

## An overview of topological spaces

### 1. Facts to recall from metric spaces

First, recall that in a metric space, the family of open sets is closed under finite intersections and arbitrary unions.

Second, recall that in a metric space, a number of concepts can be characterized in terms of open sets (where as usual, we often refer to subsets as simply “sets”):

- A set is closed  $\Leftrightarrow$  its complement is open.
- A function is continuous  $\Leftrightarrow$  the inverse image of every open set is open.
- A space is connected  $\Leftrightarrow$  it cannot be partitioned into two open sets.
- A space is compact  $\Leftrightarrow$  every open cover (family of open sets whose union is the space) has a finite subcover (finite subfamily whose union is the space).
- A point is isolated  $\Leftrightarrow$  it is open as a singleton.
- A sequence converges to  $x \Leftrightarrow$  for each open set  $O$  containing  $x$ , the sequence is eventually in  $O$ .

### 2. Topological spaces

These facts suggest that open sets could be used as a starting concept. The resulting theory is more general than the theory of metric spaces and is helpful for various spaces of functions that are not metric.

**Definition.** A *topology* on a set  $X$  is a family  $\mathcal{T}$  of subsets of  $X$  such that  $\mathcal{T}$  is closed under finite intersections and arbitrary unions. The members of  $\mathcal{T}$  are called *open sets* (or simply *open sets*) and  $X$  with  $\mathcal{T}$  is a *topological space*.

We would also list that the the empty set and  $X$  itself are open, but these facts already follow from the definition since the union of no sets is empty and the intersection of no subsets is  $X$ .

All the concepts from Section 1 can be turned into definitions. Many theorems that you know from metric spaces remain valid. However, the definition of a topological space is mismatched with metric spaces in two ways:

- The definition of a topological space is weak, in that it does not ensure that open sets can distinguish between points. In fact, given any set  $X$  we can define a rudimentary topology in which the only open sets are the empty set and  $X$ ; in this topology, it is no longer true that a convergent sequence has a unique limit, for example. Therefore we often go beyond the definition of a topological space and impose separation conditions, as in §3 below.
- Sequences (indexed by nonnegative integers), which are sufficient to determine the topology in a metric space, are inadequate to do so for topological spaces in general. In other words, it is not true in general that a subset  $S$  is closed when any convergent sequence in  $S$  converges to a point of  $S$ . Instead, one can use “nets”—generalized sequences indexed by a directed set instead. However, theorems in topology can usually be proved without using nets.

### 3. Separation conditions

Here are some separation conditions of increasing strength. Which (if any) is needed depends on the application.

$T_0$  space: The open sets distinguish points. In other words, given two points in  $X$ , there is an open set that contains one point but not the other.

$T_1$  space: The open sets distinguish points both ways around: Given two points, for each point there is an open set that contains it but not the other point. An equivalent condition is that every singleton is a closed set.

$T_2$  space, or Hausdorff space: Any two points can be separated by disjoint open sets. In other words, given two points  $x, y$ , there are disjoint open sets  $O_x, O_y$  with  $x \in O_x$  and  $y \in O_y$ .

There are stronger possibilities as well.

### 4. Remarks

- Any metric space is a Hausdorff space.
- A frequent object of study is compact Hausdorff spaces, which include the compact metric spaces such as the real unit interval.
- Just as for metric spaces, for a subset  $S$  of a topological space  $X$ , we can relativize to  $S$ : The *relative topology* on  $S$  consists of the intersections of  $S$  with the open sets of  $X$ .

- Two topological spaces are said to be *homeomorphic* if they are in one-to-one correspondence by a correspondence that preserves open sets. Equivalently, there is a pair of inverse continuous functions between them.

## 5. Problems

**Problem M-1.** Show that the two descriptions of a  $T_1$  space are equivalent.

**Problem M-2.** Consider the metric space  $X = \{\frac{1}{2}, \frac{2}{3}, \frac{3}{4}, \dots\} \cup \{1\} \subseteq \mathbb{R}$ . Describe the open sets of  $X$ . Which sets are clopen (simultaneously closed and open)?

**Problem M-3.** Given a topological space  $X$  with topology  $\mathcal{T}$ , a family  $\mathcal{U}$  of sets of  $X$  is a *base* for the topology if every member of  $\mathcal{T}$  is a union of members of  $\mathcal{U}$  (possibly infinitely many). If  $X$  is the real unit interval with the usual topology, are the open intervals with rational endpoints a base for the topology of  $X$ ?

**Problem M-4.** A *Boolean* topological space is a compact Hausdorff space in which the clopen sets form a base for the topology. (For definitions, see problems 2 and 3.) Show that the only connected subsets of a Boolean topological space are singletons. (A subset is said to be connected if it is connected in the relative topology.)

**Problem M-5.** Show that if a compact Hausdorff space  $X$  has the property that every connected subset is a singleton, then  $X$  is Boolean.

**Problem M-6.** Let  $\omega_1$  be the “first uncountable ordinal”, an uncountable well ordered set for which all principal ideals are countable. Let  $\omega_1^+$  be  $\omega_1$  with a top element added. Give  $\omega_1^+$  the topology for which the open intervals ( $\{x : a < x < b\}$  or  $\{x : a < x\}$  or  $\{x : x < b\}$ ) form a basis.

(a) Is  $\omega_1^+$  compact Hausdorff with this topology?

(b) Are sequences adequate to determine whether a subset is closed?