

# Lecture XII: Line Integrals, Path Independence and Related Topics, and Classical Vector Calculus

Converse of equality of mixed partials: If  $U^{\text{open}} \subset \mathbb{R}^2$

is an open rectangle (or open disc) and if  $P$  and  $Q$  are continuous functions on  $U$  such that  $\partial P / \partial y$  and  $\partial Q / \partial x$  exist and are continuous on  $U$  and if  $\partial P / \partial y \equiv \partial Q / \partial x$  on  $U$ , then  $\exists f: U \rightarrow \mathbb{R}$  with  $\frac{\partial f}{\partial x} = P$  and  $\frac{\partial f}{\partial y} = Q$  at each point of  $U$ .

Proof. Wlog  $(0,0) \in U$  (and  $(0,0)$  = center of disc if  $U$  = disc). Define  $f$  for  $(x,y) \in U$

$$f(x,y) = \int_0^x P(t,0) dt + \int_0^y Q(x,s) ds$$

By the Fundamental Theorem of Calculus,  $\frac{\partial f}{\partial y}$  exists at each  $(x,y)$  and  $\frac{\partial f}{\partial y} = Q(x,y)$  there.

Also  $\left[ \frac{d}{dx} \left( \int_0^x P(t,0) dt \right) \right] \Big|_{(x,y)} = P(x,0)$

while, by differentiation under the integral sign and using  $\frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y}$ :

$$\frac{d}{dx} \left( \int_0^y Q(x,s) ds \right) = \int_0^y \frac{\partial}{\partial x} Q(x,s) ds \Big|_x$$

$$= \int_0^y \frac{\partial P}{\partial y} \Big|_{(x,s)} ds = P(x,y) - P(x,0)$$

(Fund. Th. of Calculus again)

$$\text{So } \frac{d}{dx} f(x,y) \Big|_{(x,y)} = P(x,0) + (P(x,y) - P(x,0)) = P(x,y)$$

! Exercise: Generalize to  $P_1, \dots, P_n$  on open rectangle (or ball) in  $\mathbb{R}^n$ ,  $\partial P_j / \partial x_i = \partial P_i / \partial x_j$  all  $i, j$ . Use induction.

Now-example:  $U = \mathbb{R}^2 - \{0\}$  (2)

$$P = -y / (x^2 + y^2) \quad Q = x / (x^2 + y^2)$$

$$\partial P / \partial y = [(x^2 + y^2)(-1) + y(2y)] / (x^2 + y^2)^2$$

$$= -x^2 + y^2 / (x^2 + y^2)^2$$

$$\partial Q / \partial x = [(x^2 + y^2) - x(2x)] / (x^2 + y^2)^2$$

$$= (-x^2 + y^2) / (x^2 + y^2)^2$$

Note: This had to work since  $P = \frac{\partial \theta}{\partial x}$   $Q = \frac{\partial \theta}{\partial y}$  where  $\theta$  is a "local" branch of polar coordinate angle, i.e.  $(r, \theta) \rightarrow (x, y)$  locally inverted ( $r \neq 0$ ),  $\theta = \theta(x, y)$ .

But if  $\exists f: \mathbb{R}^2 - \{0\} \rightarrow \mathbb{R}$  with  $\frac{\partial f}{\partial x} = P$ ,

$\frac{\partial f}{\partial y} = Q$  then

$$f(1, 1) - f(1, -1) = \int_{-1}^{+1} \frac{1}{1+s^2} ds$$

$$= \arctan s \Big|_{-1}^{+1} = (\pi/4) - (-\pi/4) = \pi/2$$

and similarly

$$f(-1, 1) - f(1, 1) = \pi/2$$

$$f(-1, -1) - f(1, -1) = \pi/2$$

$$f(1, -1) - f(-1, -1) = \pi/2$$

Adding all four  $f-f$  equalities gives  
 $0 = 2\pi$ , a contradiction!

So no such  $f$  exists! (smooth or even continuous)

This is a precise version of no "global" polar coordinate angle existing on  $\mathbb{R}^2 - \{0\}$

Exercise: Prove: If  $V^{open} \subset \mathbb{R}^2 - \{0\}$  and if  $f: V \rightarrow \mathbb{R}$  is continuous and satisfies  $(x, y) = (\sqrt{x^2+y^2} \cos f(x, y), \sqrt{x^2+y^2} \sin f(x, y))$  for all  $(x, y) \in V$ , then  $f$  is actually  $C^1$  (indeed,  $C^\infty$ ). So our proof that no  $C^1$  polar coordinate choice exists on all of  $\mathbb{R}^2 - \{0\}$  actually proves no continuous choice exists

Line Integrals

Def: A curve  $\gamma: [a, b] \rightarrow \mathbb{R}^2$  (or  $\mathbb{R}^n$ ) is  $C^1$  on  $[a, b]$  if  $\exists \varepsilon > 0$  and  $\hat{\gamma}: (a-\varepsilon, b+\varepsilon) \rightarrow \mathbb{R}^2$  (or  $\mathbb{R}^n$ ) which is  $C^1$  differentiable and satisfies  $\hat{\gamma}|_{[a, b]} = \gamma$ .

Definition: If  $U^{open} \subset \mathbb{R}^n$  and  $P_1, \dots, P_n$  are continuous function (into  $\mathbb{R}$ ) on  $U$  and if  $\gamma: [a, b] \rightarrow U$  is  $C^1$  then

$$\int_{\gamma} P_1 dx_1 + \dots + P_n dx_n = \int_a^b \sum_{j=1}^n P_j(\gamma(t)) \cdot \frac{dx_j(t)}{dt} dt$$

where the  $x_j$  are determined by  $\gamma(t) = (x_1(t), \dots, x_n(t))$

Example  $\mathbb{R}^2$   $\int_{\gamma} P dx + Q dy = \int_a^b P(\gamma(t)) \frac{dx}{dt} + Q(\gamma(t)) \frac{dy}{dt}$   
 [Here  $P_j(\gamma(t)) = P_j|_{\gamma(t)}$ , the function  $P$  evaluated at  $\gamma(t)$  etc.]

Basic fact If  $f$  is  $C^1$  on  $U$  and  $\gamma$   $[a, b] \rightarrow U$  is  $C^1$  then ④

$$\int_{\gamma} \frac{\partial f}{\partial x_1} dx_1 + \dots + \frac{\partial f}{\partial x_n} dx_n = f(\gamma(b)) - f(\gamma(a)).$$

Proof:  $\frac{d}{dt} f(\gamma(t)) = \frac{\partial f}{\partial x_1} \Big|_{\gamma(t)} \frac{dx_1}{dt} + \dots + \frac{\partial f}{\partial x_n} \Big|_{\gamma(t)} \frac{dx_n}{dt}$

by the Chain Rule. Now apply the Fund. Th. of Calculus.  $\square$

Notation:  $\text{grad } f$  (read: "gradient of  $f$ ") is, at  $\vec{x} \in U$ , the vector  $(\frac{\partial f}{\partial x_1} \Big|_{\vec{x}}, \frac{\partial f}{\partial x_2} \Big|_{\vec{x}}, \dots, \frac{\partial f}{\partial x_n} \Big|_{\vec{x}})$ .

If  $f$  is  $C^1$  on  $U$ , then  $\text{grad } f$  is a continuous function from  $U$  to  $\mathbb{R}^n$ . We think of this as a "vector field", i.e., an assignment of a vector to each point of  $U$ . [A vector field is no different formally in this context than an  $\mathbb{R}^n$ -valued function, but the psychology is distinctive!]

Exercise  $\frac{d}{dt} f(\vec{x}_0 + t\vec{v}) = \langle \text{grad } f \Big|_{\vec{x}_0}, \vec{v} \rangle$ .

Note: The Basic Fact applies also to  $\gamma$  which are "piecewise  $C^1$ ", i.e. to  $\gamma$  such that  $\gamma$  is continuous and  $\exists$  a partition  $a = a_0 < a_1 < \dots < a_n = b \ni$  each  $\gamma|_{[a_i, a_{i+1}]}$   $i=0, \dots, n-1$  is  $C^1$ . (Proof: Exercise)

"Path Independence": If  $P_1, \dots, P_n$  (continuous functions on  $U$ ) are  $\exists$


$$\oint_{\gamma} P_1 dx_1 + \dots + P_n dx_n$$

depends only on the endpoints  $\gamma(a), \gamma(b)$  of  $\gamma$  for all piecewise  $C^1$   $\gamma: [a, b] \rightarrow U$ , then

$\exists f$  such that  $f: U \rightarrow \mathbb{R}$  is  $C^1$  and  $\frac{\partial f}{\partial x_i} = P_i, i=1, \dots, n$ , everywhere on  $U$ .

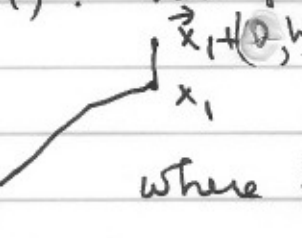
(Converse is obvious)

Proof Define (assuming wlog  $U$  is connected) with

$x_0$  fixed 

$$f(x_1) = \int_{\gamma} P_1 dx_1 + \dots + P_n dx_n$$

where  $\gamma$  is a piecewise  $C^1$  curve from  $x_0$  to  $x_1$ . (exists since piecewise  $C^1$  accessible <sup>(from  $x_0$ )</sup> pts are an open & closed set in  $U$ ). Then  $f$  satisfies the derivative condition

using pictures like (to show  $\frac{\partial f}{\partial x_i} = P_i(\vec{x}_1)$ ) 

by that shown, where last segment of  $\gamma$  is along a coordinate direction: details are an exercise

$\square$

Path independence  $\iff \oint_{\gamma} = 0$  for all piecewise  $C^1$   $\gamma$  that are closed ( $\gamma(b) = \gamma(a)$ ). ⑤  
 Proof: easy exercise.

Definition: A "differential"  $P dx + Q dy$  is closed if  $\partial P / \partial y = \partial Q / \partial x$  ( $P, Q \in C^1$ ).

The differential  $P dx + Q dy$  is exact if  $\exists f \ni df = P dx + Q dy$  where  $df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$  by definition.

["Differentials" can be thought of as formal, or is, at each point, having value in  $(\mathbb{R}^2)^*$  via  $dx((\alpha, \beta)) = \alpha$ ,  $dy((\alpha, \beta)) = \beta$ ]

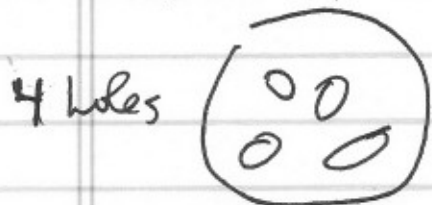
(Similar ideas for  $\mathbb{R}^n$ ).

Exact  $\Rightarrow$  Closed (equality of mixed partials: we assume everything  $C^\infty$  from here  $\circ$ )

Closed differentials and exact differentials are vector spaces (over  $\mathbb{R}$ )

The quotient space closed/exact is called the (first) deRham cohomology of  $U$ . For a disc with  $k$  "holes" removed, it has dimension  $k$ . It is

a "topological invariant": if  $U$  is homeomorphic to  $V$ , then deRham cohomologies are isomorphic (= same dimension)



Topological invariance is hard in general. ⑦  
 Diffeomorphism invariance is easier (see exercises).  
See exercises for some calculations, also.

Classical vector calculus operators on vector fields  
 (on open sets in  $\mathbb{R}^3$ )

$V$  a vector field on  $U \subset \mathbb{R}^3$ , i.e.  $V: U \rightarrow \mathbb{R}^3$ .  
 We assume as much differentiability of  $V$  as convenient  
 in the context!

Write  $V = (v_1, v_2, v_3)$   $v_j$ 's  $\mathbb{R}$ -valued

$$\text{curl } V \stackrel{\text{def.}}{=} \left( \frac{\partial v_3}{\partial x_2} - \frac{\partial v_2}{\partial x_3}, \frac{\partial v_1}{\partial v_3} - \frac{\partial v_3}{\partial x_1}, \frac{\partial v_2}{\partial x_1} - \frac{\partial v_1}{\partial x_2} \right)$$

$$\text{div } V = \frac{\partial v_1}{\partial x_1} + \frac{\partial v_2}{\partial x_2} + \frac{\partial v_3}{\partial x_3} \quad (\text{this is a number! valued item!})$$

Facts: (a)  $\text{div}(\text{curl } V) = 0$  everywhere

Check

$$\frac{\partial}{\partial x_1} \left( \frac{\partial v_3}{\partial x_2} - \frac{\partial v_2}{\partial x_3} \right) = \frac{\partial^2 v_3}{\partial x_1 \partial x_2} - \frac{\partial^2 v_2}{\partial x_1 \partial x_3}$$

$$\frac{\partial}{\partial x_2} \left( \frac{\partial v_1}{\partial x_3} - \frac{\partial v_3}{\partial x_1} \right) = \frac{\partial^2 v_1}{\partial x_2 \partial x_3} - \frac{\partial^2 v_3}{\partial x_2 \partial x_1}$$

$$\frac{\partial}{\partial x_3} \left( \frac{\partial v_2}{\partial x_1} - \frac{\partial v_1}{\partial x_2} \right) = \frac{\partial^2 v_2}{\partial x_3 \partial x_1} - \frac{\partial^2 v_1}{\partial x_3 \partial x_2}$$

Terms cancel as indicated (by = of mixed partials).

Of course, we rigged up curl to make this work!

(b) curl (grad f) = 0

Proof: Use = of mixed partials

Facts (a) and (b) have "local" converses (e.g. on open "rectangles")

(a) div V ≡ 0 ⇒ ∃ W ⊃ curl W = V

(b) curl V ≡ 0 ⇒ ∃ f ⊃ grad f = V

Item (b) is equivalent to something we have already shown (top of p. 2, analogue in R^3 of page 1).

For item (a), see Exercise

Important operator on functions: div (grad f) = ∂²f/∂x₁² + ∂²f/∂x₂² + ∂²f/∂x₃² (or ∂²f/∂x² + ∂²f/∂y² on R²)

∂²/∂x₁² + ∂²/∂x₂² + ∂²/∂x₃² (or ∂²/∂x² + ∂²/∂y² or obvious generalization to Rⁿ)

is the Laplacian (definition)

Δf ≡ 0 ⇔ f is harmonic.

Important examples:

(1) log √(x²+y²) on R² - {0}

(2) 1/√(x²+y²+z²) on R³ - {0}, 1/r^{n-2} on Rⁿ - {0}

(3) Re(x+iy)^n and Im(x+iy)^n on R² = C

E.g. x² - y² = Re(x+iy)², x³ - 3xy² = Re(x+iy)³ (by inspection)

General reason: Re(x+iy)^n = x^n - n(n-1)/2 x^{n-2} y² + ... 2nd x deriv of each term is cancelled by 2nd y deriv of next one (Ex).