

Notes for 2 parts I Function linearity et al and
 Feb. 2, 2009 II \mathcal{L} , classical vector calculus, $d^2=0$,

I Crucial Observation and Technique: deRham cohomology
 Function linearity etc.

Consider the function on vector fields

$$I(X, Y) = X \omega(Y) - Y \omega(X) - \omega([X, Y])$$

where ω is a fixed C^∞ 1-form.

This is clearly "local" in the sense that $I(X, Y)$ at a point p is determined by X and Y in any neighborhood of p . But at first sight, it does not appear to be "pointwise" or "tensorial" in X and Y in the sense that $I(X, Y)$ at p is determined by $X|_p$ and $Y|_p$.

The basic observation is this: Suppose similarly for Y
 I additively linear ($I(X_1 + X_2, Y) = I(X_1, Y) + I(X_2, Y)$)
 and local as defined above. Then
 $I(X, Y)|_p$ depends only on $X|_p$ and $Y|_p$

\Leftrightarrow I is function-linear (at p) in the sense that
 $I(fX, Y)|_p = f(p) I(X, Y)|_p$
 and $I(X, gY)|_p = g(p) I(X, Y)|_p$,
 for all C^∞ f, g defined in a neighborhood of p .

Proof of observation: Write $X = \sum f_i \frac{\partial}{\partial x_i}$, $Y = \sum g_j \frac{\partial}{\partial x_j}$.
 Function linearity gives (along with additive linearity)

$$I(X, Y)|_p = \sum f_i(p) g_j(p) I\left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j}\right)|_p$$

Thus $I(X, Y)|_p$ is determined by $X|_p, Y|_p$.
 (Other direction of implication is clear).

How to check function linearity of our particular $I(x, y)$

$$\begin{aligned} I(fX, Y) &= (fX)w(Y) - Yw(fX) - w([fX, Y]) \\ &= (fX)w(Y) - Y(fw(X)) - w(f[X, Y] - Yf(X)) \\ &= f(Xw(Y) - Yw(X)) - (Yf)w(X) - f w([X, Y]) \\ &\quad + (Yf)w(X) \\ &= f I(X, Y) \end{aligned}$$

Note that the "bad terms" $\pm(Yf)w(X)$, which involve derivatives of f cancel out!

Now function linearity means that we can check the formula

$$d\omega(X, Y) = I(X, Y)$$

(where d is $d_{(x_1, \dots, x_n)}$ in local coords)

by checking $X = \frac{\partial}{\partial x_l}$ $Y = \frac{\partial}{\partial x_k}$ only. For this case, assuming wlog $l < k$:

$d_{(x_1, \dots, x_n)} (\sum F_i dx_i)$ applied to $\frac{\partial}{\partial x_l}, \frac{\partial}{\partial x_k}$

$$\frac{d}{d} \left(\sum_{i < j} \left(-\frac{\partial F_i}{\partial x_j} + \frac{\partial F_j}{\partial x_i} \right) dx_i \wedge dx_j \right) \left(\frac{\partial}{\partial x_l}, \frac{\partial}{\partial x_k} \right)$$

$$= -\frac{\partial F_l}{\partial x_k} + \frac{\partial F_k}{\partial x_l}$$

$$= \frac{\partial}{\partial x_l} F_k - \frac{\partial}{\partial x_k} F_l = \overset{\circ}{\circ} I(X, Y)$$

So formula holds in this case, hence always \square

Corollary: $d_{(x_1, \dots, x_n)}$ is independent of choice of local coordinates.

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I Relationship of d to classical vector calculus, Associate (on \mathbb{R}^3) and related matters ($d^2=0$ etc.)

$$P \frac{\partial}{\partial x} + Q \frac{\partial}{\partial y} + R \frac{\partial}{\partial z} \stackrel{\textcircled{1}}{\longleftrightarrow} P dx + Q dy + R dz$$

and

$$P \frac{\partial}{\partial x} + Q \frac{\partial}{\partial y} + R \frac{\partial}{\partial z} \stackrel{\textcircled{2}}{\longleftrightarrow} P dy \wedge dz - Q dx \wedge dz + R dx \wedge dy$$

and

$$f(x, y, z) dx \wedge dy \wedge dz \stackrel{\textcircled{3}}{\longleftrightarrow} f(x, y, z)$$

Then

$\text{grad } f =$ vector field associated via $\textcircled{1}$ to df

$\text{curl } V =$ vector field associated via $\textcircled{2}$ to $d(\text{1-form associated to } V \text{ via } \textcircled{1})$

vector field to $d(\text{1-form associated to } V \text{ via } \textcircled{1})$

and $\text{div } V =$ function associated via $\textcircled{3}$ to $d(\text{2-form associated to } V \text{ via } \textcircled{2})$.

vector field with 3-form obtained by $d(\text{2-form associated to } V \text{ via } \textcircled{2})$.

Proof: Compute.

The idea that $d^2=0$ (which we shall check in general momentarily) corresponds to two items from vector calculus: $\text{curl}(\text{grad}(\cdot))=0$ and $\text{div}(\text{curl}(\cdot))=0$.

(Exercise).

[Note that Laplacian = $\text{div}(\text{grad}(\cdot))$ does not directly fit this since no (nonzero) second order operator arises directly from d since $d^2=0$. But one can get Laplacian by doing the associations in a peculiar order: Given a function f ,

look not at the 1-form attached to $\text{grad } f$ by ① but at the 2-form attached to $\text{grad } f$ by ②. Then d of this two-form (2-form) is associated via ③ to Laplacian of f :

$$f \rightarrow \frac{\partial f}{\partial x} dy \wedge dz - \frac{\partial f}{\partial y} dx \wedge dz + \frac{\partial f}{\partial z} dx \wedge dy$$

$$\text{and } d(\quad) = \left(\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} \right) dx \wedge dy \wedge dz$$

$$= \text{Laplacian}(f) dx \wedge dy \wedge dz.$$

As we shall see later, this has a generalization to manifolds, but it involves Riemannian metric choice.]

Reason that $\begin{matrix} d \circ d \\ \swarrow \quad \searrow \\ k \text{ forms to } k+1 \text{ forms} \\ k+1 \text{ forms to } k+2 \text{ forms} \end{matrix} = 0$] Really Important Fact!!

on any manifold, all k .

Compute in local coordinates: $\omega = \sum_{i_1 < i_2 < \dots < i_k} f_{i_1 \dots i_k} dx_{i_1} \wedge \dots \wedge dx_{i_k}$

Then

$$d\omega = \sum_{i_1 < \dots < i_k} \frac{\partial f_{i_1 \dots i_k}}{\partial x_j} dx_j \wedge dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

So

$$d(d\omega) = \sum_{\substack{j, l \\ i_1 < \dots < i_k}} \frac{\partial^2 f_{i_1 \dots i_k}}{\partial x_j \partial x_l} dx_l \wedge dx_j \wedge dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

$$= 0 \text{ since } \sum_{j, l} \frac{\partial^2 f_{i_1 \dots i_k}}{\partial x_j \partial x_l} dx_l \wedge dx_j = 0 \quad (i_1, i_2, \dots, i_k \text{ fixed})$$

Since " $d^2=0$ ", $\text{im } d_{k-1 \rightarrow k} \subset \text{ker } d_{k \rightarrow k+1}$

This makes it natural to look at

$$\frac{\text{ker } d_{k \rightarrow k+1}}{\text{im } d_{k-1 \rightarrow k}} \stackrel{\text{def.}}{=} \text{deRham } k\text{-cohomology} \\ \stackrel{\text{notation}}{=} H^k(M, \mathbb{R})$$

Example: $\mathbb{R}^2 - \{(0,0)\}$, $k=1$.

Given 1-form ω with $d\omega=0$,
 $\omega = df$ for some function f if and
 only if $\oint \omega = 0$

unit circle counterclockwise

So (since \exists 1-form with $\oint \neq 0$, namely " $d\theta$ ")

$$H^1(\mathbb{R}^2 - \{(0,0)\}) \cong \mathbb{R}.$$

Exercise: Prove the "if and only if" $\oint = 0$