

Some foundational questions (and some answers) about algorithms

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LSFA Workshop, Fortaleza, 26 September, 2018

There is no standard definition of **algorithms**

... which makes it difficult to formulate and prove results about **all** of them; but we can try!

- Using as a basic example the classical **Euclidean algorithm** which computes the **greatest common divisor** of two numbers, I will ask some natural questions about algorithms
- More than half the lecture will be dedicated to introducing intuitively and then formulating precise versions of these questions
- At the end I will discuss answers to three of these questions which are somewhat surprising
- I will simplify a little, but (quoting John Steel) **all lies are white**
- ▶ This material is from the monograph
Abstract recursion and intrinsic complexity (ARIC)
forthcoming in the *Lecture Notes in Logic* series published by the Association for Symbolic Logic and Cambridge University Press

The Euclidean algorithm ε (with division) for $\text{gcd}(x, y)$

- The **Division Theorem** for $\mathbb{N} = \{0, 1, \dots\}$: For $x, y \in \mathbb{N}$ with $y > 0$, there are unique numbers $q = \text{iq}(x, y)$, $r = \text{rem}(x, y)$ such that

$$x = yq + r, \quad 0 \leq r < y$$

- $\text{gcd}(x, y) = \max\{t \mid \text{rem}(x, t) = \text{rem}(y, t) = 0\}$ ($x, y \geq 1$)
- Specification** of ε by a while program: given $x, y \in \mathbb{N}$:

(ε) `while` $y \neq 0$ { $x := y$; $y := \text{rem}(x, y)$ } `return` x

- **Fact.** *If $y = 0$, then ε returns x , and if $y \neq 0$, then ε returns $\text{gcd}(x, y)$*

- Equivalent specification** of ε by a recursive program:

- **Fact.** *The **recursive equation** (in the **function variable** p)*

(ε) $p(x, y) = \text{if } (y = 0) \text{ then } x \text{ else } p(y, \text{rem}(x, y))$

has a unique (total) solution $\bar{p}(x, y)$, and

$$\bar{p}(x, y) = \text{if } (y = 0) \text{ then } x \text{ else } \bar{p}(x, y) = \text{gcd}(x, y)$$

The complexity of the Euclidean

- $c_\varepsilon(x, y)$ = the **number of calls** to `rem` that ε makes on the input x, y
(We do not count calls to `eq0(y)` $\iff y = 0$ —we could)
- ▶ **Fact:** If $x \geq y \geq 2$, then $c_\varepsilon(x, y) \leq 2 \log y \leq 2 \log x$ ($\log = \log_2$)
- **Basic question:** Is the Euclidean **optimal** (in some natural sense), on some infinite set of inputs?
- **Main Conjecture:** For every algorithm α from `rem` and `eq0` which computes `gcd(x, y)` when $x, y \geq 1$, there is a number $\delta > 0$, such that for infinitely many pairs (x, y) with $x > y \geq 1$,
 $c_\alpha(x, y) =$ the number of calls α makes to `rem` $\geq \delta \log x$
- The Main Conjecture is not about Turing machines with oracles, which can compute `gcd(x, y)` with no oracle calls at all
- ▶ **Fact.** For the **Fibonacci numbers** $F_0 = 0, F_1 = 1, F_{k+2} = F_k + F_{k+1}$,
 $c_\varepsilon(F_{k+1}, F_k) \geq (1/2)\varphi \log F_{k+1}$ (where $\varphi = (1/2)(1 + \sqrt{5})$, $k \geq 2$)

Partial functions and (partial) structures

- A **partial function** $f : X \rightarrow W$ is a (total) function $f : D_f \rightarrow W$ on some set $D_f \subseteq X$, its **domain of convergence**
- $f(x) \downarrow \iff x \in D_f, \quad f(x) \uparrow \iff x \notin D_f,$
 $f(x) = g(x) \iff [f(x) \uparrow \ \& \ g(x) \uparrow] \vee (\exists w \in W)[f(x) = g(x) = w],$
 $f \sqsubseteq g \iff (\forall x)[x \in D_f \implies f(x) = g(x)],$
 $f(g(x), h(x)) = w$
 $\iff (\exists u, v)[g(x) = u \ \& \ h(x) = v \ \& \ f(u, v) = w]$
- **Unified notation** for n -ary partial functions and relations on a set A :

$$f : A^n \rightarrow A_s \quad (s \in \{\text{ind}, \text{bool}\}, A_{\text{ind}} = A, A_{\text{bool}} = \{\text{tt}, \text{ff}\})$$

- A **vocabulary** is a finite set $\Phi = \{\varphi_1, \dots, \varphi_m\}$ of **function symbols**, each with an assigned **sort** s and **arity** n_i
- A (partial) Φ -**structure** is a tuple $\mathbf{A} = (A, \Phi) = (A, \varphi_1^{\mathbf{A}}, \dots, \varphi_m^{\mathbf{A}})$, where for each i , $\varphi_i^{\mathbf{A}} : A^{n_i} \rightarrow A_s$
- (Structures with many **sorts** (**data types**) are **disjoint unions** of these)

Two kinds of algorithms on a Φ -structure $\mathbf{A} = (A, \Phi)$

- With variables v_i of **sort** `ind` over A (and obvious restrictions):

(Terms) $E ::= v_i \mid \varphi_i(E_1, \dots, E_n) \mid \text{if } E_0 \text{ then } E_1 \text{ else } E_2$

- ▶ (1) The **iterative algorithms of \mathbf{A}** (of sort `ind` or `bool`) are specified by **while programs**, using partial functions on A defined by terms
 - these include all algorithms on \mathbf{A} specified by the familiar **computation models** (Turing machines, straight line and finite register programs, decision trees, random access machines, etc.)

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- Adding **pf variables** $p_i^{n,\text{ind}}, p_i^{n,\text{bool}}$ on A of every **arity** $n \in \mathbb{N}$:

(Terms) $E ::= v_i \mid p_i^{n,s}(E_1, \dots, E_n) \mid \varphi_i(E_1, \dots, E_n) \mid \text{if } E_0 \text{ then } E_1 \text{ else } E_2$

- ▶ (2) The **recursive algorithms of \mathbf{A}** are specified by **recursive programs**

$$E ::= E_0 \text{ where } \left\{ p_1(\vec{u}_1) = E_1, \dots, p_K(\vec{u}_K) = E_K \right\}$$

- Compute: plug the **least fixed points** $\bar{p}_1, \dots, \bar{p}_K$ of the **body** into E_0

Iteration vs. recursion on a (“nice”, infinite) structure \mathbf{A}

- If $f : A^n \rightarrow A_s$ with $s = \text{ind}$ or $s = \text{boole}$:

f is **iterative** on \mathbf{A} \iff f is computed in \mathbf{A} by a while program,
 f is **recursive** in \mathbf{A} \iff f is computed in \mathbf{A} by a recursive program

- ▶ **Fact. Reduction of iteration to recursion:** *Every iterative partial function of \mathbf{A} is recursive in \mathbf{A} (effectively)*
- ▶ **Fact. Partial reduction of recursion to iteration:** *Every recursive partial function of \mathbf{A} is iterative in an **expansion of an extension of \mathbf{A}***
(defined by an **implementation** of the recursive program which computes f)
- ▶ **Fact** (Patterson-Hewitt 1970, Stolboushkin-Taitslin 1983, Tiuryn 1989):
There are (nice, total) structures \mathbf{A} in which some total relation $f : A^n \rightarrow \{\# , ff\}$ is recursive but not iterative (Tiuryn’s is a forest)
- *The distinction between **interaction** and **recursion** is not trivial and foundationally significant* (Recent work by Neil Jones, Siddharth Bhaskar, ...)

Counting calls to primitives for recursive programs

Fix a Φ -structure \mathbf{A} and a recursive program

$$E ::= E_0 \text{ where } \{p_1(\vec{u}_1) = E_1, \dots, p_K(\vec{u}_K) = E_K\}$$

of \mathbf{A} which computes $f_E : A^n \rightarrow A_s$ ($s \in \{\text{ind}, \text{bool}\}$)

- For each $\Phi_0 \subseteq \Phi = \{\varphi_1, \dots, \varphi_m\}$, there is a function

$$c_E(\Phi_0) : \{\vec{x} \in A^n \mid f_E(\vec{x}) \downarrow\} \rightarrow \mathbb{N} \text{ such that (intuitively)}$$

(*) $c_E(\Phi_0)(\vec{x}) =$ the number of calls to $\varphi_i^{\mathbf{A}}$ (with $\varphi_i \in \Phi_0$) that E makes to compute $f(\vec{x})$ ($f(\vec{x}) \downarrow$)

- $c_E(\Phi_0)(\vec{x})$ is determined by the least-fixed-point **definition** of $f_E(\vec{x})$

- ▶ **Fact.** *If E is (the recursive program expressing) a while program in \mathbf{A} , then (??) is a theorem*
- ▶ **Fact.** *If E^* is a (standard) while program implementing E (in an expansion of an extension of \mathbf{A}), then $c_E(\Phi_0)(\vec{x}) = c_{E^*}(\Phi_0)(\vec{x})$ ($\vec{x} \in A^n$)*

Counting all calls for recursive programs

Fix a recursive program E of \mathbf{A} which computes $f_E : A^n \rightarrow A_s$

$c_E(\vec{x}) = c_E(\Phi)(\vec{x})$ = the number of **calls to all the primitives** that E makes to compute $f(\vec{x})$ ($f(\vec{x}) \downarrow$)

- **Logical calls:** $p_i(E_1, \dots, E_n)$ if E_0 then E_1 else E_2 : (roughly, add 1)

- There is a function $l_E : \{\vec{x} \in A^n \mid f_E(\vec{x}) \downarrow\} \rightarrow \mathbb{N}$ such that

(**) $l_E(\vec{x})$ = the number of **all calls** (to the primitives or logical) that E makes to compute $f(\vec{x})$ ($f(\vec{x}) \downarrow$)

- $l_E(\vec{x})$ is defined directly from the least-fixed-point definition of $f_E(\vec{x})$

- It counts the (logical) **time** required by E to compute $f_E(\vec{x})$

- **Fact.** If E is a while program, then (with the usual definition of time for while programs)

$$l_E(\vec{x}) = \Theta(\text{Time}_E(\vec{x})) \quad (f_E(\vec{x}) \downarrow)$$

Tserunyan's First Theorem

Fix a recursive program E of \mathbf{A} which computes $f_E : A^n \rightarrow A_s$

$c_E(\vec{x})$ = the number of calls to the primitives that

E makes to compute $f_E(\vec{x})$ ($f_E(\vec{x}) \downarrow$)

$l_E(\vec{x})$ = the number of all calls

that E makes to compute $f_E(\vec{x})$ ($f_E(\vec{x}) \downarrow$)

so clearly $c_E(\vec{x}) \leq l_E(\vec{x})$ ($f_E(\vec{x}) \downarrow$)

- **Theorem** (Anush Tserunyan, in her 2013 Ph.D. Thesis). *There is a constant $K = K_{E,\mathbf{A}} \in \mathbb{N}$ such that*

$$l_E(\vec{x}) \leq K(c_E(\vec{x}) + 1) \quad (f_E(\vec{x}) \downarrow)$$

- It provides an explanation of why all the proofs of **lower bounds** for queries on structures (that I know) count **needed calls to the primitives** and derive a lower bound for time
- The complexity functions $c_E(\vec{x})$, $l_E(\vec{x})$ are defined on recursive programs, not on **implementations**

Non-deterministic recursion

- A **nondeterministic** (nd) recursive program of a structure \mathbf{A} is just like a (deterministic) program

$$E ::= E_0 \text{ where } \left\{ p_1(\vec{u}_1) = E_1, \dots, p_K(\vec{u}_K) = E_K \right\}$$

except that we allow $p_i \equiv p_j$ for some i, j

- **Pratt's nuclid program** of the Euclidean structure $(\mathbb{N}, \text{rem}, \text{eq}_0)$:

$$E_P \equiv \text{nuclid}(a, b, a, b) \text{ where } \left\{ \right.$$

$\text{nuclid}(a, b, m, n) =$ if $(n \neq 0)$ then $\text{nuclid}(a, b, n, \text{rem}(\text{choose}(a, b, m), n))$,
else if $(\text{rem}(a, m) \neq 0)$ then $\text{nuclid}(a, b, m, \text{rem}(a, m))$,
else if $(\text{rem}(b, m) \neq 0)$ then $\text{nuclid}(a, b, m, \text{rem}(b, m))$,
else m ,

$$\text{choose}(a, b, m) = m, \quad \text{choose}(a, b, m) = a, \quad \text{choose}(a, b, m) = b$$

- Fixed point semantics and the complexity functions $c_E(\vec{x})$, $l_E(\vec{x})$ can be extended to nd programs (with some work)

► *nuclid computes gcd(x, y)*

A lower bound for coprimeness

- Def. **Difficult pairs**. A pair of numbers (x, y) is difficult if $2 \leq y < x < 2y$, $x \perp y$ and (some technical condition)
- ▶ Every pair (F_{k+1}, F_k) of successive Fibonacci with $k \geq 3$ is difficult; every solution (x, y) of **Pell's equation** $x^2 = 1 + 2y^2$ is difficult; ...
- ▶ **Theorem** (Lou van den Dries, ynm, 2004) *If E is a nd recursive program on $(\mathbb{N}, 0, 1, =, <, +, \div, \text{iq}, \text{rem})$ which computes $\text{gcd}(x, y)$:*

for every difficult pair (x, y) ,
$$c_E(\text{rem})(x, y) \geq \frac{1}{10} \log \log x$$

- ▶ A precise version of the **Main Conjecture**: *For every (deterministic) recursive program E of $(\mathbb{N}, \text{eq}_0, \text{rem})$ which computes $\text{gcd}(x, y)$ when $x, y \geq 1$, there is a number $\delta > 0$, such that*

for infinitely many pairs (x, y) with $x > y \geq 1$,
$$c_E(\text{rem})(x, y) \geq \delta \log x$$

- The theorem gives a **nondeterministic complexity inequality** which is **one log below** the claim of the Main Conjecture—too weak!

The calls complexity of Pratt's nuclid

- ▶ **Corollary**(vdd,ynm). For every nd recursive program E on $(\mathbb{N}, 0, 1, =, <, +, \div, iq, rem)$ which computes $\gcd(x, y)$,

$$c_E(rem)(F_{k+1}, F_k) \geq \frac{1}{10} \log \log F_{k+1} \quad (k \geq 2)$$

- ▶ **Pratt's Theorem** (2008) If E_P is Pratt's nd recursive nuclid program of the Euclidean structure (\mathbb{N}, rem, eq_0) which computes $\gcd(x, y)$, then

$$c_{E_P}(rem)(F_{k+1}, F_k) \leq r \log \log F_{k+1} \quad (\text{some } r, \text{ all } k \geq 3)$$

- So: vdd and ynm (2004, 2009) have **the best version of their Theorem** — but the main conjecture could be true with another infinite set of pairs; **it is still open**
- It may be that **the Main conjecture is true but only for deterministic programs**

Comments

- The most interesting foundational aspects of this work are that
 - (1) the partial function computed by a recursive program and
 - (2) its complexity measuresare defined directly from the program (by fixed point recursion) rather than through its implementation.
 - (1) simplifies greatly **proofs of correctness**, which come down to showing that **the function which we want our algorithm to compute** (together with some auxiliary functions) **satisfy a system** and is often trivial; and
 - (2) insures that lower bounds for algorithms proved for these complexities hold for all (correct) implementations