Crime Modeling with Lévy Flights

Jonah Breslau,¹ Sorathan (Tum) Chaturapruek,² Daniel Yazdi³ Mentors: Professor Theodore Kolokolnikov,⁴ Professor Scott McCalla³

¹Pomona College ²Harvey Mudd College ³University of California, Los Angeles ⁴Dalhousie University

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Figure: Crime Hot-Spot Pattern, Long Beach, LA. Short et al. 2010 [2]

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 - Crime hotspots are when several crimes occur in a short period of time and in a small area.
 - Considerable empirical evidence behind them.
- We focus on burglaries for simplicity.

Hotspot Modeling: Theory

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• Broken Windows Theory: crime causes sense of lawlessness.

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 - Every time step, criminals move to neighboring lattice spaces based on attractiveness.
 - Then decide to burgle or not based off attractiveness.
 - Crimes are self-exciting; cause attractiveness at lattice point and neighbors to increase.

The Short et al Model (2008) (cont.)

Then, taking limits as grid spacing and time steps go to zero, we get system of PDEs

The Model

$$A_t = \eta \Delta A - A + \rho A + A_0 \tag{1a}$$

$$\rho_t = \left(A\Delta\left(\frac{\rho}{A}\right) - \frac{\rho}{A}\Delta A\right) - \rho A + \overline{A} - A_0$$
(1b)

- A =attractiveness at a point
- $\rho = {\rm criminal}$ density at a location
- A_0 = a constant, background level of attractiveness
- \overline{A} = the spatially homogeneous equilibrium solution for A.

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- We use Lévy Flights
 - Power law distribution of step sizes (P(k) ~ k^{-(2s+1)}, 0 < s ≤ 1)
 - Fractal-like motion; reflects many scales of human movement.

Implementation: Discrete

• We change the transition probability as follows:

$$p_{i \to i+1}(t) = rac{A_{i+1}(t)}{A_{i+1}(t) + A_{i-1}(t)}$$
 (Brownian)

$$p_{i \to j}(t) = rac{A_j(t)|i-j|^{-(2s+1)}}{\sum_{k \in \mathbb{Z}, k \neq i} A_k(t)|i-k|^{-(2s+1)}}$$
 (Lévy)

Implementation: Continuous

• From before we had:

$$\begin{aligned} A_t &= \eta \Delta A - A + \rho A + A_0, \\ \rho_t &= \left(A \Delta \left(\frac{\rho}{A} \right) - \frac{\rho}{A} \Delta A \right) - \rho A + \overline{A} - A_0. \end{aligned}$$

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• Using our new transition probabilities and taking limits as before we get:

$$A_{t} = \eta \Delta A - A + \rho A + A_{0}$$
(No change)
$$\rho_{t} = \left(A\Delta^{s} \left(\frac{\rho}{A}\right) - \frac{\rho}{A}\Delta^{s}A\right) - \rho A + \overline{A} - A_{0},$$

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where

$$\Delta^{s} A = c_{s} \int_{-\infty}^{\infty} \frac{A(y) - A(x)}{|y - x|^{2s + 1}} \mathrm{d}y, \qquad (2)$$

 c_s is a constant and $0 < s \le 1$.

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 - Is a non-local operator. Leads to super-diffusion. Degree of non-locality controlled by *s*.
 - Fourier Transform has nice property: $\mathcal{F}_{x o q} \{ \Delta^s A \} = -|q|^{2s} \hat{A}$

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 ightarrow q} \{ \Delta^s A \} = |q|^{2s} \hat{A}.$
- Then use MATLAB's stiff ODE solver.
- We used to use a forward Euler spectral method, but that could not handle much of the parameter space.

Examples



Figure: Single Hot-Spot.



Figure: Four Hot-Spots, $D = 1, s = 1, \varepsilon = 0.05$.

Examples



Figure: No Hot-Spot, $D = 1, s = 0.5, \varepsilon = 0.05$.



Figure: Oscillating Hot-Spots, $s = 0.7, \eta = 0.1, \overline{\rho} = 0.4, \overline{A} = 0.12$.
Linear Stability of Homogeneous Equilibrium

• The homogeneous equilibrium does not change from Short et al. We get

$$\overline{A} = A^0 + \overline{B}$$
 and $\overline{\rho} = \frac{\overline{B}}{A^0 + \overline{B}}$. (3)

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• Perturb from the homogeneous equilibrium as follows and plug into linearized equations:

$$\begin{array}{lll} A(x,t) &=& \overline{A} + \delta_A e^{\sigma t} e^{ik \cdot x}, \\ \rho(x,t) &=& \overline{\rho} + \delta_\rho e^{\sigma t} e^{ik \cdot x}. \end{array}$$
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 (4a) (4b)

• Solving the resulting eigenvalue problem results in this condition for instability: there *exists* |k| such that

$$\eta |k|^{2s+2} - |k|^{2s} (3\overline{\rho} - 1) + \eta \overline{A} |k|^2 + \overline{A} < 0.$$
(5)

The first attempt to solve Eq. (5): the condition for instability is equivalent to, there exists |k| such that

$$\overline{\rho} > \frac{1}{3} \left(1 + \eta |k|^2 \right) \left(1 + \frac{\overline{A}}{|k|^{2s}} \right).$$
(6)

The first attempt to solve Eq. (5): the condition for instability is equivalent to,

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$$\overline{\rho} > \frac{1}{3} \left(1 + \eta |\boldsymbol{k}_{*}|^{2} \right) \left(1 + \frac{\overline{A}}{|\boldsymbol{k}_{*}|^{2s}} \right), \tag{6}$$

where $|k_*|$ is a root of

$$|k|^{2s+2} + \overline{A}(1-s)|k|^2 - \frac{\overline{A}s}{\eta} = 0.$$
(7)

The second attempt to solve Eq. (5): the condition for instability is equivalent to, there exists |k| such that

$$\overline{A} < \frac{3\overline{\rho}|k|^{2s}}{1+\eta|k|^2} - |k|^{2s}.$$
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where $|k_*|$ is a root of the equation

$$\eta^{2} s |k|^{4} + \eta (3\overline{\rho}(1-s) + 2s)|k|^{2} + s(1-3\overline{\rho}) = 0.$$
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• For $\overline{\rho} > \frac{1}{3}$, this generates condition for linear instability for the system:

$$\overline{A} < \overline{A}_*(\overline{\rho}, \eta, s) \equiv \left(\frac{-3\overline{\rho}(1-s)-2s+\sqrt{W}}{2\eta s}\right)^s \left(\frac{3\overline{\rho}(1+s)-\sqrt{W}}{-3\overline{\rho}(1-s)+\sqrt{W}}\right),$$
where $W = 3\overline{\rho}(3\overline{\rho}(1-s)^2+4s)$ (10)

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• When s = 1, the above inequality reduces to

$$\sqrt{\overline{A}\eta} + 1 < \sqrt{3\rho},\tag{11}$$

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 Has bifurcations in s, so changing degree of Lévy Flight alters stability.







(a) Fractional diffusion leads to (b) Fractional diffusion leads to stability stability



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Remark. The fixed points |k| of $\sigma(|k|)$ with respect s are given by

$$|k_1| = 1, \quad |k_2| = \sqrt{\frac{6(\overline{\rho} - \frac{1}{3}) + 3\overline{A}}{2\eta}}.$$
 (12)





We need to automate a hot-spot detection.



• The variance and its derivative.



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- The difference between the maximum and the minimum.



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- The difference between the maximum and the minimum.
- An ensemble method.



Figure: A parameter analysis with a bifurcation curve. Fix $\overline{\rho}$ and η .



Figure: A hot-spot formation when $\overline{A} = 13$, s = 0.8.



Figure: A parameter analysis with a bifurcation curve. Fix $\overline{\rho}$ and η .



Figure: No hot-spot formation when $\overline{A} = 21, s = 0.6$



Hot-spot Shape

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- Yes and no. Attractiveness hotspots do not change, and first order approximations from Kolokolnikov et al. still work very well.
- But distribution of criminals changes.

Hotspot Shape (cont.)



Figure: The inner region and the outer region of a hotspot.

Hotspot Shape (cont.)

• Let
$$x = \varepsilon y$$
, and $v = \rho/A^2$.

Hotspot Shape (cont.)

- Let $x = \varepsilon y$, and $v = \rho/A^2$.
- In the inner region $(|x| < \varepsilon)$,

$$\begin{array}{lll} \mathcal{A} & \sim & \varepsilon^{-1} v_0^{-1/2} w(y), & (12) \\ v & \sim & v_0, & (13) \end{array}$$

where v_0 and v_1 are constants, and $w = \sqrt{2} \operatorname{sech} y$ (same as Kolokolnikov et al.).
Hotspot Shape (cont.)

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where v_0 and v_1 are constants, and $w = \sqrt{2} \operatorname{sech} y$ (same as Kolokolnikov et al.).

• In the outer region ($\varepsilon \ll |x| \leq l$), we have

$$A = \alpha + o(1),$$
(14a)
 $v = h_0(x) + o(1),$ (14b)

where

$$\Delta^{s} h_{0}(x) = \zeta = \frac{\alpha - \gamma}{D_{0} \alpha^{2}} < 0, \quad 0 < |x| \le I, \quad (h_{0})_{x}(\pm I) = 0,$$
(15)

• Analyze the perturbation near hot-spots.

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- Study the dynamics of K-hot-spots with Lévy Flights.

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Lévy based model.

• Add the police.

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- Improve the numerical simulation, especially hotspot detector.

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Brownian based model. Lévy based model.

- Add the police.
- Improve the numerical simulation, especially hotspot detector.
- Analyze weakly-nonlinear stability.

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