

Automated Detection of Chondrocytes in Growth Plate Images

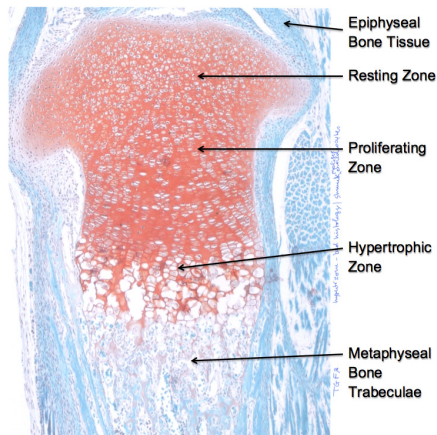
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UCLA Applied Mathematics REU 2012

Growth Plates

Bones

- ▶ Longitudinal bone growth via growth plates
- ▶ Chondrocytes arranged in vertical columns
- ▶ Cell division causes growth



Our Project

Disorders in the Growth Plate

- ▶ Misaligned chondrocytes stunt growth
- ▶ Alignment depends on genetic factors

Our Goals

- ▶ Develop automated image processing software
- ▶ Compare normal and abnormal growth plates

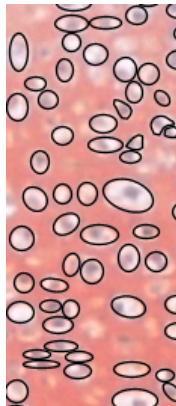
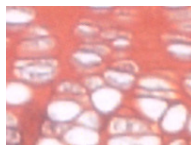
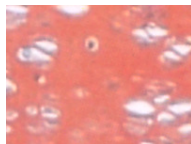
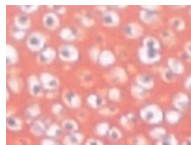


Image Processing

- ▶ Want to extract cell locations from matrices of intensity values



Challenges

- ▶ Cells beneath plane of focus
- ▶ Inconsistencies across image
 - ▶ Cell size/shape
 - ▶ Appearance of nuclei
 - ▶ Stain penetration in background

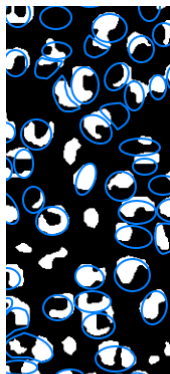
Pre-Existing Methods

Software

- ▶ ImageJ
- ▶ CellProfiler
- ▶ High-throughput and high-content screening (HT-HCS)

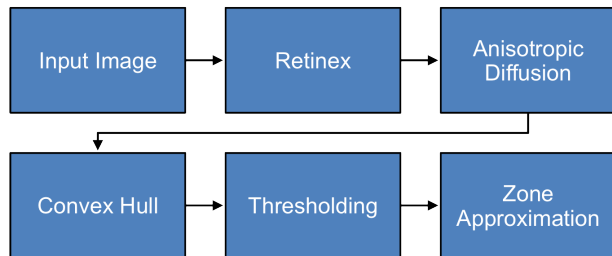
Methods

- ▶ Segmentation
- ▶ Cartoon-Texture Decomposition
- ▶ K-Means Clustering
- ▶ Spectral Clustering



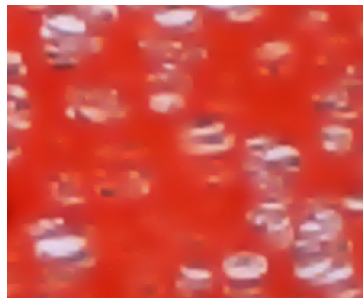
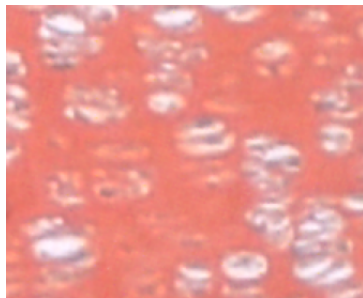
Manual detections
(blue) overlaid on
texture decomposition

Algorithm



Retinex: A Color Contrast Algorithm

- ▶ Attempt to imitate and describe human color perception
- ▶ Smooths together subtle variations in shading
- ▶ Remove cells outside plane of focus



Retinex cont.

Given an initial image, f , finds a reconstructed image, u , such that

$$-\Delta u_{i,j} = F_{i,j}$$

Where

$$\Delta u_{i,j} = u_{i+1,j} + u_{i-1,j} + u_{i,j+1} + u_{i,j-1} - 4u_{i,j}$$

is the discrete Laplacian at mesh point (i,j) ,

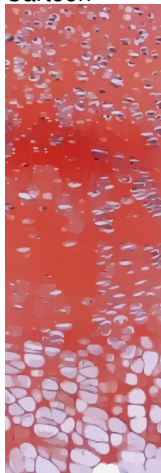
$$F_{i,j} = T(f_{i,j} - f_{i+1,j}) + T(f_{i,j} - f_{i-1,j}) + T(f_{i,j} - f_{i,j+1}) + T(f_{i,j} - f_{i,j-1})$$

and T is a thresholding function such that

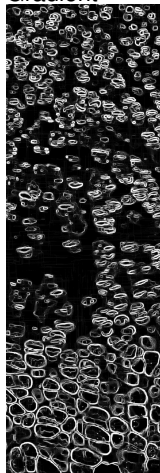
$$T(x) = \begin{cases} 0 & \text{if } |x| \leq \tau \\ x & \text{if } |x| > \tau \end{cases}$$

Anisotropic Diffusion

Cartoon



Gradient



$$\min_u \int \Psi(\nabla u, \nabla u^T) dx$$

$$g(|\nabla u|) = \frac{1}{|\nabla u|^p}$$

- ▶ Related to Perona-Malik Diffusion
- ▶ Both nonlocal and nonlinear
- ▶ Emphasis on preserving edges

Morphological Functions

Convex Hull

- ▶ Fits polygon to cell outline
- ▶ Connects discontinuities linearly
- ▶ Need separation between cells

Morphological Functions

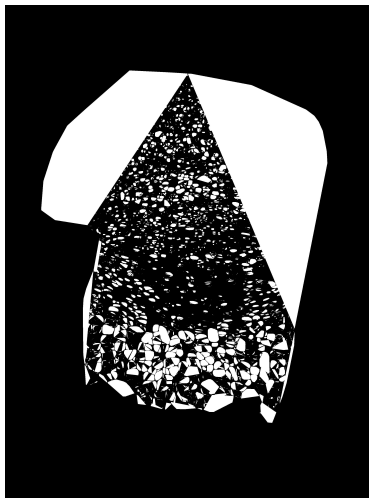
Size Thresholding

Shape Thresholding

- ▶ Isoperimetric Inequality

$$\frac{4\pi A}{L^2}$$

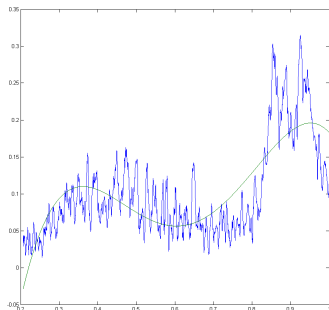
- ▶ Relationship between shape area and circumference
- ▶ Ratio equals one for circle



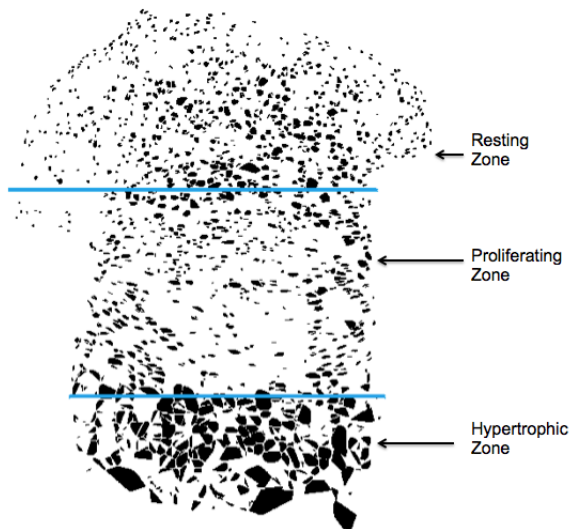


Automated Growth Plate Zone Detection

- ▶ Classify each object by its Isoperimetric Ratio ($\frac{4\pi A}{L^2}$)
- ▶ Plot object location vs. Ratio and approximate graph with a fourth degree polynomial
- ▶ Inflection points at zone boundaries



Results

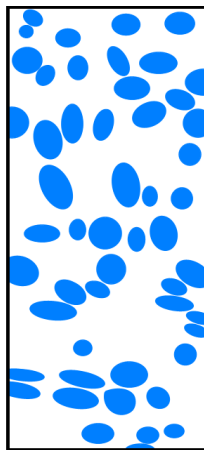


Results

Algorithm
Detections



Manual
Detections

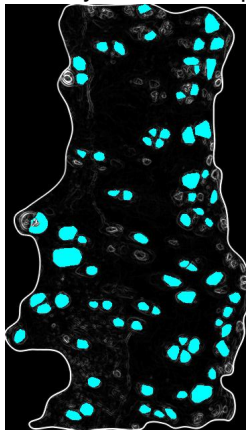


Results

Original Growth Plate



Overlay of Final Output



Clustering Error Statistics

Error Analysis

- ▶ How well does our algorithm segment the cells in our images?
- ▶ Many metrics/statistics for clustering analysis

Metric Requirements

- ▶ Can compare an unequal number of clusters
- ▶ Can handle large variations in cluster sizes
- ▶ Must not be computationally complex

Error Statistics

- ▶ Classes $\{L_j\}$ in our 'ground truth' image $S = \{I_1, \dots, I_N\}$
- ▶ Clusters $\{C_i\}$ in our segmented image $S' = \{I'_1, \dots, I'_N\}$

Clustering Purity

- ▶ Purity = $\sum_i \frac{|C_i|}{N} \max_j \frac{|C_i \cap L_j|}{|L_j|}$
- ▶ Not robust to clusters which subdivide classes, trivial clusters, or clusters that span multiple classes
- ▶ Up to 88%

Rand Indices

- ▶ Classes $\{L_j\}$ in our 'ground truth' image $S = \{l_1, \dots, l_N\}$
- ▶ Clusters $\{C_i\}$ in our segmented image $S' = \{l'_1, \dots, l'_N\}$

Rand Index

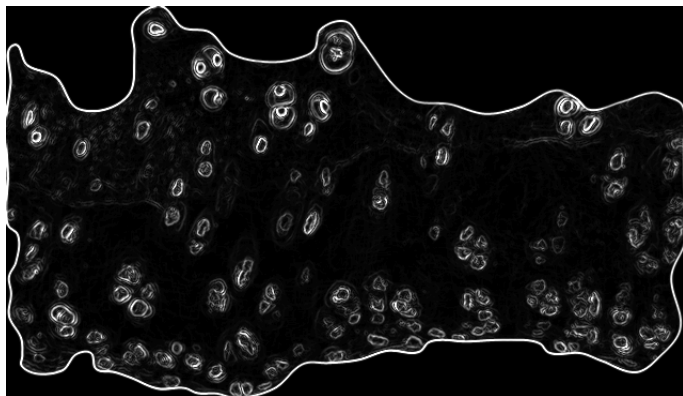
- ▶ $R(S, S') = \frac{1}{\binom{N}{2}} (|A| + |B|)$
where $A = \{(i, j) | i \neq j, l_i = l_j, l'_i = l'_j\}$ and
 $B = \{(i, j) | i \neq j, l_i \neq l_j, l'_i \neq l'_j\}$
- ▶ Compare clustering of *pairs* of pixels
- ▶ Penalizes false positives and true negatives *equally*
- ▶ Up to 74%

Conclusion

In summary, we developed a successful algorithm for:

- ▶ extraction of chondrocyte location
- ▶ zone approximations

Questions?



References

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