Problems #3

[1] The median, ξ , of a set of numbers is such that half the values in the set are less than or equal to ξ , and half are greater than or equal to ξ . For example, the median of the set of values $\{2, 3, 8, 20, 21, 25, 31\}$ is 20. Show that an operator applied to the set of images (matrices) of the same dimension, that computes the median, is nonlinear.

[2] Refer to the contraharmonic filter given in the lecture notes.

- (a) Explain why the filter is effective in eliminating pepper noise when Q is positive.
- (b) Explain why the filter is effective in eliminating salt noise when Q is negative.
- (c) Explain why the filter gives poor results when the wrong polarity is chosen for Q.
- (d) Discuss the behavior of the filter when Q = -1.

(e) Discuss (for positive and negative Q) the behavior of the filter in areas of constant gray levels.

[3] We have seen in continuous variables that $\mathcal{F}(\delta) \equiv 1$, thus δ and 1 form a Fourier pair; we also have that $\mathcal{F}(1) = \delta$. Using the second property and the translation property, show in one dimension that the Fourier transform of $f(x) = \sin(2\pi u_0 x)$, where u_0 is a real number, is $F(u) = (i/2) \left[\delta(u+u_0) - \delta(u-u_0) \right]$.

(hint: you could express f function of exponentials).

[4] We have seen in continuous variables that $\mathcal{F}(\delta) \equiv 1$, thus δ and 1 form a Fourier pair; we also have that $\mathcal{F}(1) = \delta$. Using the second property and the translation property, show that the Fourier transform of the continuous function $f(x, y) = A \sin(2\pi u_0 x + 2\pi v_0 y)$ is

$$F(u,v) = A\frac{i}{2} \Big[\delta(u+u_0, v+v_0) - \delta(u-u_0, v-v_0) \Big].$$

(hint: you could express f function of exponentials).

[5] Assume that $\mathcal{F}(1) = \delta$ also holds in the discrete case (this can be shown). Using this property and the translation property, show that the Fourier transform of the discrete function $f(x, y) = \sin(2\pi u_0 x + 2\pi v_0 y)$ is

$$F(u,v) = \frac{i}{2} \Big[\delta(u + Mu_0, v + Nv_0) - \delta(u - Mu_0, v - Nv_0) \Big].$$

[6] Consider the motion blur in the frequency domain given by

$$H(u,v) = \int_0^T e^{-2\pi i [ux_0(t) + vy_0(t)]} dt.$$

For uniform motion given by $x_0(t) = \frac{at}{T}$ and $y_0(t) = \frac{bt}{T}$ (T=exposure time), show that the degradation function becomes

$$H(u,v) = \frac{T}{\pi(ua+vb)} \sin\left[\pi(ua+vb)\right]e^{-\pi i(ua+vb)}.$$