

Math 273b: Calculus of Variations
Homework #3

[1] Consider the 1D length functional minimization problem

$$\min_u F(u) = \int_0^1 L(u'(x))dx, \text{ or } \min_u \int_0^1 \sqrt{1 + (u'(x))^2}dx,$$

for twice differentiable functions $u : [0, 1] \rightarrow \mathbb{R}$ with boundary conditions $u(0) = 0, u(1) = 1$.

(a) Show that the functional $u \mapsto F(u)$ is convex.

(b) Formally compute the Gateaux-differential and then obtain the Euler-Lagrange equation associated with the minimization. Solve the partial differential equation and thus obtain the unique solution of the minimization.

[2] Let $A : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear self-adjoint operator, $b \in \mathbb{R}^n$, and consider the quadratic function for $x \in \mathbb{R}^n$

$$x \mapsto q(x) := \langle Ax, x \rangle - 2\langle b, x \rangle.$$

Show that the three statements

(i) $\inf\{q(x) : x \in \mathbb{R}^n\} > -\infty$

(ii) $A \geq O$ and $b \in \text{Im}A$.

(iii) the problem $\inf\{q(x) : x \in \mathbb{R}^n\} > -\infty$ has a solution

are equivalent. When they hold, characterize the set of minimum points of q , in terms of the pseudo-inverse of A .

[3] Computation of the Euler-Lagrange equation.

(a) Consider the minimization problem

$$\inf_u F(u) = \int_{x_0}^{x_1} L(x, u(x), u'(x))dx,$$

with $u(x_0) = u_0, u(x_1) = u_1$ given constants, and L a sufficiently smooth function. Obtain formally the Euler-Lagrange equation of the minimization problem that is satisfied by a smooth optimal u .

Hint: Consider smooth test functions v , such that $v(x_0) = v(x_1) = 0$. Since u is a minimizer, we must have $F(u) \leq F(u + \varepsilon v)$ for all such sufficiently smooth functions v and every real ε . Apply integration by parts to obtain the desired result. You should obtain a second-order differential equation.

(b) Let now $u(x, t)$ be a smooth solution of the time-dependent partial differential equation (PDE)

$$\frac{\partial u}{\partial t} = \frac{\partial}{\partial x} L_{u'}(x, u, u') - L_u(x, u, u'),$$

with $u(x, 0) = u_0(x)$ on (x_0, x_1) and $u(x_0, t) = U_0$, $u(x_1, t) = U_1$ for $t \geq 0$. Show that the function $E(t) = F(u(\cdot, t))$ is decreasing in time, where $F(u) = \int_{x_0}^{x_1} L(x, u, u') dx$.

Optional problems

[1] Consider the minimization problem

$$\inf_u F(u) = \int_{x_0}^{x_1} L(x, u(x), u'(x), u''(x)) dx,$$

with $u(x_0) = u_0$, $u(x_1) = u_1$, $u'(x_0) = U_0$, $u'(x_1) = U_1$ given, and L a sufficiently smooth function. As in the previous problem, derive the equation satisfied by a smooth optimal u . Choose test functions v in $C^\infty[x_0, x_1]$ that satisfy $v(x_0) = v(x_1) = v'(x_0) = v'(x_1) = 0$. (you should obtain a fourth-order differential equation).

[2] Consider the minimization problem in two dimensions (x, y) ,

$$\inf_u E(u) = \int_{\Omega} L(x, y, u, u_x, u_y) dx dy, \quad u = g \text{ on } \partial\Omega,$$

where g is a given function on the boundary $\partial\Omega$, with Ω a bounded and open region in the plane. Assume that the integrand L is differentiable.

(i) Show that a sufficiently smooth minimizer u formally satisfies the Euler-Lagrange equation

$$\frac{\partial}{\partial x} L_{u_x}(P) + \frac{\partial}{\partial y} L_{u_y}(P) - L_u(P) = 0$$

on Ω , where $P = (x, y, u(x, y), u_x(x, y), u_y(x, y))$.

(ii) Apply the above result to the case when $L(x, y, u_x, u_y) = u_x^2 + u_y^2 - 2fu$.

Hint for (i): consider another test function v , such that $v = 0$ on $\partial\Omega$. Since u is a minimizer, we must have $E(u) \leq E(u + \varepsilon v)$ for all such sufficiently smooth functions v and all real ε . Apply integration by parts to obtain the desired result. Here, $(u_x, u_y) = \nabla u$.

Notes:

• **Pseudo-Inverse.** If A is a symmetric (or self-adjoint) linear operator on X , then $\text{Im}A^\perp = \text{Ker}A$. Let $p_{\text{Im}A}$ be the operator of orthogonal projection onto $\text{Im}A$. For given $y \in X$, there is a unique $x = x(y)$ in $\text{Im}A$ such that $Ax = p_{\text{Im}A}y$. Furthermore, the mapping $y \mapsto x(y)$ is linear. This mapping is called the pseudo-inverse, or generalized inverse of A .

• **Integration by Parts Formula.** Let Ω be an open and bounded subset of R^d , with Lipschitz-continuous (or sufficiently smooth) boundary $\partial\Omega$. Let $\vec{n} = (n_1, n_2, \dots, n_d)$ be the exterior unit normal to $\partial\Omega$. Let me recall the following fundamental Green's formula, or integration by parts formula: given two functions u, v (with u, v , and all their 1st order partial derivatives belonging to $L^2(\Omega)$, or $u, v \in H^1(\Omega)$), then

$$\int_{\Omega} uv_{x_i} dx = - \int_{\Omega} u_{x_i} v dx + \int_{\partial\Omega} uv n_i dS.$$