Math 155, Vese

Homework # 5 Due on Friday, May 28

[1] Show that the Fourier transform of the 2-D continuous sine function $f(x,y) = A \sin(u_0 x + v_0 y)$ is the pair of conjugate impulses

$$F(u,v) = -i\frac{A}{2} \left[\delta \left(u - \frac{u_0}{2\pi}, v - \frac{v_0}{2\pi} \right) - \delta \left(u + \frac{u_0}{2\pi}, v + \frac{v_0}{2\pi} \right) \right].$$

Hint: use the continuous version of the FT, and express the sine in terms of exponentials.

[2] Consider the motion blur

$$H(u,v) = \int_0^T e^{-2\pi i [ux_0(t) + vy_0(t)]} dt.$$

For uniform motion given by $x_0(t) = \frac{at}{T}$ and $y_0(t) = \frac{bt}{T}$ (T=exposure time), show that the degradation function becomes

$$H(u,v) = \frac{T}{\pi(ua+vb)} \sin\left[\pi(ua+vb)\right] e^{-\pi i(ua+vb)}.$$

[3] Periodic Noise Reduction Using a Notch Filter

- (a) Write a program that implements sinusoidal noise of the form given in Problem [1] above. The inputs to the program must be the amplitude, A, and the two frequency components u0 and v0 shown in the problem equation.
- (b) Download image 5.26(a) and add sinusoidal noise to it, with u0 = M/2 (the image is square) and v0 = 0. The value of A must be high enough for the noise to be quite visible in the image.
 - (c) Compute and display the spectrum of the image.
- (d) Notch-filter the image using a notch filter of the form shown in Fig. 5.19(c).

[4] Parametric Wiener Filter

- (a) Implement a motion blurring filter as in problem [2] above.
- (b) Blur image 5.26(a) in the +450 direction using T=1, as in Fig. 5.26(b) (a=b=0.1).
 - (c) Add Gaussian noise of 0 mean to the blurred image.
- (in Matlab use the following commands to add Gaussian noise of zero mean to an image:

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 \begin{split} f&=\mathrm{imread}(\mathrm{'Fig5.26a.jpg'});\\ &\mathrm{imagesc}(f);\,\,\mathrm{colormap}(\mathrm{gray});\\ f&=\mathrm{double}(f);\\ [M\ N]&=\mathrm{size}(f);\\ &\mathrm{noise=}\mathrm{randn}(256,256);\\ &g=f+10*\mathrm{noise};\\ &\mathrm{imagesc}(g);\,\,\mathrm{colormap}(\mathrm{gray});\\ ) \end{split}
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(d) Restore the image using the parametric Wiener filter given by

$$\hat{F}(u,v) = \Big[\frac{1}{H(u,v)} \frac{|H(u,v)|^2}{|H(u,v)|^2 + K}\Big] G(u,v).$$

(in the D.S. on Tuesday you may discuss how to avoid division by zero, if H(u, v) = 0).