

Homework II

1. A lie group G is a ^{group and} manifold such that the group operations of multiplication $G \times G \rightarrow G$ and inverse $G \rightarrow G$ are C^∞ . A vector field on G is called left invariant if for each $g \in G$

$$V(g \cdot h) = dL_g(V(h))$$

where $L_g: G \rightarrow G$ is defined by $h \rightarrow gh$, then

- (a) Show that for each vector $v \in T_e G$, $e = \text{identity of } G$, there is a unique left-invariant vector field V with $V(e) = v$.

- (b) Prove that the integral curves of V are defined on $(-\infty, +\infty)$ (even if G is not compact). [Suggestion: Left multiplication takes an integral curve to an integral curve.]

- (c) Show that the integral curve of V through e is a "one parameter subgroup" of G , i.e., $\gamma_e(t) \cdot \gamma_e(s) = \gamma_e(t+s)$

where $\cdot = G$ -multiplication, $\gamma_e = \text{integral curve at } e$, tangent = V .

2. Suppose $V(x, y, z) = P(x, y, z) \frac{\partial}{\partial x} + Q(x, y, z) \frac{\partial}{\partial y} + R(x, y, z) \frac{\partial}{\partial z}$

is a nowhere-zero C^∞ vector field on \mathbb{R}^3 . Find the condition for the existence

(locally) of a C^∞ function $\lambda(x, y, z)$

nowhere vanishing and such that

$$\lambda V = \text{gradient } F$$

for some C^∞ function F .

Suggestion: The gradient thing is going to happen if and only if

$(\lambda V)^\perp$ is integrable (where $\perp =$ orthogonal complement) because the level surfaces of F (if F exists) are integral submanifolds of $(\lambda V)^\perp$.

Now $(\lambda V)^\perp = V^\perp$. So we are looking for V^\perp to be integrable.

The vectors $(-Q, P, 0)$ and $(0, -R, Q)$ are a basis for V^\perp (supposing $Q \neq 0$). So compute Lie brackets, etc.

3. Considers problem 2 from the "classical" viewpoint by showing that

$$(a) \text{ curl } (\lambda V) = \lambda \text{ curl } V + \nabla \lambda \times V$$

and so that

$$\text{curl } (\lambda V) = 0 \iff -\lambda \text{ curl } V = \nabla \lambda \times V$$

and then a vector A can be written as $B \times C$ if and only if $A \perp C$. [You need to do the necessary condition here only for problem 2: proof of sufficiency is not asked for].

Homework II (continued)

4 Let $SO(3) =$ the set of 3×3 orthogonal matrices with determinant $= +1$.

(a) Show that every element in $SO(3)$ is a rotation around some axis.

(b) Deduce that every element of $SO(3)$ belongs to a one-parameter subgroup.

(c) Show that this one-parameter subgroup has the $t \rightarrow e^{Bt}$

where B is a 3×3 skew-symmetric matrix and matrix exponentiation is given by

$$e^M = I + M + \frac{1}{2} M^2 + \frac{1}{3!} M^3 + \dots$$

(d) Prove that in general (any ^{square} matrix M , $n \times n$), the series for e^M converges

[Suggestion: Use "operator norm",

$$\|A\| = \sup \{ \|A\vec{x}\| : \|\vec{x}\| \leq 1 \}$$

and note that $\|A_1 A_2\| \leq \|A_1\| \|A_2\|$.)

5. (continuation of problem 4 and extension of it)

(a) Show that $t \rightarrow e^{tM}$ is a one-parameter subgroup of the group of $n \times n$ nonsingular matrices for any $n \times n$ matrix M (group = $GL(n, \mathbb{R})$)

(b) Show that $t \rightarrow e^{tM}$ has all its elements in $SO(n)$ (orthogonal ^{$n \times n$} matrices of determinant $= 1$) if and only if M is skew symmetric.

(c) Show that every element of $GL(n, \mathbb{R})$ has the form e^M if the element is sufficiently close to the identity (i.e., \exists a neighborhood U

of the identity such that every matrix in U has this form for some M).

[Suggestion: Use the series $\log(1-x) = x + \frac{x^2}{2} + \frac{x^3}{3} + \dots$]

6. Show that a 1-parameter subgroup (which you may assume is C^∞) $t \rightarrow \varphi(t)$ of $GL(n, \mathbb{R})$ (with $\varphi(t) \cdot \varphi(s) = \varphi(t+s)$ etc.) is uniquely determined by its tangent vector at e namely $V = \left. \frac{d\varphi(t)}{dt} \right|_{t=0}$

[Suggestion: Show that φ must be an integral of the left invariant vector field determined by V].

7. Deduce that every 1-parameter subgroup of $GL(n, \mathbb{R})$ has the form $t \rightarrow e^{tM}$ and that every 1-parameter subgroup of $SO(n)$ has the form $t \rightarrow e^{tA}$, where A is skew-symmetric.

8. Work out details of proof that $\frac{d}{dt} (d\varphi_{-t}(W(\varphi_t)) - W(p)) = [V, W]$ where φ_t = flow of vector field V .

9. Write out Taylor expansion of integral curves in local coordinates to show (in general - done in class in specific case) $\left[\begin{array}{l} \text{W curve} \\ \text{V curve} \end{array} \right] \text{ differs from } \left[\begin{array}{l} \text{W curve} \\ \text{V curve} \end{array} \right] \text{ by } t^2 [V, W] + h.o.$