

Recursive algorithms from specified primitives

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What is an algorithm?

- **Algorithms are not just Turing machines!** (later)
and there is no generally accepted definition of what they are
 - Many classical notions were **defined** after centuries of study:
The **natural numbers** $\mathbb{N} = \{0, 1, \dots\}$, ? – 1870s (Dedekind)
The **real numbers** \mathbb{R} , ? – 1870s (Dedekind, Cantor)
Random variables, 1700s – 1931 (Kolmogorov)
 - A precise definition of a notion should make it possible to give rigorous proofs of results which have been proved intuitively; and so I will start with an elementary discussion of some classical algorithms
- ▶ This material is (mostly) from the monograph
Abstract recursion and intrinsic complexity (ARIC)
forthcoming in the *Lecture Notes in Logic* series published by the
Association for Symbolic Logic and Cambridge University Press

The Euclidean algorithm ε (with division) for $\text{gcd}(x, y)$

- The **Division Theorem** for $\mathbb{N} = \{0, 1, \dots\}$: For $x, y \in \mathbb{N}$ with $y > 0$, there are unique numbers $q = \text{iq}(x, y)$, $r = \text{rem}(x, y)$ such that

$$x = yq + r, \quad 0 \leq r < y$$

$$\text{gcd}(x, y) = \max\{t \mid \text{rem}(x, t) = \text{rem}(y, t) = 0\} \quad (x, y \geq 1)$$

- Specification** of ε by a **while program**: given $x, y \in \mathbb{N}$:

(ε) while $y \neq 0$ $\left\{ x := y; \quad y := \text{rem}(x, y) \right\}$ return x

- **Fact.** *If $y = 0$, then ε returns x , and if $y \neq 0$, then ε returns $\text{gcd}(x, y)$*

- Equivalent specification** of ε by a **recursive equation**:

- **Fact.** *The **recursive equation** (in the **function variable** p)*

(ε) $p(x, y) = \text{if } (y = 0) \text{ then } x \text{ else } p(y, \text{rem}(x, y))$

has a unique (total) solution $\bar{p}(x, y)$, and

$$\bar{p}(x, y) = \text{if } (y = 0) \text{ then } x \text{ else } \bar{p}(x, y) = \text{gcd}(x, y)$$

The complexity of the Euclidean

- $c_\varepsilon(x, y)$ = the **number of calls** to `rem` that ε makes on the input x, y
(We do not count calls to `eq0(y)` $\iff y = 0$ —we could)

► **Fact:** If $x \geq y \geq 2$, then $c_\varepsilon(x, y) \leq 2 \log y \leq 2 \log x$ ($\log = \log_2$)

- **Basic question:** Is the Euclidean **optimal** (in some natural sense), on some infinite set of inputs?
- **Main Conjecture:** For every algorithm α from `rem` and `eq0` which computes `gcd(x, y)` when $x, y \geq 1$, there is a number $\delta > 0$, such that for infinitely many pairs (x, y) with $x > y \geq 1$,

$$c_\alpha(x, y) = \text{the number of calls } \alpha \text{ makes to } \text{rem} \geq \delta \log x$$

- The Main Conjecture is not about Turing machines with oracles, which can compute `gcd(x, y)` with no oracle calls at all
- **Fact.** For the **Fibonacci numbers** $F_0 = 0$, $F_1 = 1$, $F_{k+2} = F_k + F_{k+1}$,
 $c_\varepsilon(F_{k+1}, F_k) = k - 1 \geq (1/2)\varphi \log F_{k+1}$ ($\varphi = (1/2)(1 + \sqrt{5})$, $k \geq 2$)

Variations of the Euclidean

- **Coprimeness:** $x \perp y \iff x, y \geq 1 \ \& \ \gcd(x, y) = 1$
 $(\varepsilon_{\perp}) \text{ while } y \neq 0 \left\{ \begin{array}{l} x := y; y := \text{rem}(x, y) \end{array} \right\}$
 $\text{return} \left(\text{if } (x = 1) \text{ then tt else ff} \right)$
- ▶ **Fact.** *If $x, y \geq 1$, then ε_{\perp} decides $x \perp y$*
- ε_{\perp} can also be specified by a **system of two recursive equations**
- $K(X)$ = the *ring* of polynomials in the indeterminate X over the *field* K
- ▶ **Fact.** *The natural version of the Euclidean on $K(X)$ computes the (monic) polynomial $\gcd(P(x), Q(X))$*
- ▶ **Fact.** *The ***Sturm algorithm*** is a minor variation of the Euclidean on \mathbb{N}, \mathbb{R} , and $\mathbb{R}(X)$ which, given $P(X) \in \mathbb{R}(X)$ and an open interval (α, β) in \mathbb{R} , computes the number of real roots of $P(X)$ in (α, β)*
- These algorithms act on complex inputs and use primitives which are not “computable” in any intuitive way—e.g., $\alpha = 0$ on \mathbb{R} ;
— their “implementations” for all inputs bring in **numerical analysis**

The mergesort algorithm

- Suppose L is a set with a fixed (total) ordering \leq on it.
- A **string** $v = (v_0, \dots, v_{n-1}) = v_0 v_1 \cdots v_{n-1} \in L^*$ is **sorted** if $v_0 \leq v_1 \leq \cdots \leq v_{n-1}$, and for each $u \in L^*$,
$$\text{sort}(u) = \text{the unique sorted "rearrangement" of } u$$
- ▶ **Fact.** *The two recursive equations (on L, L^* , with variables p , merge)*
$$p(u) = \text{if } |u| \leq 1 \text{ then } u \text{ else merge}(p(\text{half}_1(u)), p(\text{half}_2(u)))$$
$$\text{merge}(w, v) = \text{if } |w| = 0 \text{ then } v \text{ else if } |v| = 0 \text{ then } w$$
$$\text{else if } (\text{head}(w) \leq \text{head}(v)) \text{ then cons}(\text{head}(w), \text{merge}(\text{tail}(w), v))$$
$$\text{else cons}(\text{head}(v), \text{merge}(w, \text{tail}(v)))$$

has unique (total) solutions \bar{p} , $\overline{\text{merge}}$, and $\boxed{\text{sort}(u) = \bar{p}(u)}$
- There is a natural, more detailed system of four equations which expresses the mergesort from \leq and the primitives of Lisp
$$\text{nil} = (), \text{eq}_{\text{nil}}(u), \text{head}(u) = u_0, \text{tail}(u), \text{cons}(s, u) = su_0 \cdots u_{n-1}$$

The complexity of sorting

- There is no single `while` program which expresses faithfully
the algorithm from the primitives of Lisp and \leq
defined by the mergesort
 - because to compute $\text{merge}(p(\text{half}_1(u)), p(\text{half}_2(u)))$ you have to decide whether to compute the two values $p(\text{half}_1(u))$ and $p(\text{half}_2(u))$ together, **in parallel** or **in sequence**, in one of two orders

- **Fact** (proved in every class on algorithms). *For the mergesort μ , if*

$$c_\mu(u) = \text{the number of calls to } \leq \text{ that } \mu \text{ makes on the input } u,$$

then $c_\mu(u) \leq |u| \log |u|$ (Proved “intuitively” by induction on $|u|$)

- **Fact** (proved in every class on complexity). *If α is any **sorting algorithm that uses comparisons**, then $(\exists u)[c_\alpha(u) \geq |u| \log |u|]$*

- A rigorous formulation and proof can be given if α is specified by a `while` program from \leq and the Lisp primitives

Partial functions and (partial) structures

- A **partial function** $f : X \rightarrow W$ is a (total) function $f : D_f \rightarrow W$ on some set $D_f \subseteq X$, its **domain of convergence**
- $$f(x) \downarrow \iff x \in D_f, \quad f(x) \uparrow \iff x \notin D_f,$$
$$f(x) = g(x) \iff [f(x) \uparrow \ \& \ g(x) \uparrow] \vee (\exists w \in W)[f(x) = g(x) = w],$$
$$f \sqsubseteq g \iff (\forall x)[x \in D_f \implies f(x) = g(x)],$$
$$f(g(x), h(x)) = w$$
$$\iff (\exists u, v)[g(x) = u \ \& \ h(x) = v \ \& \ f(u, v) = w]$$
- **Unified notation** for n -ary partial functions and relations on a set A :

$$f : A^n \rightarrow A_s \quad (s \in \{\text{ind}, \text{bool}\}, A_{\text{ind}} = A, A_{\text{bool}} = \{\text{tt}, \text{ff}\})$$

- A **vocabulary** is a finite set $\Phi = \{\varphi_1, \dots, \varphi_m\}$ of **function symbols**, each with an assigned **sort** s and **arity** n_i
- A (partial) Φ -**structure** is a tuple $\mathbf{A} = (A, \Phi) = (A, \varphi_1^{\mathbf{A}}, \dots, \varphi_m^{\mathbf{A}})$, where for each i , $\varphi_i^{\mathbf{A}} : A^{n_i} \rightarrow A_s$
- (Structures with many **sorts** (**data types**) are **disjoint unions** of these)

Problem: define algorithms of $\mathbf{A} = (A, \Phi)$ so that:

(1) An algorithm of \mathbf{A} computes a partial function $f : A^n \rightarrow A_s$

(2) The Euclidean(s) and the mergesort are algorithms

(3) The **Facts** proved intuitively can be proved rigorously and the Main Conjecture can be made precise

- How do we **define** (or **model faithfully**) mathematical objects in set theory?
- Def. A **real number** is a sequence $x : \mathbb{N} \rightarrow \mathbb{Q}$ which has the **Cauchy property**

$$\mathbb{R} = \{x : \mathbb{N} \rightarrow \mathbb{Q} \mid x \text{ is Cauchy}\};$$

and two real numbers x, y are **equal** (or equivalent) if “they get arbitrarily close together”, i.e.,

$$x \cong y \iff \lim_{n \rightarrow \infty} |x(n) - y(n)| = 0$$

- We could take the reals to be the set of **equivalence classes** of this set \mathbb{R} under \cong

Iterative and recursive algorithms of a structure **A**

- An algorithm of **A** is **iterative** if it is specified by a `while` program which is **explicitly defined** on A from the primitives Φ of **A** (known)
- An algorithm of **A** is **recursive** if it is specified by a **recursive program** of **A** (needs rigorous definition)
- It can be argued that if we accept **(1)** - **(3)**, then the problem of defining **the algorithms of A** comes down to identifying them with **either** the iterative **or** the recursive algorithms of **A**
- The first choice—that

algorithms are (ultimately) specified by `while` programs

is **the standard view**: it is (explicitly or implicitly) accepted by almost all computer scientists, including Knuth; it covers all familiar **models of computation**—Turing machines, \dots , RAMS, \dots); and it has been developed extensively by Gurevich and his co-workers

- — but it does not cover **recursive algorithms** like the mergesort

Recursive algorithms: two more examples

- **Primitive recursion**, $f(0, y) = g(y), \quad f(x + 1, y) = h(f(x), x, y)$

► **Fact.** f is *the least fixed point* \bar{p} in $\mathbf{N}_{g,h} = (\mathbb{N}, \text{Pd}, \text{eq}_0, g, h)$ of

$$(*) \quad p(x, y) = \text{if } (x = 0) \text{ then } g(y) \text{ else } h(p(\text{Pd}(x), y), \text{Pd}(x), y)$$

- f can be computed by a while program of $(\mathbf{N}_{g,h}, S)$, but **the recursive algorithm specified by (*)** is not obviously the algorithm specified by any while program of $\mathbf{N}_{g,h}$

► **Fact** (Bezout's Lemma). *For all $x, y \geq 1$, there are $\alpha, \beta \in \mathbb{Z}$ such that*

$$(**) \quad \text{gcd}(x, y) = \alpha x + \beta y;$$

*and (**)* holds with $\alpha = \bar{p}(x, y), \beta = \bar{q}(x, y)$, **the least fixed points** of

$$\begin{aligned} p(x, y) &= \text{if } (\text{rem}(x, y) = 0) \text{ then } 0 \text{ else } q(y, \text{rem}(x, y)), \\ q(x, y) &= \text{if } (\text{rem}(x, y) = 0) \text{ then } 1 \\ &\quad \text{else } p(y, \text{rem}(x, y)) - iq(x, y)q(y, \text{rem}(x, y)) \end{aligned}$$

Recursive Φ -programs and their fixed-point semantics

- A **recursive** (McCarthy) **Φ -program** is a syntactic expression

$$E(\vec{u}) \equiv \underbrace{E_0(\vec{u})}_{\text{head}} \text{ where } \underbrace{\left\{ p_1(\vec{x}_1) = E_1(\vec{x}_1), \dots, p_K(\vec{x}_K) = E_K(\vec{x}_K) \right\}}_{\text{body, all variables in it are bound}}$$

which satisfies the following conditions:

- (1) p_1, \dots, p_K are distinct (fresh) **partial function variables**
 - (2) With $\vec{x}_0 \equiv \vec{u}$, each $E_i(\vec{x}_i)$ is an explicit term in the vocabulary $\Phi \cup \{p_1, \dots, p_K\}$ whose variables are all in the list \vec{x}_i
 - (3) The arities and sorts of the variables p_i and the terms $E_i(\vec{x}_i)$ “fit”, so that the equations in the **body** of E are well-formed
- For a Φ -structure \mathbf{A} and $i \leq K$, we set $\alpha_i(\vec{x}_i, \vec{p}) = \text{den}((\mathbf{A}, \vec{p}), E_i(\vec{x}_i))$
 - $\text{den}(\mathbf{A}, E(\vec{u})) = \alpha_0(\vec{u}, \vec{p}_1, \dots, \vec{p}_K)$ where $\vec{p}_1, \dots, \vec{p}_K$ are the **least fixed points** of the system $p_i(\vec{x}_i) = \alpha_i(\vec{x}_i, p_1, \dots, p_K), \quad i = 1, \dots, K$

Fixed-point definitions of complexity functions

- Fix a Φ -structure \mathbf{A} and a Φ -program

$$E(\vec{u}) \equiv E_0(\vec{u}) \text{ where } \left\{ p_1(\vec{x}_1) = E_1(\vec{x}_1), \dots, p_K(\vec{x}_K) = E_K(\vec{x}_K) \right\}$$

- To compute $\text{den}(\mathbf{A}, E(\vec{u}))$ for some $\vec{u} \in A^n$:

- (1) Compute (in any way) the least fixed points $\bar{p}_1, \dots, \bar{p}_K$ of the system of recursive equations in the body of $E(\vec{u})$;
- (2) Set $\text{den}(\mathbf{A}, E(\vec{u})) = \text{den}(\mathbf{A}^{\bar{p}}, E_0(\vec{u}))$ where $\mathbf{A}^{\bar{p}} = (\mathbf{A}, \bar{p}_1, \dots, \bar{p}_K)$, is the expansion of \mathbf{A} by these fixed points

- For each $\mathbf{A}, E(\vec{u}), \vec{u} \in A^n$ and $\Phi_0 \subseteq \Phi$, we can define

$$(*) \quad c_{E(\vec{u})}(\Phi_0)(\mathbf{A}, \vec{u}) = \text{the number of calls to } \varphi_i \in \Phi_0 \\ \text{in the definition of } \text{den}(\mathbf{A}, E(\vec{u}))$$

by a direct least-fixed-point recursion, so (*) is plausible; it is a theorem if $E(\vec{u})$ is (the recursive representation of) a while program; and it validates the proofs above about the mergesort

- The same can be done about many other complexity functions

Algorithmic equivalence of recursive programs

- Assume we have a reasonable definition of **the algorithm expressed** by a Φ -program on a Φ -structure and set

$$E(\vec{u}) \cong F(\vec{u}) \iff_{\text{df}} E(\vec{u}) \text{ and } F(\vec{u}) \text{ express the same algorithm in } \mathbf{A}$$

For $\varphi, \psi, c \in \Phi$ of suitable arities and sorts, TRUE or FALSE:

$$(1) \varphi(c) \cong \varphi(p) \text{ where } \{p = c\} \quad \text{TRUE}$$

$$(2) \psi(c, c) \cong \psi(p, p) \text{ where } \{p = c\} \quad \text{FALSE}$$

$$(3) \psi(c, c) \cong \psi(p, q) \text{ where } \{q = c, p = c\} \quad \text{TRUE}$$

$$(4) \psi(p_1(u), p_2(v)) \text{ where } \left\{ p_1(u) = E(u, p_2), p_2(s) = F(s, p_1, p_2) \right\} \\ \cong \psi(r_1(u), r_2(v)) \text{ where } \left\{ r_2(t) = F(t, r_1, r_2), r_1(t) = E(t, r_2) \right\} \quad \text{TRUE}$$

- Def. **Congruence** of programs: $E(\vec{u}) \equiv_c F(\vec{u})$ if F can be constructed from E by renaming the bound variables and reordering the parts in the body

Program reduction

- We define a **one-step reduction relation** $E(\vec{u}) \Rightarrow_1 F(\vec{u})$ on Φ -programs and set

$$E(\vec{u}) \Rightarrow F(\vec{u}) \iff E(\vec{u}) \equiv_c F(\vec{u})$$

or there exists a sequence $(F_1(\vec{u}), \dots, F_k(\vec{u}))$ such that

$$E(\vec{u}) \Rightarrow_1 F_1(\vec{u}) \Rightarrow_1 \dots \Rightarrow F_k(\vec{u}) \equiv F(\vec{u})$$

- $E(\vec{u})$ is **irreducible** $\iff (\forall F(\vec{u})) [E(\vec{u}) \Rightarrow F(\vec{u}) \implies E(\vec{u}) \equiv_c F(\vec{u})]$

$$\psi(c, d) \Rightarrow_1 \psi(p, d) \text{ where } \{p = c\} \Rightarrow_1 \psi(p, r) \text{ where } \{r = d, p = c\}.$$

$$\psi(c, c) \Rightarrow_1? \psi(p, p) \text{ where } \{p = c\} \quad \text{FALSE}$$

$$\psi(c, c) \Rightarrow_1 \psi(p, c) \text{ where } \{p = c\} \Rightarrow_1 \psi(p, r) \text{ where } \{r = c, p = c\}.$$

$$\psi(p) \text{ where } \{p = \varphi(c)\} \Rightarrow_1 \psi(p) \text{ where } \{p = \varphi(q), q = c\}.$$

- Reduction models (one step at a time, innermost first) **compilation**

The strict recursive algorithms of a Φ -structure \mathbf{A}

► If $E(\vec{u}) \Rightarrow F(\vec{u})$, then for every Φ -structure \mathbf{A} :

(1) $\text{den}(\mathbf{A}, E(\vec{u})) = \text{den}(\mathbf{A}, F(\vec{u}))$

(2) For every $\Phi_0 \subseteq \Pi$, $c_{E(\vec{u})}(\Phi_0)(\mathbf{A}, \vec{u}) = c_{F(\vec{u})}(\Phi_0)(\mathbf{A}, \vec{u})$
(and the same is true for many other complexity measures)

Canonical Form Theorem

Every recursive Φ -program $E(\vec{u})$ is effectively reducible to a **unique up to congruence irreducible program**, its canonical form $\text{cf}(E(\vec{u}))$

- Def. The **strict algorithm (intension)** expressed by a Φ -recursive program $E(\vec{u})$ in a Φ -structure \mathbf{A} is $E(\vec{u})$, $\text{int}_s(\mathbf{A}, E(\vec{u})) = E(\vec{u})$
- Def. $E(\vec{u}) \cong_s F(\vec{u}) \iff \text{cf}(E(\vec{u})) \equiv_c \text{cf}(F(\vec{u}))$
- *The identity relation between recursive programs is decidable (NP) and at least as difficult as the problem of isomorphism for finite graphs*

The denotational algorithms of a Φ -structure \mathbf{A}

- Suppose $\mathbf{A} = (A, \varphi, \psi)$ and $\varphi = \psi$

If $E(u) \equiv \varphi(u)$ where $\{ \}$, then $c_{E(u)}(\varphi)(u) = 1 \neq c_{E(u)}(\psi)(u) = 0$

For $E(\vec{u}) \equiv E_0(\vec{u})$ where $\left\{ p_1(\vec{x}_1) = E_1(\vec{x}_1), \dots, p_K(\vec{x}_K) = E_K(\vec{x}_K) \right\}$:

- Def. $\tau(\mathbf{A}, E(\vec{u})) = (\alpha_0, \dots, \alpha_K)$ with $\alpha_i(\vec{x}_i, \vec{p}) = \text{den}((\mathbf{A}, \vec{p}), E_i(\vec{x}_i))$
- Def. $\text{int}_d(\mathbf{A}, E(\vec{u})) = \tau(\mathbf{A}, (\text{cf}(E(\vec{u}))))$
- Def. $E(\vec{u}) \cong_{d, \mathbf{A}} F(\vec{u}) \iff \text{int}_d(\mathbf{A}, E(\vec{u})) = \text{int}_d(\mathbf{A}, F(\vec{u}))$
for some $F \equiv_c F$

Decidability of identity of denotational algorithms For every infinite \mathbf{A} , the relation $\cong_{d, \mathbf{A}}$ on recursive programs is decidable

- One of the strict or denotational algorithms of a program may be more appropriate for a particular problem—as for random variables

Comments

- Specification of algorithms by recursive rather than imperative programs simplifies greatly **proofs of correctness** which come down to showing that **the function which we want our algorithm to compute** (together with some auxiliary functions) **satisfy a system**

This separates the proof of correctness for the algorithm from the proof of correctness of (some) implementation of it—which is surely needed at some time

- The most interesting contribution of this work is the direct definition of complexity measures to recursive problems partly because the lower bound results established for a recursive program hold for all its implementations.