

Construction of a Massless Quantum Field Theory over the p -adics

Abdelmalek Abdesselam, Ajay Chandra, Gianluca Guadagni

University of Virginia

September 6, 2011

Generalized Random Fields ϕ over \mathbb{K}^d

- Given by some measure μ on $\mathcal{S}'(\mathbb{K}^d)$ where \mathcal{S}' is the dual of the Schwartz-Bruhat space \mathcal{S} of test functions on \mathbb{K}^d

Generalized Random Fields ϕ over \mathbb{K}^d

- Given by some measure μ on $\mathcal{S}'(\mathbb{K}^d)$ where \mathcal{S}' is the dual of the Schwartz-Bruhat space \mathcal{S} of test functions on \mathbb{K}^d
- Can construct such measures via Bochner-Minlos Theorem. In particular can construct Gaussians from symmetric positive definite bilinear forms $C(\cdot, \cdot)$ on \mathcal{S}

Generalized Random Fields ϕ over \mathbb{K}^d

- Given by some measure μ on $\mathcal{S}'(\mathbb{K}^d)$ where \mathcal{S}' is the dual of the Schwartz-Bruhat space \mathcal{S} of test functions on \mathbb{K}^d
- Can construct such measures via Bochner-Minlos Theorem. In particular can construct Gaussians from symmetric positive definite bilinear forms $C(\cdot, \cdot)$ on \mathcal{S}
- Cannot talk about " $\phi(x)$ ", no coordinate process. For any $f \in \mathcal{S}$ we have a random variable:

$$\phi(f) = (\phi, f) = \int_{\mathbb{K}^d} d^d x \phi(x) f(x)$$

This \mathcal{S} -indexed family of random variables completely determines ϕ .

Generalized Random Fields ϕ over \mathbb{K}^d

- Given by some measure μ on $\mathcal{S}'(\mathbb{K}^d)$ where \mathcal{S}' is the dual of the Schwartz-Bruhat space \mathcal{S} of test functions on \mathbb{K}^d
- Can construct such measures via Bochner-Minlos Theorem. In particular can construct Gaussians from symmetric positive definite bilinear forms $C(\cdot, \cdot)$ on \mathcal{S}
- Cannot talk about " $\phi(x)$ ", no coordinate process. For any $f \in \mathcal{S}$ we have a random variable:

$$\phi(f) = (\phi, f) = \int_{\mathbb{K}^d} d^d x \phi(x) f(x)$$

This \mathcal{S} -indexed family of random variables completely determines ϕ .

- (Gaussian) Examples: White Noise, Continuum GFF with $d > 2$

A Particular Class of Generalized Random Fields

- (a) Tempered: For all $f \in \mathcal{S}$, $\mathbb{E} \left[e^{z\phi(f)} \right]$ is analytic in z in some ball around 0.

A Particular Class of Generalized Random Fields

- (a) Tempered: For all $f \in \mathcal{S}$, $\mathbb{E} \left[e^{z\phi(f)} \right]$ is analytic in z in some ball around 0.
- (b) Stationary: " $\phi(x + a) \stackrel{d}{=} \phi(x)$ "

A Particular Class of Generalized Random Fields

- (a) Tempered: For all $f \in \mathcal{S}$, $\mathbb{E} \left[e^{z\phi(f)} \right]$ is analytic in z in some ball around 0.
- (b) Stationary: " $\phi(x+a) \stackrel{d}{=} \phi(x)$ "
- (c) Rotation invariant: " $\phi(Ex) \stackrel{d}{=} \phi(x)$ " for all $E \in GL_d(\mathbb{K})$ that preserve the \mathbb{K}^d norm.

A Particular Class of Generalized Random Fields

- (a) Tempered: For all $f \in \mathcal{S}$, $\mathbb{E} \left[e^{z\phi(f)} \right]$ is analytic in z in some ball around 0.
- (b) Stationary: " $\phi(x+a) \stackrel{d}{=} \phi(x)$ "
- (c) Rotation invariant: " $\phi(Ex) \stackrel{d}{=} \phi(x)$ " for all $E \in GL_d(\mathbb{K})$ that preserve the \mathbb{K}^d norm.
- (d) κ scale invariant: " $|\lambda|^{-\kappa} \phi\left(\frac{x}{\lambda}\right) \stackrel{d}{=} \phi(x)$ " for all $\lambda \in \mathbb{K}^*$.

A Particular Class of Generalized Random Fields

- (a) Tempered: For all $f \in \mathcal{S}$, $\mathbb{E} \left[e^{z\phi(f)} \right]$ is analytic in z in some ball around 0.
- (b) Stationary: " $\phi(x+a) \stackrel{d}{=} \phi(x)$ "
- (c) Rotation invariant: " $\phi(Ex) \stackrel{d}{=} \phi(x)$ " for all $E \in GL_d(\mathbb{K})$ that preserve the \mathbb{K}^d norm.
- (d) κ scale invariant: " $|\lambda|^{-\kappa} \phi\left(\frac{x}{\lambda}\right) \stackrel{d}{=} \phi(x)$ " for all $\lambda \in \mathbb{K}^*$.
- (e) Non-trivial (Non-Gaussian): $\left. \left(\frac{d}{dz} \right)^4 \right|_{z=0} \log \left(\mathbb{E} \left[e^{z\phi(f)} \right] \right) \neq 0$ for some $f \in \mathcal{S}$.

Theorem (Abdesselam, C., Guadagni): Let p be prime and set $\mathbb{K} = \mathbb{Q}_p$, $d = 3$. There exists an $L_0 > 1$ such that for any $L = p^j > L_0$ there exists a measure ν (on $\mathcal{S}'(\mathbb{Q}_p^3)$) satisfying (a)-(c) and (e) along with a restricted version of (d) (ν satisfies scale invariance with some κ for any λ of the form L^k , $k \in \mathbb{Z}$).

Theorem (Abdesselam, C., Guadagni): Let p be prime and set $\mathbb{K} = \mathbb{Q}_p$, $d = 3$. There exists an $L_0 > 1$ such that for any $L = p^j > L_0$ there exists a measure ν (on $\mathcal{S}'(\mathbb{Q}_p^3)$) satisfying (a)-(c) and (e) along with a restricted version of (d) (ν satisfies scale invariance with some κ for any λ of the form L^k , $k \in \mathbb{Z}$).

Earlier Work:

(Bleher, Sinai 1973), (Collet, Eckmann 1977): Hierarchical model, non-trivial fixed point

(Gawedzki, Kupianien 1983 and 1984): Hierarchical model, non-trivial fixed point and nonzero connected four point function

(Brydges, Mitter, Scoppola 2003): Euclidean model, non-trivial fixed point

(Abdesselam 2006): Euclidean model, construction of a trajectory between Gaussian and non-trivial fixed points

Constructing a singular perturbation of the Gaussian μ_C with the covariance $C : \mathbb{K}^3 \times \mathbb{K}^3 \rightarrow \mathbb{R}$:

$$\begin{aligned} C(x, y) = C(x - y) &= \frac{A}{|x - y|^{\frac{3-\epsilon}{2}}} \\ &= \frac{A}{|x - y|^{2[\phi]}} \quad [\phi] = \frac{(3 - \epsilon)}{4} = \kappa \end{aligned}$$

Written in Fourier we have:

$$\hat{C}(k) = \frac{1}{|k|^{\frac{(3+\epsilon)}{2}}}$$

Constructing a singular perturbation of the Gaussian μ_C with the covariance $C : \mathbb{K}^3 \times \mathbb{K}^3 \rightarrow \mathbb{R}$:

$$\begin{aligned} C(x, y) = C(x - y) &= \frac{A}{|x - y|^{\frac{3-\epsilon}{2}}} \\ &= \frac{A}{|x - y|^{2[\phi]}} \quad [\phi] = \frac{(3 - \epsilon)}{4} = \kappa \end{aligned}$$

Written in Fourier we have:

$$\hat{C}(k) = \frac{1}{|k|^{\frac{(3+\epsilon)}{2}}}$$

Formally the perturbation is given by:

$$\exp \left[-g \int_{\mathbb{K}^3} d^3x \phi^4(x) \right]$$

$$\exp \left[-g \int_{\mathbb{K}^3} d^3x \phi^4(x) \right] \left\{ \begin{array}{l} \text{How to interpret } \phi^4(x)?: \text{ **UV Divergence**} \\ \text{Interaction in infinite volume: **IR Divergence**} \end{array} \right.$$

$$\exp \left[-g \int_{\mathbb{K}^3} d^3x \phi^4(x) \right] \left\{ \begin{array}{l} \text{How to interpret } \phi^4(x)?: \text{ **UV Divergence**} \\ \text{Interaction in infinite volume: **IR Divergence**} \end{array} \right.$$

$$\text{Regularize!} : \left\{ \begin{array}{l} \text{Replace } C \text{ with } C_r \text{ where } \hat{C}_r(k) = \mathbb{1}_{\{|k| \leq L^{-r}\}} \hat{C}(k) \\ \text{Put the interaction in a finite box } \Lambda_s \text{ where } \text{vol}(\Lambda_s) = L^{3s} \end{array} \right.$$

$$\exp \left[-g \int_{\mathbb{K}^3} d^3x \phi^4(x) \right] \left\{ \begin{array}{l} \text{How to interpret } \phi^4(x)?: \text{ **UV Divergence**} \\ \text{Interaction in infinite volume: **IR Divergence**} \end{array} \right.$$

$$\text{Regularize!} : \left\{ \begin{array}{l} \text{Replace } C \text{ with } C_r \text{ where } \hat{C}_r(k) = \mathbb{1}_{\{|k| \leq L^{-r}\}} \hat{C}(k) \\ \text{Put the interaction in a finite box } \Lambda_s \text{ where } \text{vol}(\Lambda_s) = L^{3s} \end{array} \right.$$

Define the following sequence of cutoff measures for $-\infty < r < s < \infty$:

$$d\nu_{r,s}(\tilde{\phi}) = \frac{1}{Z_{r,s}} \exp \left[- \int_{\Lambda_s} d^3x \tilde{g}_r : \tilde{\phi}^4(x) :_{C_r} + \tilde{\mu}_r : \tilde{\phi}^2(x) :_{C_r} \right] d\mu_{C_r}(\tilde{\phi})$$

We'll construct our measure via the following limit:

$$\lim_{r \rightarrow -\infty} \lim_{s \rightarrow \infty} \nu_{r,s}$$

RG and its associated dynamical system

It is important to choose the UV cutoff so that:

$$C_r(x) = L^{-2[\phi]r} C_0(x/L^r)$$

RG and its associated dynamical system

It is important to choose the UV cutoff so that:

$$C_r(x) = L^{-2[\phi]r} C_0(x/L^r)$$

Then if $\check{\phi} \sim C_r$ and $\phi \sim C_0$ we have $\check{\phi}(x) \stackrel{d}{=} L^{-[\phi]r} \phi(x/L^r)$.

RG and its associated dynamical system

It is important to choose the UV cutoff so that:

$$C_r(x) = L^{-2[\phi]r} C_0(x/L^r)$$

Then if $\check{\phi} \sim C_r$ and $\phi \sim C_0$ we have $\check{\phi}(x) \stackrel{d}{=} L^{-[\phi]r} \phi(x/L^r)$.

If we are trying to calculate the partition function we see:

$$\begin{aligned} Z_{r,s} &= \int_{S'} \exp \left[- \int_{\Lambda_s} d^3x \check{g}_r : \check{\phi}^4(x) :_{C_r} + \check{\mu}_r : \check{\phi}^2(x) :_{C_r} \right] d\mu_{C_r}(\check{\phi}) \\ &= \int_{S'} \exp \left[- \int_{\Lambda_{s-r}} d^3x L^{(3-4[\phi])r} \check{g}_r : \phi^4(x) :_{C_0} + L^{(3-2[\phi])r} \check{\mu}_r : \phi^2(x) :_{C_0} \right] d\mu_{C_0}(\phi) \end{aligned}$$

RG and its associated dynamical system

It is important to choose the UV cutoff so that:

$$C_r(x) = L^{-2[\phi]r} C_0\left(\frac{x}{L^r}\right)$$

Then if $\check{\phi} \sim C_r$ and $\phi \sim C_0$ we have $\check{\phi}(x) \stackrel{d}{=} L^{-[\phi]r} \phi(x/L^r)$.

If we are trying to calculate the partition function we see:

$$\begin{aligned} \mathcal{Z}_{r,s} &= \int_{S'} \exp \left[- \int_{\Lambda_s} d^3x \check{g}_r : \check{\phi}^4(x) :_{C_r} + \check{\mu}_r : \check{\phi}^2(x) :_{C_r} \right] d\mu_{C_r}(\check{\phi}) \\ &= \int_{S'} \exp \left[- \int_{\Lambda_{s-r}} d^3x L^{(3-4[\phi])r} \check{g}_r : \phi^4(x) :_{C_0} + L^{(3-2[\phi])r} \check{\mu}_r : \phi^2(x) :_{C_0} \right] d\mu_{C_0}(\phi) \\ &= \int_{\mathbb{R}^{Lat(\Lambda_{s-r})}} \prod_{x \in Lat(\Lambda_{s-r})} F_0(\phi(x)) d\mu_{C_0}(\phi) \end{aligned}$$

Integrating short range fluctuations

We define the fluctuation covariance Γ as follows:

$$C_0(x) = \Gamma(x) + C_1(x)$$

Integrating short range fluctuations

We define the fluctuation covariance Γ as follows:

$$C_0(x) = \Gamma(x) + C_1(x)$$

$\Gamma(x)$ represents short range interactions and is of finite range

Integrating short range fluctuations

We define the fluctuation covariance Γ as follows:

$$C_0(x) = \Gamma(x) + C_1(x)$$

$\Gamma(x)$ represents short range interactions and is of finite range

We integrate out Γ and rescale to define a sequence of effective actions. Given a function $F_j : \mathbb{R} \rightarrow \mathbb{R}$ we define F_{j+1} and δb_{j+1} in a way so that the following equation is satisfied:

$$\int \prod_{x \in \text{Lat}(\Lambda_{s-r-j})} F_j(\phi(x)) d\mu_{C_0}(\phi) = \int \prod_{x \in \text{Lat}(\Lambda_{s-r-(j+1)})} \left(F_{j+1}(\phi(x)) e^{\delta b_{j+1}} \right) d\mu_{C_0}(\phi)$$

Integrating short range fluctuations

We define the fluctuation covariance Γ as follows:

$$C_0(x) = \Gamma(x) + C_1(x)$$

$\Gamma(x)$ represents short range interactions and is of finite range

We integrate out Γ and rescale to define a sequence of effective actions. Given a function $F_j : \mathbb{R} \rightarrow \mathbb{R}$ we define F_{j+1} and δb_{j+1} in a way so that the following equation is satisfied:

$$\int \prod_{x \in \text{Lat}(\Lambda_{s-r-j})} F_j(\phi(x)) d\mu_{C_0}(\phi) = \int \prod_{x \in \text{Lat}(\Lambda_{s-r-(j+1)})} (F_{j+1}(\phi(x)) e^{\delta b_{j+1}}) d\mu_{C_0}(\phi)$$

This gives us the definition:

$$\text{For } F_{j+1}(\phi(0)) = \int d\mu_{\Gamma}(\zeta) \prod_{y \in \text{Lat}(\Lambda_1)} F_j(L^{-[\phi]} \phi(0) + \zeta(y)) e^{-\delta b_{j+1}}$$

Preserved Functional Form

$$F_j(\phi) = \exp \left[-g_j : \phi^4(x) :_{C_0} - \mu_j : \phi^2 :_{C_0} \right] + K_j(\phi) \leftrightarrow (g_j, \mu_j, K_j) \in \mathbb{R} \times \mathbb{R} \times \mathcal{C}^9$$

Preserved Functional Form

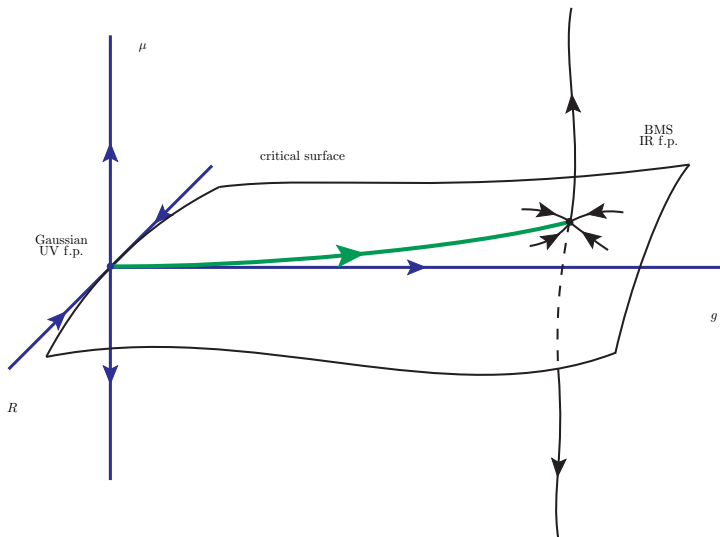
$$F_j(\phi) = \exp \left[-g_j : \phi^4(x) :_{C_0} - \mu_j : \phi^2 :_{C_0} \right] + K_j(\phi) \leftrightarrow (g_j, \mu_j, K_j) \in \mathbb{R} \times \mathbb{R} \times \mathcal{C}^9$$

$$g_{j+1} = L^\epsilon g_j - a(L) L^{2\epsilon} g_j^2 + \dots$$

$$\mu_{j+1} = L^{\frac{(3+\epsilon)}{2}} \mu_j + \dots$$

$$\|K_{j+1}\| \leq L^{-\frac{1}{4}} \|K_j\|$$

Sketch of the RG phase portrait:



Existence of the Critical Mass

Analog of BMS Fixed point (g_*, μ_*, K_*) , $g_* > 0$

Stable Manifold: $h(g, K) = \mu_{critical}$

$\lim_{n \rightarrow \infty} RG^n [(g, h(g, K), K)] = (g_*, \mu_*, K_*)$

Existence of the Critical Mass

Analog of BMS Fixed point (g_*, μ_*, K_*) , $g_* > 0$

Stable Manifold: $h(g, K) = \mu_{critical}$

$\lim_{n \rightarrow \infty} RG^n [(g, h(g, K), K)] = (g_*, \mu_*, K_*)$

We now know how to choose $\{\tilde{g}_r, \tilde{\mu}_r\}_{-\infty \leq r \leq 0}$:

Pick some g_0 near g_*

Choose \tilde{g}_r and $\tilde{\mu}_r$ so that:

$$g_0 = L^{(3-4[\phi])r} \tilde{g}_r, \quad h(g_0, 0) = L^{(3-2[\phi])r} \tilde{\mu}_r$$

This puts F_0 on the stable manifold

Computation via collecting vacuum renormalizations

Controlling the F_j 's gives control of the δb_j 's

Computation via collecting vacuum renormalizations

Controlling the F_j 's gives control of the δb_j 's

$$\log(\mathcal{Z}_{r,s}) = \sum_{j=1}^{(s-r-1)} \text{vol}(\Lambda_{r-s-j}) \delta b_j + \int d\mu_{C_0}(\phi) F_{s-r}(\phi(0))$$

Can easily see existence of pressure for fixed UV cut-off

Computation via collecting vacuum renormalizations

Controlling the F_j 's gives control of the δb_j 's

$$\log(\mathcal{Z}_{r,s}) = \sum_{j=1}^{(s-r-1)} \text{vol}(\Lambda_{r-s-j}) \delta b_j + \int d\mu_{C_0}(\phi) F_{s-r}(\phi(0))$$

Can easily see existence of pressure for fixed UV cut-off

To construct the measure we introduce a source term:

$$\mathcal{Z}_{r,s}(\tilde{f}) = \int_{S'} \exp \left[- \int_{\Lambda_s} d^3x \tilde{g}_r : \tilde{\phi}^4(x) :_{C_r} + \tilde{\mu}_r : \tilde{\phi}^2(x) :_{C_r} + \tilde{f}(x) \tilde{\phi}(x) \right] d\mu_{C_r}(\tilde{\phi})$$

Computation via collecting vacuum renormalizations

Controlling the F_j 's gives control of the δb_j 's

$$\log(\mathcal{Z}_{r,s}) = \sum_{j=1}^{(s-r-1)} \text{vol}(\Lambda_{r-s-j}) \delta b_j + \int d\mu_{C_0}(\phi) F_{s-r}(\phi(0))$$

Can easily see existence of pressure for fixed UV cut-off

To construct the measure we introduce a source term:

$$\mathcal{Z}_{r,s}(\tilde{f}) = \int_{S'} \exp \left[- \int_{\Lambda_s} d^3x \tilde{g}_r : \tilde{\phi}^4(x) :_{C_r} + \tilde{\mu}_r : \tilde{\phi}^2(x) :_{C_r} + \tilde{f}(x) \tilde{\phi}(x) \right] d\mu_{C_r}(\tilde{\phi})$$

$$\mathbb{E} \left[e^{\phi(\tilde{f})} \right] = \lim_{r \rightarrow -\infty} \lim_{s \rightarrow \infty} \frac{\mathcal{Z}_{r,s}(\tilde{f})}{\mathcal{Z}_{r,s}(0)}$$