.t. } \begin{cases} x_1 - x_2 = 0 & \lambda & (1) \\ x_1 \geq 0 & \mu & (2) \end{cases}$$

$$L(x_1, x_2, \lambda, \mu)$$

$$= x_1 x_2^2 + \lambda (x_1 - x_2) - \mu x_1$$

$$\text{KKT: } (3) \nabla_x L = \begin{pmatrix} x_2^2 + \lambda - \mu \\ 2x_2 - \lambda \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$(4) \mu \geq 0$$

$$(5) \mu x_1 = 0$$

$$\Rightarrow \lambda = 2x_2 x_2$$

$$\Rightarrow \lambda = 2x_2^2$$

$$x_2^2 + 2x_2^2 - \mu = 0$$

$$\text{If } x_1 > 0, \Rightarrow \mu = 0 \Rightarrow x_2^2 + 2x_2^2 = 0$$

$$3x_2^2 = 0$$

$$\Rightarrow x_2 = 0, \text{ which contradicts } x_1 = x_2$$

~~$\forall x_1 = 0, \Rightarrow$~~

Contradicts $x_1 = x_2$

$$\text{If } x_1 = 0, \text{ then } x_2 = 0, \lambda, \mu = 0$$

So only point satisfying KKT conditions is $x_1 = 0, x_2 = 0$.

$$\begin{aligned} \min \quad & 2x_1 + 3x_2 - 4 \\ \text{s.t.} \quad & x_1 x_2 = 6 \end{aligned}$$

$$L(x_1, x_2, \lambda) = 2x_1 + 3x_2 - 4 + \lambda(x_1 x_2 - 6)$$

$$\nabla_x L = \begin{pmatrix} 2 + \lambda x_2 \\ 3 + \lambda x_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\text{z.B. } \lambda = -\frac{2}{x_2}$$

$$\text{z.B. } 3 - 2\frac{x_1}{x_2} = 0$$

$$\begin{aligned} (\Rightarrow) \quad & 3 = 3x_1 = 2x_2 \Rightarrow 3x_1 x_2 = 2x_2^2 \\ & \Rightarrow 3 \cdot 6 = 2x_2^2 \Rightarrow x_2 = \pm \sqrt{9} \\ & \Rightarrow x_2 = \pm 3 \end{aligned}$$

$$x_1 = \pm 2$$

$$\min \frac{1}{2} \|x\|^2$$

$$\text{s.t. } Ax = b$$

$$L(x, \lambda) = \frac{1}{2} \|x\|^2 + \lambda(Ax - b)$$

$$\nabla_x L = x + A^T \lambda = 0$$

$$= Ax + AA^T \lambda = 0$$

$$b + AA^T \lambda \Rightarrow x = -(AA^T)^{-1} b$$

$$\begin{aligned} x &= -A^T \lambda \\ &= A^T (AA^T)^{-1} b \end{aligned}$$